

ISTANBUL TECHNICAL UNIVERSITY ★ GRADUATE SCHOOL OF SCIENCE
ENGINEERING AND TECHNOLOGY

**AN INVESTIGATION ON COASTAL
SEA LEVEL CHANGES OF BLACKSEA USING
TIDE-GAUGE AND SATELLITE ALTIMETRY DATA**



M.Sc. THESIS

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Department of Geomatics Engineering
Geomatics Engineering Programme

JUNE 2016

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İSTANBUL TEKNİK ÜNİVERSİTESİ ★ FEN BİLİMLERİ ENSTİTÜSÜ

**KARADENİZ'DE MAREOGRAF İSTASYONU
VE UYDU ALTIMETRE VERİLERİ İLE KIYI DENİZ SEVİYESİ
DEĞİŞİMLERİNİN ARAŞTIRILMASI ÜZERİNE BİR İNCELEME**

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HAZİRAN 2016

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To my dear wife, Negar



FOREWORD

By writing this acknowledgment, I will finish my two years graduate studies in Istanbul Technical University. During this period, I also passed colourful easy and difficult times same as the four seasons. Although only my name appear on the cover but I was not alone on this path and many people accompanied me on this way. Some of them were present by my side, memories and guidelines of some brightened my way and love of some other warmth my heart and gave me energy and enthusiasm on each step I took to success. Herby, I would like to thank everyone for their kind companionship.

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(Geomatics Engineer)

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ABBREVIATIONS

AVISO	: Achieving, Validation and Interpretation of the Satellite Oceanographic
BRAT	: Basic Radar Altimetry Toolbox
CNES	: Center National D'études Spatiales
COI	: Cone of Influence
CORS	: Continuously Operating Reference Station
CO-OPS	: Center for Operational Oceanographic Products and Services
CWT	: Continuous Wavelet Transform
DAC	: Dynamic Atmosphere Correction
DUACS	: Data Unification and Altimeter Combination System
EPN	: EUREF Permanent Network
FFT	: Fast Fourier Transform
GCM	: General Command of Mapping
GIA	: Glacial Isostatic Adjustment
GIS	: Geographic Information Systems
GNSS	: Global Navigation Satellite System
GPS	: Global Positioning System
GRACE	: Gravity Recovery and Climate Experiment
IGS	: International GNSS Service
LSSA	: Least Square Spectral Analysis
MSL	: Mean Sea Level
MSSH	: Mean Sea Surface Height
NWLON	: National Water Level Observation Network
PCA	: Principle Component Analysis
PSMSL	: Permanent Service for Mean Sea Level
RLR	: Revised Local Reference
SLA	: Sea Level Anomaly
SONEL	: Système d'Observation du Niveau des Eaux Littorales
SOPAC	: Scripps Orbit and Permanent Array Center
SSALTO	: Segment Sol multimissions d'ALTimétrie, d'Orbitographie et de localisation précise
SSH	: Sea Surface Height
STFT	: Short-Time Fourier Transform
WTC	: Wavelet Coherence Transform
XWT	: Cross Wavelet Transform
VLM	: Vertical Land Motion



SYMBOLS

h_{isl}	:	Geometric height of the Instantaneous Sea Surface
h_{orb}	:	Satellite orbit
h_{alt}	:	Distance between the satellite and the Instantaneous Sea Surface
ω_j	:	Frequency
\mathbf{M}	:	Manifold
ϕ_i	:	Basis vectors
\mathbf{H}	:	Hilbert space
ψ_j	:	Phase
A_j	:	Amplitude
\mathbf{p}	:	Orthogonal projection of vector \mathbf{f}
$\hat{\mathbf{X}}$:	Unknown vector
\mathbf{S}	:	Spectrum
Q_n	:	Noise
Q_s	:	Signal
ζ	:	frequency
$\psi_{a,b}(t)$:	wavelet with scaling a and time shifting b
Λ	:	Diagonal matrix
Σ	:	Covariance matrix
λ	:	Eigenvalue
q_i	:	Eigenvector
S_a	:	Solar annual
S_{sa}	:	Solar semiannual



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AN INVESTIGATION ON COASTAL SEA LEVEL CHANGES OF BLACKSEA USING TIDE-GAUGE AND SATELLITE ALTIMETRY DATA

SUMMARY

The sea level changes are one of the indicators of climate change and effect the world life today and in future, with reasons such as coastal erosion, saltwater intrusion, inundation etc. Beside the oceanographic data, evaluation of tide-gauge and satellite altimetry data provide valuable input to analyse and estimate the long-term sea level changes and also contribution of these results to oceanographic and climate investigations will be vital for future planning and precautions for life. In order to know the exact causes of sea level changes, Vertical Land Motion (VLM) rates must be also considered. This study investigates and compares various spectral analyzing methods that are Least Square Spectral Analysis (LSSA), Wavelet Analysis and Principle Component Analysis (PCA), in evaluation of tide-gauge and satellite altimetry data hence clarifies the advantages and drawbacks of each methods from methodological and practical point of view for each group of data. In this purpose both monthly Mean Sea Level (MSL) observations at ten tide-gauge stations surrounding Blacksea coast and Sea Level Anomaly of grid and Along-Track altimetry data of this region are considered. Also difference between tide gauge and altimetry data are compared with nearby continuous GPS data for VLM rates' analysis. The tide gauge data (Igneada, Amasra and Trabzon-Turkey; Batumi and Poti-Georgia; Tuapse-Russia; Sevastopol-Ukraine; Constantza-Romania; Varna and Burgas-Bulgaria) are obtained from Permanent Services for Mean Sea Level (PSMSL) global network of tide gauges, with varying time spans between 8 to 139 years. Satellite altimetry data includes multi-mission grid altimetry data and Along-Track data of Topex/Poseidon, Jason 1, Jason 2 and Geosat Follow-On (GFO) during 1993-2015 are obtained from Achieving, Validation and Interpretation of the Satellite Oceanographic (AVISO) service. GPS vertical velocity data of nearby tide gauge stations in Turkish coasts are obtained from Continuously Operating Reference Station (CORS) which are delivered by General Command of Mapping (GCM) and for other stations are obtained from Scripps Orbit and Permanent Array Center (SOPAC) and EUREF Permanent Network. In conclusion, beside representing amplitude and phase of tidal constituents, sea level trend, periodicities, correlations among the stations, the regional observing system and the quality of the tide gauge and satellite altimetry records in the region are discussed and reported over the drawn results of the study.



**KARADENİZ'DE MAREOGRAF İSTASYONU
VE UYDU ALTIMETRE VERİLERİ İLE KIYI DENİZ SEVİYESİ
DEĞİŞİMLERİNİN ARAŞTIRILMASI ÜZERİNE BİR İNCELEME**

ÖZET

Dünya nüfusunun büyük bir çoğunluğu kıyı alanlarda toplanmıştır ve deniz seviyesi değişimi canlı yaşamına doğrudan ya da dolaylı olarak etki eder. Global iklim değişiminin (Greenhouse gazları, buzulların erimesi, vb. nedenlerden) yol açtığı deniz seviyesi değişimlerinin izlenmesi ile yeryuvarını ve yaşamı yakından ilgilendiren bu süreç deniz seviyesi değişimleri ile sebep-sonuç ilişkisi içerisinde incelenebilir ve ileriye yönelik tahminler ortaya koyulabilir. Bu gibi nedenlerle deniz seviyesi değişimlerinin global ve lokal anlamda düzenli olarak izlenmesi, analiz edilmesi, yöneliminin saptanması, zamansal değişimlerinin irdelenmesi önem arz etmektedir. Deniz seviyesi değişimlerinin irdelenmesinde mareograf istasyonu verileri, GNSS gözlemleri, uydu altimetre, yer gravite alanı uydu misyonu verileri ve oşinografik verilerden yararlanılır. Değişimlerin izlenmesinde yalnızca tek bir veri grubuna (konvansiyonel mareograf istasyonu verilerine) dayalı analizler deniz seviyesinin irdelenmesine yönelik dar kapsamlı ve kısıtlı irdeleme olanağı sağlar. Mareograf istasyonlarında kayıt edilen deniz seviyesi gözlemlerinin karanın düşey hareketlerinden etkilenmesi bu gözlemlere dayalı gerçekleştirilecek analizler için bir diğer önemli olumsuzluk olarak değerlendirilmekte ve deniz seviyesi gözlemlerinin irdelenmesi öncesinde istasyona ilişkin düşey deformasyonların belirlenmesi gereğini ortaya koymaktadır. Bunun yanı sıra mareograf istasyonu verilerine dayalı deniz seviyesi değişimi analizi gözlem istasyonlarının seyrek dağılımı nedeniyle de yetersiz kalmaktadır. Mareograf verilerinin taşıdığı bu olumsuzların üstesinden gelinmesinde uydulardan elde edilen radar altimetre gözlemleri kullanılmaktadır. Uydu altimetresi 1970'li yıllardan günümüze deniz seviyesi araştırmalarında kullanılmaktadır. Gerçekleştirilen çalışma kapsamında Karadeniz'e ilişkin deniz seviyesi değişimleri 10 adet mareograf istasyonlarındaki veriler ve uydu altimetre verileri kullanılarak analiz edilmektedir. Bu verilerin analizinde uygulanan spektral analiz yaklaşımları (En Küçük Kareler Spektral Analizi-LSSA, Dalgacık Spektral Analizi - WSA, Başlıca Bileşen Analizi-PCA) karşılaştırılarak, yöntemlerin avantaj ve zayıflıkları rapor edilerek karşılaştırılmaktadır. Mareograf verilerinin değerlendirilmesi sonucu elde edilen deniz seviyesi değişimleri uydu altimetre verileri ile elde edilen sonuçlar ile karşılaştırılmakta ve çalışma alanına ilişkin deniz seviyesi ve değişimleri global ve lokal değerlendirilmektedir. Elde edilen sonuçlar spektral analiz yöntemlerinin karşılaştırılmasının yanı sıra Karadeniz deniz seviyesi değişimlerinin yorumlanmasında da kullanılmaktadır. Bu araştırmanın hedeflediği katkıları iki temel başlıkta belirtebiliriz: 1. Aynı bir zaman diliminde elde edilen verilerin analizi için gelişmiş istatistiksel yöntemler ve matematiksel modellere ihtiyaç duyulur. Zaman serisi analizi ile analiz edilen sinyalin temel karakteristik davranışları çok daha iyi ve detaylı irdelenebilir. Sinyalin içerdiği gürültü ayrıştırılabilir. Bu çalışmada Karadeniz'de deniz seviyesi

değişimlerinin gözlemlerin zaman serilerine dayanarak analiz edilmesinde, En Küçük Spektral Analizi (Least Square Spectral Analysis-LSSA), Dalgacık Spektral Analizi (Wavelet Spectral Analysis-WSA, Continues Wavelet Transform-CWT), Başlıca Bileşen Analizi (Principle Component Analysis-PCA) , Fourier Dönüşümü (FT), yaklaşımları uygulanmıştır. Bu yöntemlerin matematiksel kurgularının ve bu yöntemlerle analiz sonuçlarının karşılaştırılması hem metodolojik açıdan hem de deniz seviyesi değişimlerinin irdelenmesindeki uygunlukları açısından üstünlük ve zayıflıklarını ortaya koyacaktır. Deniz seviyesi değişimlerinin araştırılmasında geleneksel ve yeni yöntemlerin bir arada karşılaştırılması nedeniyle de literatüre katkı sağlamaktadır. 2. Diğer taraftan bu çalışma Karadeniz deniz seviyesi değişimlerinin yersel (mareograf) ve de uydulara dayalı (altimetre) verilerin değerlendirilmesi ile geniş spektrumlu bir irdemeye tabii tutulacaktır. Deniz seviyesi değişimlerinin kapsamlı irdelenmesi, zamansal trend ve periyodik değişimlerin ortaya koyulması, yalnızca çevreye olan etkilerinin saptanması açısından değil jeodezi uygulamalarında sağlıklı bir dişey datum tanımlanması ve geoidin ifade edilmesi açısından da önem taşımaktadır. Çalışma elde edilen sonuçlara göre Karadeniz mareograf istasyonu verilerinin değerlendirmesi neticesinde, İğneada, Amasra ve Trabzon istasyonlarında kayıt edilen kısa zaman serilerinin gel-git' e dayalı bileşenlerinin belirlenmesinde yetersiz kaldığı, özellikle yıllık ve yarı-yıllık gelgit bileşenlerini ortaya koyamadığı görülmüştür. Sürekli Dalgacık Dönüşümü (Continuous Wavelet Transform-CWT) ve çarpaz Dalgacık Dönüşümü (Cross Wavelet Transform-XWT) yöntemlerinde aynı sonucu doğrulamaktadır. Dalgacık yöntemi analizi sonuçları, Sevastopol, Batumi, Tuapse ve Varna da deniz seviyesi aynı özellikleri gösterdiği ortaya koyulmuştur. Tez araştırması kapsamında yapılan analizlerde deniz seviyesi değişimlerinin aynı zaman aralıklarında yakın faz da gerçekleşti görülmüştür. Uygulanan Başlıca Bileşen Analizi (Principle Component Analysis-PCA) algoritması özellikle Varna ve Batumi istasyonlarında kayıt edilen deniz seviyesi gözlemlerindeki kaba hatalı ölçülerin ayıklanmasında oldukça başarılı sonuçlar ortaya koymuş ve neticesinde spektral analizlerin daha sağlıklı gerçekleştirilmesinde sağlanmıştır. Çalışmanın kapsamında ayrıca en küçük kareler spektral analiz yöntemi uygulanmıştır. Zaman serilerinin spektral analizinde, en küçük kareler spektral yönteminin avantajı, eşit aralıkla kayıt edilmemiş, boşluklar içeren gürültü düzeyi yüksek, verilerin de analiz edilebilmesidir. Bu çalışmada da mareograf verilerinden elde edilen deniz seviyesi gözlemleri, zaman serilerinin etkin bir biçimde analiz edildiği ve anlamlı sonuçlar ortaya koyduğu görülür. Karadeniz deniz seviyesinin araştırılmasında ve irdelenmesinde mareograf istasyonu verilerinin yanı sıra, uydu altimetre verilerinden elde edilen grid ve uydu izi boyunca gözlemlerde kulanılmıştır. Uydu altimetre verilerinin genel kapsama alanı ve Karadeniz'in tamamını temsil etmesi yalnızca, noktasal deniz seviyesi değişimlerinin analizini olanak sağlayan mareograf istasyonu verilerine göre, üstünlüğü olarak söylenebilir. Çalışmada altimetre verilerin analizinden elde edilen, deniz seviyesi değişime periyodik bileşenler ve faz büyüklükleri mareograf istasyonu destekler niteliktedir. Bunu yanısıra, uydu izi boyunca mevcut verilerin kullanılması neticesinde elde edilmesi beklenen doğruluk artışı sağlanamamıştır. Çalışma sonuçları altimetre verilerinden elde edilen ve grid formda servis edilen, verilerin çalışma için yeterli olduğunu göstermiştir. Vurgulanması gereken diğer bir önemli sonuç ise PCA algoritmasının kaba hatalı ölçülerin elemine edilmesinde kullanılmasının irdelenen gel-git periyotlarının spektral anlamlılığını (gücünü) arttırdığını göstermiştir. Uydu izi boyunca altimetre verilerinin grid verideki boşlukların doldurulmasında anlamlı

katkı sağladığı görünmüştür. Bunu yanı sıra altimetre verisinin kıyı alanlarda düşük doğruluğa sahip olması en önemli dezavantajdır. Deniz seviyesi izlenmesine yönelik yapılan çalışmalarda, uydu izlerinin mareograf verilerinin belirli bir uzaklıktan geçiyor olması, mareograf istasyonundaki altimetre değerinin üretilmesinde uygun interpolasyon algoritmasının kullanılmasını gerektirir. Tez çalışmasının içeriğinde ilk bölüm konun tanıtımı, Karadeniz ve genel olarak deniz seviyesi değişimlerinin ele alındığı yayınlar ile kullanılan spektral analiz yöntemlerine ilişkin temel kaynakların incelendiği literatür ve araştırmanın amaçlarını içermektedir. İkinci bölümde deniz seviyesinin araştırılmasında ve incelenmesinde kullanılan veri kaynakları (deniz durağı gözlem (mareograf) istasyonları, uydu altimetre misyonları) tanıtılmakta ve bu verilere dayalı olarak deniz seviyesinin irdelenmesinde dayanan temel ilişki ve eşitlikler verilmektedir. Üçüncü bölümde çalışma kapsamında kullanılan spektral analiz yöntemleri (harmonik analiz, En Küçük Kareler Spektral Analizi, Fourier Dönüşümü, Dalgacık Spektral Analizi ve Başlıca Bileşen Tahmini) detaylı olarak anlatılmakta ve temel literatüre dayandırılarak ilgili matematiksel altyapıları tanıtılmaktadır. Son olarak çalışmanın dördüncü ve beşinci bölümlerinde Karadeniz mareograf istasyonları ve uydu altimetre verileri kullanılarak gerçekleştirilen analiz sonuçları sayısal olarak verilmekte ve yorumlanmaktadır. Elde edilen analiz sonuçlarına dayalı olarak uygulanan spektral analiz yöntemlerinin üstünlük ve zayıflıkları ortaya koyulmakta, Karadeniz’de deniz seviyesi değişimi için elde edilen sonuçlar yorumlanmaktadır.



1. INTRODUCTION

In Turkey, a significant part of population lives in coastal zones and one of the important factors that directly or indirectly affect the human life in these regions is the sea level changes. Sea level changes have many reasons, such as, changing the mass and volume of ocean bodies and also thermal expansion of water because of global climate changes (caused by greenhouse gases, melting of ice and etc.) (Tang, 2012). It can be said that, prediction of sea level change as a revealer factor can be represented this climate changes (Houghton, 1996). Therefore, observing and measuring the sea level changes and also analysing its time series (i.e. a regular intervals over a period of time which records the sea level change) is very important. To evaluate the sea level changes, mainly two data sets are used; tide gauge (traditional method) and satellite altimetry (modern method). Tide gauge can observe sea level continuously in specific location during long time. There are three types of tide gauges based on pressure, acoustics and radar (Tang, 2012). Only using the conventional method (tide gauge) to evaluate the sea level changes introduces certain disadvantages (Fu and Cazenave, 2000). First, tide gauge can only measure sea level changes relate to land, hence it may move in vertical direction related to the land (Douglas, 1995). The other handicap is the sparse distribution of tide gauge stations which provide insufficient measurements in terms of spatial resolution in order to obtain the sea level variations (Barnett, 1984; Gröger and Plag, 1993).

Satellite Altimetry (SA) method was started to be used forty years ago, in oceanography and geodesy fields. It provides homogeneous, continuous, wide coverage and repeated measurements of ocean surface with high accuracy (Tang, 2012). In global scale, monitoring and modeling the Mean Sea Level (MSL) and its variations, gravity field, tides, meteorology parameters (temperature and pressure), etc., are the most important applications of satellite altimetry (Vergos, 2002). Beside using tide gauge and altimetry in local regions, shipborne campaign is another method for data collection for geodetic and oceanography observations. However, shipborne

measurements are time-consuming and not economic, therefore it is not applicable in wide range (Tang, 2012).

Studying sea level change also requires to know Vertical Land Motion (VLM) rates. Reasons for land motion are different in local and large scale regions. In local regions, tectonics, subsidence and sedimentation (i.e. due to groundwater withdrawal, oil and gas extraction, dam building and etc.) are parameters that effect the land motion. On the other hand, melting of ice sheets (because of geological process) results in changing the mass loading of the earth's surface which causes the land motion in large scale (Tang, 2012).

All measurements from different observations (tide gauge or altimetry) are time variable (hourly, daily, monthly or annual). In order to evaluate the sea level changes from these measurements in details, time series analysis must be applied. The aim of time series evaluation of tide gauge data is determination of tidal constituents (semi-diurnal, diurnal, semi annual and annual) which is done by spectral analysis methods. In addition, by using some filtering procedures, daily or monthly data can be obtained from high frequency hourly data. Fast Fourier Transform (FFT) is conventional spectral method in field of time series analysis. However when data sets are unequally spaced and also contains some gaps, this method does not work accurately (disadvantage of FFT). Therefore, data should be equally spaced and all gaps through time series must be filled. Beside of this method, Least Square Spectral Analysis (LSSA) and Wavelet Transform (WT) are also frequently applied spectral methods to analyse the time series (Erol, 2011).

LSSA algorithm calculates the optimum least square spectrum of non-stationary and colored time series (i.e. equally or unequally spaced) based on some known constituents (systematic noises) (Wells et al., 1985). In addition, wavelet theory can solve time-localization in frequency domain that FFT does not sense it (Keller, 2004). Generally, data analysing means that large numbers of variables and observations and outlier detection for multi-dimensional data is a main topic in statistical research. Principal Component Analysis (PCA) is also a well known technique especially benefit to dimensionality reduction (Chen, 2002).

1.1 Purpose of Thesis

The aim of this study is observation of sea level changes based on two spectral analysis methods (Least Square Spectral Analysis and Wavelet Transform) with three data sets (tide gauge, grid and along-track altimetry). Obtained results of each data from both spectral algorithms are compared with each other due to find the abilities and drawbacks of each spectral analysis. Also, by using various data, it can possible to firstly, comparing spectral methods in terms of accuracy and secondly, recognizing the characters of each data sets.

In this study, spectral and statistical analysis are applied for tide gauge and altimetry time series at Blacksea basin. At the first step, monthly time series of 10 number of tide gauges established at the Blacksea coast with different time periods (obtained from Permanent Service for Mean Sea Level, PSMSL (PSMSL, 2015)) are evaluated in spectral domain by following steps;

- Applying LSSA in order to detect frequency, trend, amplitude and phase of tidal constituents and comparing them with natural tidal constituents
- Applying PCA for outlier detection
- Repeating LSSA for new modified data sets (after removing outliers)
- Applying Wavelet Transform (CWT, XWT and WTC) in order to find correlation and relation between time series in spectral domain

In the next step, time series of grid altimetry and along-track data (obtained from Achieving, Validation and Interpretation of the Satellite Oceanographic data, AVISO AVISO (2016)) will be investigated applying above procedures, as well.

Afterwards, calculated trends of Mean Sea Level (MSL) from tide gauge and altimetry data will be compared to each other in order to find behaviours of these two data sets in the interested stations. In final step, GPS vertical velocity and difference between altimetry and tide gauge data at tide gauge stations are comprised with each other due to calculate the Vertical Land Motion (VLM) in Blacksea region.

1.2 Literature Review

According to General Command of Mapping (GCM), observation of sea level with new tide gauge system have been carried out since 1998 (GCM, 2016). Based on the tide-gauge time series analysis, monthly changes of mean sea levels between Blacksea and Marmara sea is high during spring and summer and low during fall and winter. Also topography and hydrodynamics of the strait, wind system and seasonal variations provide more complicated condition to analyse sea level changes (Alpar et al., 2000). According to investigation of long time periods of time series from 1858 to 1998, water budget and sea level variations at different coastal zones of Blacksea region are affected by river water supply (such as Danube) (Bondar, 2007). With the advent of Satellite Altimeter technology in 1993, analysing altimetric data with tide gauge data was started (Kubryakov and Stanichnyi, 2013). Observation of sea level changes and Sea Surface Height (SSH) by using satellite altimetry for Mediterranean sea and Blacksea were shown that heating of surface layers and decreasing the river runoff are reasons for sea level changes in Blacksea (Cazenave et al., 2002).

Estimation of vertical motions of Earth crust from sea level (Karabil, 2011) are another sections that satellite altimetry was applied. To determine relative and absolute sea level changes and the vertical crustal movements, satellite altimetry data was integrated with GPS measurements (Yildiz and Demir, 2002). Although, vertical land motion information can be derived and corrected from tide gauge records based on Glacial Isostatic Adjustment (GIA) models, but VLM components cannot be fully detected with these GIA models. On the other hand, GIA effect in the southwestern coasts of Turkey was found to be negligible (Yildiz et al., 2013). Along with the advancement of technology, new method for analysing sea level data, such as spectral analysis (Erol, 2011) and Principle Component Analysis (PCA) were also applied (Yildiz and Demir, 2002). Nowadays, in addition to tide gauge and satellite altimetry, the GRACE gravity data is also used to analyse the sea level changes (Feng et al., 2013). Determining the risk area in coastal regions (Simav, 2012b), estimation of mass induced variation in sea level of Mediterranean Sea (gravimetric method) (Simav, 2012a) and investigation of climatic forcing on the Blacksea (hydrodynamic models) (Korkmaz, 2011) are another application of GRACE data.

1.3 Thesis' Outline

This study contains 6 chapters. The first chapter includes some introduction, literature review and purpose of thesis.

In the second chapter, procedures of evaluation of sea level will be discussed. Also study area, specification of tide gauge stations and satellite altimetry data with its missions will be described.

Numerical methods, i.e. spectral methods, for time series is explained in Chapter 3. These methods includes harmonic analysis, LSSA, Short-Time Fourier Transform (STFT), wavelet and PCA. Advantage and disadvantage of different spectral methods are also described in this chapter.

In Chapter 4 and 5, steps of tide gauge and altimetry data investigations with their results will be described, respectively. This thesis will be finalized with conclusions and some recommendations.



2. SEA LEVEL EVALUATION

Tide gauges (mareographs) continuously record the height of the water level (placed on piers) with respect to a height reference surface (geodetic benchmark)(figure 2.1).

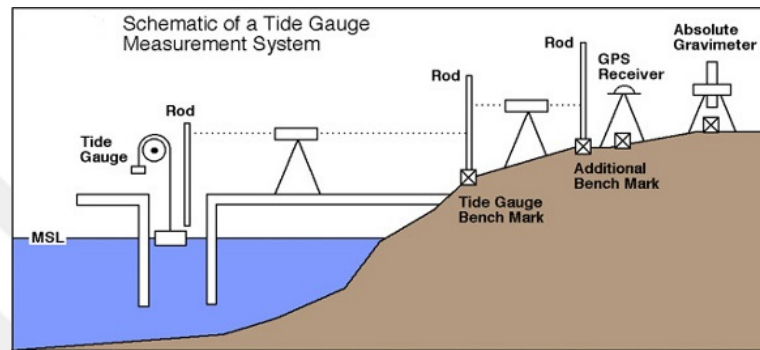


Figure 2.1 : Tide gauge measurement system (CU, 2015)

There are several global services which collect, analyse, interpretation and share the tide gauge data for users. These services distribute the tide gauge data (time series data) in different frequencies (based on the missions of service). High frequency tide gauge data can be received hourly or daily bases and the data can also be obtained monthly and annual as well. Permanent Service for Mean Sea Level (PSMSL, <http://www.psmsl.org/>) is one of these services. By analysing only time series data of tide gauge stations, relative sea level changes are obtained. Figure 2.2 shows global tide gauge stations with minimum span of 30 years and their regional trend of sea level (NOAA, 2016b).

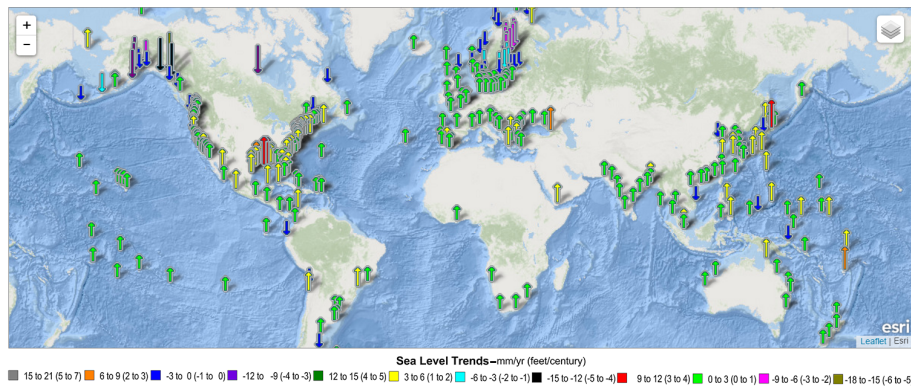


Figure 2.2 : Regional trend of sea level based on 240 global tide gauge stations during 30 years (NOAA, 2016b)

In this figure (figure 2.2), mean sea level at tide gauge stations was measured by The Center for Operational Oceanographic Products and Services (CO-OPS) with 142 tide gauge stations of the National Water Level Observation Network (NWLON) on all U.S. coasts, during 150 years. In order to calculate the linear trend, long-term water level observations at each station was considered and due to remove effect of higher frequency, all observation was averaged, monthly. This procedure for trend analysis was extended to 240 global tide gauge stations using data from PSMSL (NOAA, 2016b).

In order to calculate the absolute sea level changes, vertical crustal deformations must be considered (Feng et al., 2013). In this case GPS observation of nearest stations to the tide gauge stations must be collected. Figure 2.3 shows the vertical land movements based on the reanalysis of 16 years of GPS data from 1995 to 2010 (Santamaría-Gómez et al., 2012).

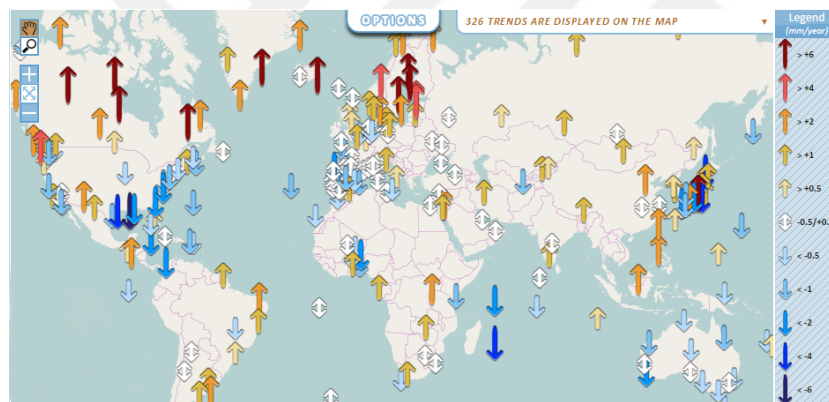


Figure 2.3 : Vertical Land Movements analysis by using 326 GPS stations (SONEL, 2016)

There are several national and international services which distribute GPS vertical velocities such as International GNSS Service (IGS), Scripps Orbit and Permanent Array Center (SOPAC), EUREF Permanent Network (EPN) and Continuously Operating Reference Station (CORS).

In addition of local assessment of sea level (based on the tide gauge data), spaceborne radar altimeter is another important data source which covers and measure more different influencing factors in sea level changes (McAdoo, 2006). Figures 2.4 and 2.5 show the global sea level trend and mean sea level, respectively from 1993 to 2015 that is one of important applications of altimetry.

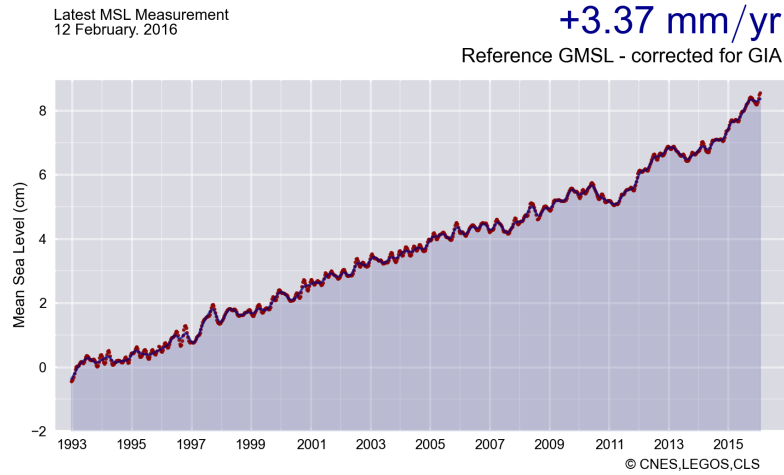


Figure 2.4 : The reference mean sea level (T/P, J1 and J2) since January 1993 after removing the annual and semi-annual signals (AVISO, 2016)

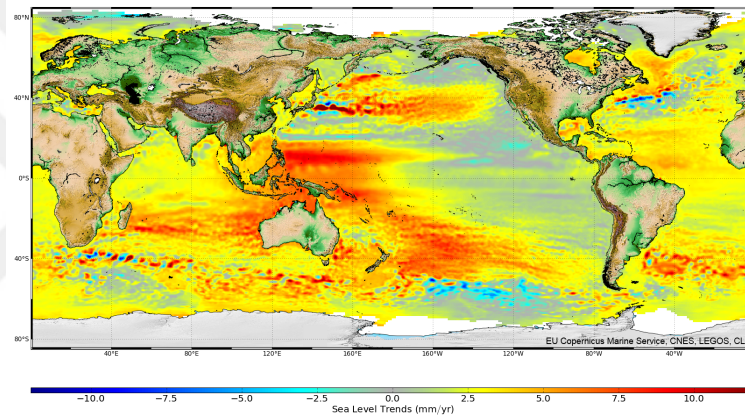


Figure 2.5 : Observed sea level (in mm/year) from multi-mission Ssalto/Duacs data since 1993 in grid (AVISO, 2016)

By using satellite altimetry method, Sea Surface Height (SSH) directly can be derived with respect to an ellipsoidal reference surface over a certain time period in grid form (Fu and Cazenave, 2000). Achieving, Validation and Interpretation of the Satellite Oceanographic data (AVISO) service is one of responsible services for satellite altimetry data. Because of varying temporal resolution of altimetry, satellite missions' combination of several altimetric data must be used. If the altimetric solutions for different epochs are compared, sea surface variations with time can be determined (Torge, 2001).

2.1 Tide Gauge Data

By upgrading the tide gauge systems, Turkish National Sea Level Monitoring System (TUDES) has been established. At the moment, 20 digital and automatic tide gauge

stations are controlled by TUDES. Data center is located at Geodesy Department of General Command of Mapping (GCM) (GCM, 2016). Distribution of stations is shown in figure 2.6.



Figure 2.6 : Turkish National Sea Level Monitoring System (TUDES) (GCM, 2016)

Instantaneous sea level and meteorological parameters, automatically are stored and transmitted to data center (Ankara) and can be obtained from TUDES (TUDES, 2016). Briefly, the aim of providing TUDES are (GCM, 2016);

1. Determining and improving the height system
2. Connecting the vertical datum of Anatolia with Turkish Republic of Northern Cyprus and the other Turkish islands
3. Geoid test
4. Analysing the tidal characteristics
5. Evaluation of natural hazards by sea level analysis

In this study, our focus is evaluation of tide gauge stations at Blacksea region which includes six country (Turkey, Georgia, Russia, Ukraine, Romany and Bulgaria). Since providing long-time high frequency tide gauge data (hourly or daily) is not possible, sea level analysis is applied based on monthly time series at each stations.

In PSMSL service, there are 10 tide gauge stations data for Blacksea region that three stations belong to Turkey (İğneada, Amasra and Trabzon).

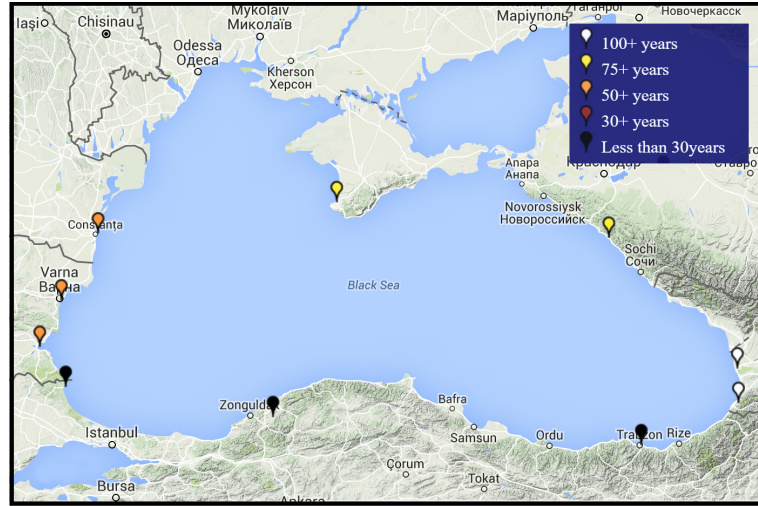


Figure 2.7 : 10 Tide Gauge stations in Blacksea. Size of each time series is represented by different colors (PSMSL, 2015)

Specification and time duration of each stations is given in table 2.1. In this table, number of values in each time series (4th column), number of void data (5th column) and number of valid data (6th column) are also given.

Table 2.1 : Time duration and other specification of tide gauge stations in Blacksea

Station(contry)	First date	Last date	Values	Void data	Valid data
Igneada(Tur.)	18.07.2002	17.11.2009	89	6	83
Amasra(Tur.)	17.06.2001	17.12.2009	103	6	97
Trabzon(Tur.)	18.07.2002	17.12.2009	89	9	80
Batumi(Geo.)	16.01.1882	17.12.2013	1584	212	1372
Poti(Geo.)	16.01.1874	17.12.2013	1680	96	1584
Tuapse(Rus.)	16.01.1917	18.05.2013	1157	12	1145
Sevastopol(Ukr.)	16.01.1910	17.12.1994	1020	32	988
Constantza(Rom.)	16.01.1933	17.12.1997	780	39	741
Varna(Bul.)	16.01.1929	16.12.1996	816	40	776
Bourgas(Bul.)	16.01.1929	16.12.1996	816	112	704

Center of PSMSL (established in 1933) is in Liverpool (National Oceanography Centre (NOC)). Responsibility of PSMSL is collection, distribution, analysis and interpretation of sea level data from the global network of tide gauges (PSMSL, 2015). In order to form the time series, PSMSL service reduced all data to a datum (approximately 7000 mm below mean sea level). This adjusted data is called *Revised Local Reference* (RLR) and according to PSMSL, only RLR data can be used for time series analysis.

The monthly data files which are distributed by PSMSL include date (year-month in

decimal form), Mean Sea Level (MSL) values for month (in mm), number of missing days and flags (PSMSL, 2015).

2.2 Satellite Altimetry Data

Altimetry is basically defined as a height measuring technique. Height calculation in satellite altimetry is applied based on measuring time interval between the transmission and reception of very short electromagnetic pulses from satellite to the earth's surface. When this measurements is combined with precise satellite location data, more accurately height measurement can be obtained. By radar altimeter measurements, different information can be detected, such as; time-varying Sea Surface Height (ocean topography), lateral extent of sea ice, altitude of large icebergs above sea level, land and ice sheets' topography, sea floor, sea surface wind speed and sea level anomaly (ESA, 2016b).

Principle components of satellite altimetry is shown in figure 2.8.

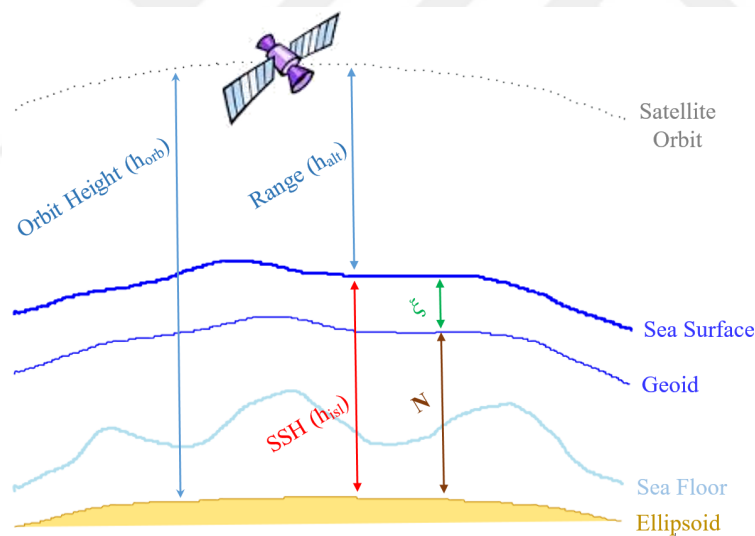


Figure 2.8 : Principle of altimetry

According to above image;

$$h_{isl} = h_{orb} - h_{alt} \quad (2.1)$$

where, h_{isl} and h_{orb} are the geometric height of the Instantaneous Sea Surface (ISS) and satellite orbit, respectively and h_{alt} is the distance between the satellite and the ISS (Vergos, 2002).

However, altimetry measurement have some errors which can be expressed by

following equation;

$$h_{isl} = [h_{orb}^c + \Delta h_{orb}] - [h_{alt}^m + \Delta\alpha] \quad (2.2)$$

where Δh_{orb} is true satellite orbit determination's error, h_{orb}^c is the ellipsoidal height of determined satellite from its computed orbit and h_{alt}^m is the altimeter measurement. However, the $\Delta\alpha$ (the altimeter measurement error) is defined by the next equation;

$$\begin{aligned} \Delta\alpha = \alpha_{instr} + \alpha_{prop} + \alpha_n = \alpha_{instr}^c + \alpha_{iono}^c + \alpha_{dry}^c + \alpha_{wet}^c + \Delta\alpha_{instr}^c + \Delta\alpha_{iono}^c \\ + \Delta\alpha_{dry}^c + \Delta\alpha_{wet}^c + \alpha_n \end{aligned} \quad (2.3)$$

where, α_{instr} is the instrumental errors, α_{prop} is propagation errors of radar pulse, α_{instr}^c is estimation errors of instrument, α_{iono}^c is estimation errors of ionosphere, α_{dry}^c is estimation errors of dry troposphere, α_{wet}^c is estimation errors of wet troposphere, $\Delta\alpha_{instr}^c$ is residual of instrumental error, $\Delta\alpha_{iono}^c$ is residual error of ionosphere, $\Delta\alpha_{dry}^c$ is residual error of dry troposphere, $\Delta\alpha_{wet}^c$ is residual error of wet troposphere and α_n is the noise altimetric measurement (Vergos, 2002). Therefore, in order to obtain true measurement, all of these correction must be done and it shows that, we encounter with huge amount of observations as well as huge calculation processes. Missions of satellite altimetry are divided into three parts; Past, Current and Future mission. Table 2.2 briefly shows specifications of each satellite missions;

Table 2.2 : Satellite altimetry missions (ESA, 2016a; Vergos, 2002)

Satellites	Launch	Altitude(km)	Inclination (deg)	Weight(kg)	Period(day)	Prec. range(cm)	Prec. orbit(cm)	Agency
Past Missions								
Skylab	1973	435	50	-	-	100	500	NASA
GEOS-3	1974	845	115	341	-	25	500	NASA
SEASAT	1978	800	108	2300	17	5	100	NASA
GEOSAT	1985	800	108	635	17	4	30-50	US Navy
ERS1	1991	785	98.5	2384	35	3	8-15	ESA
Topex/Poseidon	1992	1336	66	2402	10	2	2-3	NASA/CNES
ERS2	1995	785	98.5	2516	35	3	7-8	ESA
GFO	1998	800	108	300	17	3.5	-	US Navy
JASON-1	2001	1336	66	-	10	2-3	2-3	NASA/CNES
ENVISAT	2002	800	98.5	8140	35	2-3	2-3	ESA
Current Missions								
Jason-2	2008	1336	66		10			NASA/CNES Eumetsat/NOAA
Cryosat	2008	720	92		369			ESA
HY-2	2010	963	99.3		-			China
SARAL	2013	800	92		35			ISRO/CNES
Sentinel-3	2016	814	98.5		27			ESA
Jason-3	2016	1336	66		-			NASA/CNES Eumetsat/NOAA
Future Missions								
Jason-CS	2020							

Modified altimetry data are distributed in along-track and grid forms. For many applications and time series analysis, it is easier to use altimetry data as a regular grids. Thus mapping techniques are developed to transform along-track measurement data onto grid (Le Traon, 2007).

In order to compare the tide gauge and altimetry data, obtained sea level anomalies from tide gauges and altimeter data must be considered. The following diagram represent the procedure of comparison of these data sets (AVISO, 2013).

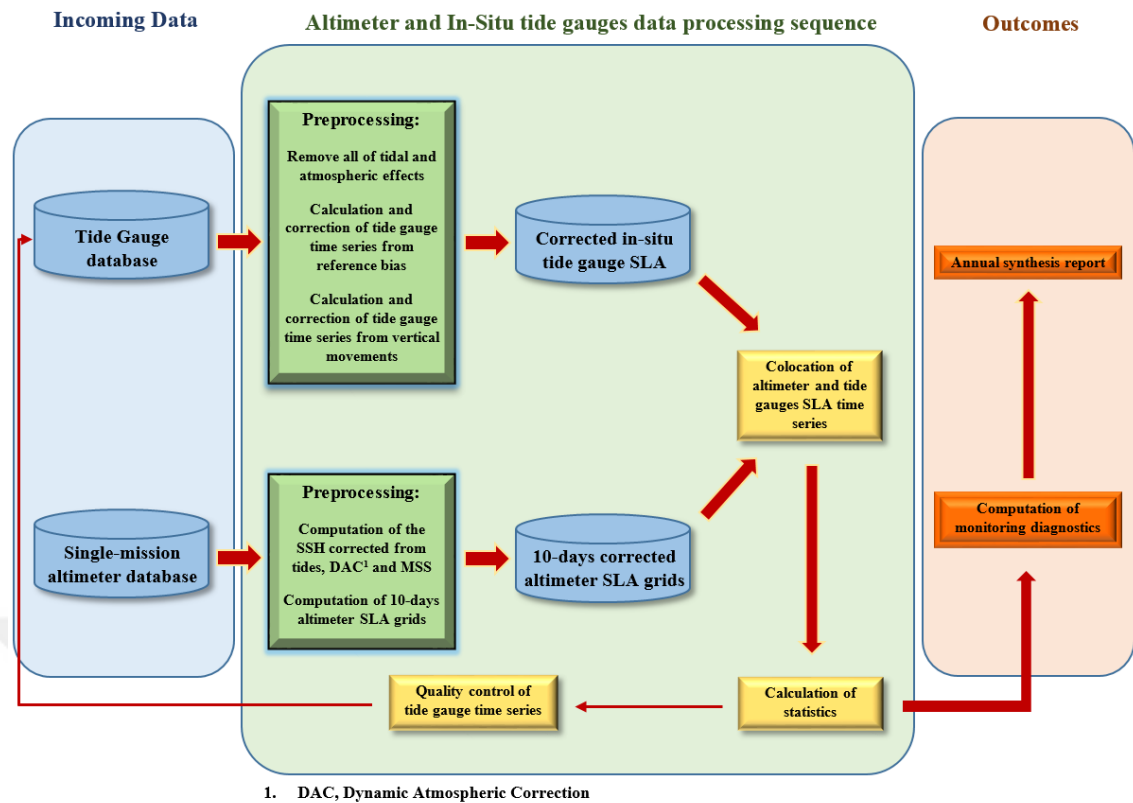


Figure 2.9 : Main steps of the altimeter/tide gauges comparison procedures

It must be mentioned that, each tide gauge station provides high temporal resolution of sea surface height, separately (e.g. hourly) while altimetry data includes sea level dynamic height for whole water area with less temporal resolution (e.g. 10 days for Topex/Poseidon). Therefore, in order to prepare a comparison condition for both tide gauge and altimetry data, several corrections must be applied for these data and also these corrections are documented by AVISO service, regularly (AVISO, 2013).

Segment Sol multimissions d'ALTimétrie, d'Orbitographie et de localisation précise (SSALTO) and Data Unification and Altimeter Combination System (DUACS) which is called Ssalto/Duacs system is a processing system of altimeter data to produce homogeneous list of data for different applications (AVISO, 2016). The Ssalto/Duacs altimeter products are produced and distributed by the Copernicus Marine and Environment Monitoring Service (CMEMS) (CMEMS, 2016). New version of AVISO productions (Ssalto/Duacs) include more accurate corrections and upgrades which are applied for several regions such as Blacksea.

The main important improvement of new version is the extension of reference period. In order to determine the reference period, sea level anomaly must be define (figure 2.10) (DUACS-AVISO, 2014).

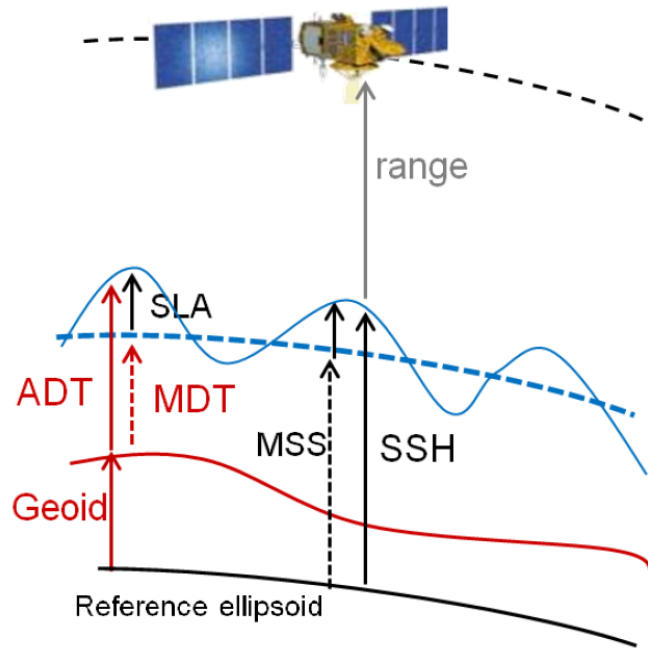


Figure 2.10 : Definition of sea level anomaly (DUACS-AVISO, 2014)

According to above figure, Sea Level Anomaly (SLA) represents the changes of Sea Surface Height (SSH) based on a Mean Sea Surface (MSS) ($SLA = SSH - MSS$). However, this MSS is related to a specific period of time which is called *Reference Period*. In previous Ssalto/Duacs version (up to 14 April 2014), reference period was 7-years (1993-1999) but in new version (from 15 April 2014), 20-years (1993-2012) reference period of SLA was applied. Selection of different reference periods has an impact of 2.3 cm and up to ± 5 cm changes for Near-Real Time¹ (NRT) global and regional SLA, respectively (DUACS-AVISO, 2014).

Other scientific upgrades and important changes for whole altimetry data can be summarized in table 2.3.

Duacs 2014 covers the global and regional area according to table 2.4. In grid altimetry data, resolution are modified to 0.125° and also Delayed-Time (DT) gridded files can be achieved with a daily temporal resolution. For Along-Track products, it was applied a filtering process due to reduce the noises and retain the physical content of the signal. This was an important drawbacks of previous version of along-track products because filtering procedures removed some important parts of signal. Another important improvement in the Duacs 2014 is SLA sub-sampling method which provides availability of more along-track signal.

¹Delivered less than 3 hours after data acquisition. It mainly used for marine meteorology and ocean-atmosphere gas transfer studies (ESA, 2016c).

Table 2.3 : List of new standards for DUACS 2014 productions (DUACS-AVISO, 2014)

Specifications	Topex/Poseidon	Jason-1	Jason-2	Geosat FO
Orbit	GFSC STD08	GDR-D	GDR-D	GSFC
Sea State Bias	N.P. ¹ SSB	Tran 2012 (OSTST)	Tran 2013	N.P. SSB
Ionosphere	B1 frequency (T/P) DORIS	D.F. ²	D.F.	GIM
Wet troposphere	TMR	MWR R.P. ³	GDR-D (MWR) JPL E.P. ⁴	From GFO radiometer
Dry troposphere	ERA I.B. ⁵	ECMWF R.G.B. ⁶	ECMWF G.G.B. ⁷	ECMWF R.G.B.
Combined atmospheric correction	MOG2D High Resolution forced with Era Interim pressure and wind fields	MOG2D High Resolution forced with ECMWF pressure and wind fields + IB computed from rectangular grid		
Ocean Tide		GOT4V8		
MSS	CNES-CLS-2011 + reference period change			

Table 2.4 : Area covers by Duacs 2014 version of gridded products (DUACS-AVISO, 2014)

Product area	Longitudes (degree East)		Latitudes (degree North)	
	min	max	min	max
Global	0.125	359.875	-89.875	89.875
Mediterranean	354.0625	396.9375	30.0625	45.9375
Blacksea	27.0625	41.9375	40.0625	46.9375
Mozambique	30.0625	59.9375	-29.9375	-0.0625

In this study, 23 years multi-mission grid altimetry data with daily temporal resolution (8289 data) from Ssalto/Duacs altimeter processing system for Blacksea region are used. Also for along-track analysis, Topex/Poseidon, Jason-1, Jason-2 and Geosat Follow-On satellite altimetry are selected. For data analysing and visualization, Basic Radar Altimetry Toolbox (BRAT) and Panoply (a cross-platform desktop application in the netCDF, HDF and GRIB formats) (NASA, 2016) are applied.

¹Non Parametric

²Dual Frequency

³Replacement Product

⁴Enhancement Product

⁵Interim Based

⁶Rectangular Grids Based

⁷Gaussian Grids Based



3. NUMERICAL METHODS

Analysing concurrent of different data requires specific statistical methods and mathematical models. Using the time series analysis, the major characters of a signal can be studied but, the significant part of a signal which are called noise can not be recognized and removed, easily.

In order to analyse of tide gauge and satellite altimetry data, some spectral analysis methods such as Harmonic Analysis (HA), Least Square Spectral Analysis (LSSA), Short-Time Fourier Transform (STFT) and Continues Wavelet Transform (CWT) are used. Comparing of these methods leads to better understanding of the nature of the noises and also can help to select the best method for spectral analysis.

3.1 Spectral Analysis

Mathematical spaces are divided in two groups; finite and infinite spaces which include finite and infinite elements. Generally, finite-element is discussed on local arguments (e.g. complex geometry) while character of spectral methods are globally. In other words, spectral methods can provide preferable accuracy based on domain (Shen et al., 2011). Basic concept of difference between spatial and spectral methods is summarized at their domains. Spatial methods are related to argument domain whereas spectral methods are applied in frequency domain. If there is a linear equation system, $\mathbf{Y} = \mathbf{AX}$, it can be written as; (Sünkel, 1986)

$$y_i = \sum_{j=1}^n a_{ij}x_j \quad (3.1)$$

In this formula y_i is obtained from x_j by a discrete convolution (simply multiplication followed by summation). The most common view of the spectral analysis is expressed in sinus and cosines form of a_{ij} in the equation 3.1 (Fourier series) (Wells et al., 1985).

$$f(x_i) = \sum_{j=0}^k (a_j \cos \omega_j x_i + b_j \sin \omega_j x_i); i = 1, 2, \dots, n \quad (3.2)$$

where ω_j , a_j and b_j are frequency and amplitudes, respectively. In fact the aim of spectral analysis is determination of a_j and b_j for unknown ω_j . In order to explain the

spectral analysis, some terms must be defined;

Time Series $f(t)$: It is supposed that t is a vector of observation time, $t = (t_i), i = 1, 2, \dots, n$, therefore, $f(t_i)$ is defined as a function of time which is called *Time Series*. Time series often consist of two parts; an interested part *Signal* and destructor part of signal which is called *Noise* (Wells et al., 1985).

Coloured Time Series: The *Colored Time Series* is produced when all constituents of time series are periodic. In this condition signal and noise will be *Colored signal* and *Colored noise* (Wells et al., 1985).

Stationarity and non-Stationarity of Time Series: If all statistical properties of a time series (mean value, variance, ...) are independent from time, this time series is *Stationary* and if it is not, then is called *non-stationary*. For example, datum shift and trend are constituents that they change mean and variance values of time series therefore they are categorized in non-stationary time series (Abbasi, 1999).

Systematic Noise: Most of time, we know there is a noise in time series but we do not know its magnitude. To analyse time series, periodic constituents, datum shifts and trends (linear, quadratic, exponential, ...) are considered as *Systematic noise* because although they infect the signal but they do not obscure the signal, totally (Wells et al., 1985).

Hilbert Space: It is a vector space with inner product and a plane of this space is called *Manifold* (Hui and Pagiatakis, 2004).

$$\mathbf{M} = \sum x_i \phi_i \quad (3.3)$$

where ϕ_i are basis vectors of \mathbf{M} and x_i are scalar values.

Projection Theorem: The shortest distance between a point and a plane is a perpendicular line from point to plane (Wells et al., 1985).

3.2 Harmonic Analysis

Tidal Phenomena which is caused by gravitational forces from celestial body (especially, sun and moon), is one of the most important problems to deform the earth shape. This forces act on the ocean in different frequencies (Vanicek and Krakiwsky, 1986). *Harmonic Analysis* is one of methods to define, amplitude and phase of known *Tidal Constituents'* frequencies. In this section mathematical representation of harmonic analysis will be explained.

Hilbert space $\mathbf{H} = L_2[-l, l]$ is defined in this form (Abbasi, 1999)

$$\left\{ 1, \cos \frac{\pi}{l}x, \sin \frac{\pi}{l}x, \cos \frac{2\pi}{l}x, \sin \frac{2\pi}{l}x \right\} \quad (3.4)$$

This system function is orthogonal on $L_2[-l, l]$ and it does not only creates full basis for \mathbf{H} but also the system is orthogonal on discrete equidistant set $\mathbf{M} \equiv [-l, l)$ or $(-l, l]$ (Wells et al., 1985).

The system function (equation 3.4), is used to create the following system;

$$\Phi = \{ \cos \omega_j x, \sin \omega_j x \}, \quad j = 0, 1, \dots, k \quad (3.5)$$

A sampled time series with n equidistant points is;

$$x_i = c + \frac{d-c}{n}i, \quad i = 1, 2, \dots, n \quad (3.6)$$

Where d and c are two real number $d > c$. Note that, this sample of time series, equation 3.6, is defined in a vector space $\mathbf{E}_n(c, d]$ and it must be transferred to vector space $\mathbf{E}_n(-l, l]$, therefore x_i is converted to y_i ;

$$y_i = \frac{2l}{d-c}(x_i - c) - l, \quad i = 1, 2, \dots, n \quad (3.7)$$

where $f(x) = g(y)$.

By using the system function (equation 3.4), trigonometrical polynomial of $g(y)$ can be written as (Vanicek and Krakiwsky, 1986);

$$g(y) = \sum_{j=0}^k (\alpha_j \cos \frac{j\pi}{l}y + \beta_j \sin \frac{j\pi}{l}y), \quad k < \frac{1}{2}(n-1) \quad (3.8)$$

After some multiplying, substituting, rearrangement and using orthogonality, $f(x)$ will be obtained;

$$\begin{aligned} f(x) = \sum_{j=0}^k \{ \{ \alpha_j \cos [j\pi(\frac{2c}{d-c} + 1)] - \beta_j \sin [j\pi(\frac{2c}{d-c} + 1)] \} \cos(\frac{2\pi j}{d-c}x) \\ + \{ \alpha_j \sin [j\pi(\frac{2c}{d-c} + 1)] + \beta_j \cos [j\pi(\frac{2c}{d-c} + 1)] \} \sin(\frac{2\pi j}{d-c}x) \} \end{aligned} \quad (3.9)$$

The result of comparing equation 3.9 with trigonometric terms of $f(x)$;

$$f(x_i) = \sum_{j=0}^k (a_j \cos \omega_j x_i + b_j \sin \omega_j x_i), \quad i = 1, 2, \dots, n \quad (3.10)$$

will be;

$$\begin{aligned}
a_j &= \alpha_j \cos\left[j\pi\left(\frac{2c}{d-c} + 1\right)\right] - \beta_j \sin\left[j\pi\left(\frac{2c}{d-c} + 1\right)\right] \\
b_j &= \alpha_j \sin\left[j\pi\left(\frac{2c}{d-c} + 1\right)\right] + \beta_j \cos\left[j\pi\left(\frac{2c}{d-c} + 1\right)\right] \\
\omega_j &= \frac{2\pi j}{d-c}
\end{aligned} \tag{3.11}$$

Which is written in this form;

$$f(x_i) = \sum_{j=0}^k A_j \cos(\omega_j x_i - \psi_j), \quad i = 1, 2, \dots, n \tag{3.12}$$

where

$$\begin{aligned}
A_j &= \sqrt{\alpha_j^2 + \beta_j^2} \\
\psi_j &= 2 \arctan \frac{\beta_j}{A_j + \alpha_j}
\end{aligned} \tag{3.13}$$

Where A_j is *amplitude*, ψ_j is *phase* and ω_j is *frequency*. It must be mentioned that the $\omega_j = \frac{2\pi j}{d-c}$ in equation 3.11 is orthogonal to vector space $\mathbf{E}_n(c, d]$ (Craymer, 1998).

The solution of spectral analysis can be written as;

$$\begin{aligned}
a_0 &= \frac{1}{n} \langle f, \cos \omega_j x \rangle, \quad j = 0 \\
a_j &= \frac{2}{n} \langle f, \cos \omega_j x \rangle, \quad j = 1, 2, \dots, k \\
b_j &= \frac{2}{n} \langle f, \sin \omega_j x \rangle, \quad j = 1, 2, \dots, k \\
\omega_j &= 2\pi j \nu_0, \quad \nu_0 = \frac{1}{d-c}
\end{aligned} \tag{3.14}$$

And if equation 3.14 is substituted in equation 3.13 the *Harmonic analysis* formula will be formed (Abbasi, 1999)

$$A(\omega_j) = \frac{2}{n} \sqrt{\left(\sum_{i=0}^n f(x_i) \cos \omega_j x_i\right)^2 + \left(\sum_{i=0}^n f(x_i) \sin \omega_j x_i\right)^2}, \quad j = 1, 2, \dots, k \tag{3.15}$$

The most important deficiency of Harmonic Analysis is its inability to recognize peaks when a time series consists of unequally distant points. This fact is proved when the gaps of data series is filled by e.g. interpolation methods. In order to fill gaps and evaluate time series accurately, the other methods such as Artificial Neural Network (ANN) can be applied (Erol, 2011).

In order to calculate *Tidal Potential* (tidal analysis for astronomical variables), position of sun and moon and their variables must be known (Foreman, 1979). However, tidal

effects on the coastal regions are not directly forced by the astronomical bodies. In this regions, shallower coastal waters and side-effect of deep oceanic variability are the main parameters (Pawlowicz et al., 2002).

For tidal analysis, there are 146 tidal constituents that 45 of these are astronomical in origin (main constituents) and remaining 101 are shallow water constituents, but only the main 24 elements from 101 shallow water constituents are selected and analysed (Foreman, 1979).

There are several free source programs for hourly sea level data analysis (or high frequency tidal data). SLP64 (Fortran program) and T_Tide (MATLAB program) are two of them. SLP64 consist of three principle task:

- Tidal analysis and prediction for periods of 1 year or shorter by using nodal corrections
- Quality control
- Filtering hourly into daily and monthly values

Furthermore, T_Tide program can compute confidence interval for the analysed components (Caldwell, 2014; Pawlowicz et al., 2002) ¹

3.3 Least Square Spectral Analysis (LSSA)

LSSA has some advantages with respect to Fourier spectral analysis;

1. Systematic noise, i.e. periodic noise (colored noise) or non-periodic noise (non-stationary), can be estimated accurately without spectral peaks' shift (Taylor and Hamilton, 1972). LSSA can detect periodic signals in time series when it consists of both random and systematic noise (Pagiatakis, 1999).
2. In Fourier spectral analysis the time series must be *equally spaced* however the LSSA can calculate *unequally spaced* time series without any preprocessing, e.g. approximation fitting (Maul and Yanaway, 1978; Press et al., 1992). In other words, interpolation of gaps in the data series is not necessary in LSSA method (Hui and Pagiatakis, 2004).

¹Since period of our tide gauge data is monthly, this method is not used.

3. Analyzing of time series relates to covariance matrix can be calculated (Steeves, 1981).
4. Statistical test to define the significant level of spectral peaks can be obtained (Pagiatakis, 1999).

Principle of LSSA is based on projection theorem (Wells et al., 1985) which is defined on the Hilbert space. According to this theorem, it can be possible to decompose a vector into two orthogonal components; the first one is the orthogonal projection of vector \mathbf{f} to \mathbf{M} manifold (\mathbf{p}). It must be mentioned that, \mathbf{p} is generated by a set of basis vectors $\mathbf{p}(\phi_i)$.

$$\Phi = [\phi_1, \phi_2, \dots, \phi_n] \quad (3.16)$$

The second produced component from projection procedure is $\mathbf{v} = \mathbf{f} - \mathbf{p}$ that is perpendicular to \mathbf{M} ($\mathbf{f} - \mathbf{p} \perp \mathbf{M}$) (Hui and Pagiatakis, 2004).

$$\left\langle \mathbf{f} - \sum_i x_i \mathbf{p}(\Phi), \Phi \right\rangle = 0 \quad (3.17)$$

According to principle of least square parametric adjustment, if \mathbf{f} is the observation vector, estimation of \mathbf{f} is defined as $\hat{\mathbf{f}} = \mathbf{A}\hat{\mathbf{X}}$. In this case the shortest distance between \mathbf{f} and its estimated $\hat{\mathbf{f}}$ is residual vector \mathbf{v} . Therefore;

$$\hat{\mathbf{X}} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{f} \quad (3.18)$$

$$\mathbf{v} = \mathbf{f} - \hat{\mathbf{f}} = \mathbf{f} - \mathbf{A}(\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{f} \quad (3.19)$$

To define the *spectrum* form of equation 3.19, we need to \mathbf{p} (orthogonally projection of \mathbf{f});

$$\mathbf{p} = \sum_i \phi_i \hat{x}_i = \Phi \hat{\mathbf{X}} \quad (3.20)$$

where Φ is base function (equation 3.16) and $\hat{\mathbf{X}}$ is unknown vector. Figure 3.1 shows geometrical relations between \mathbf{f} , \mathbf{M} , \mathbf{p} and ϕ_i .

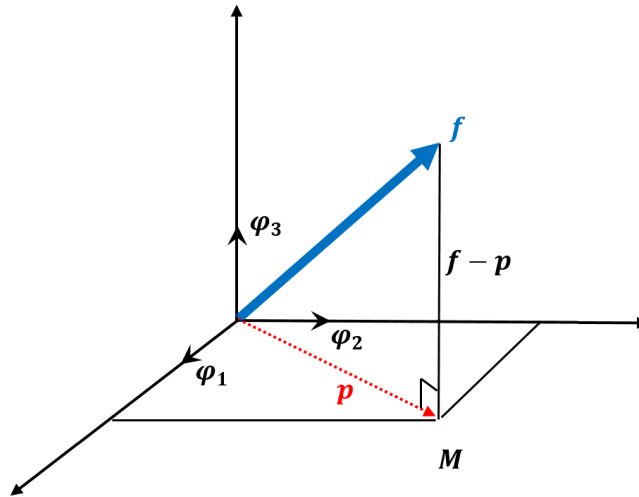


Figure 3.1 : Geometrical relations between f, M, p and ϕ_i

By using the least square theorem, the difference between f and p is equal to *residual* (v);

$$\hat{X} = (\Phi^T \Phi)^{-1} \Phi^T f \quad (3.21)$$

$$p = \Phi (\Phi^T \Phi)^{-1} \Phi^T f \quad (3.22)$$

therefore;

$$v = f - p = f - \Phi (\Phi^T \Phi)^{-1} \Phi^T f \quad (3.23)$$

To estimate the similarity between p and f , the p must be projected back onto f . This procedure introduces the *spectrum* (figure 3.2) (Hui and Pagiatakis, 2004).

$$S = \frac{\langle f, p \rangle}{\|f\|} = \frac{f^T p}{f^T f} \quad (3.24)$$

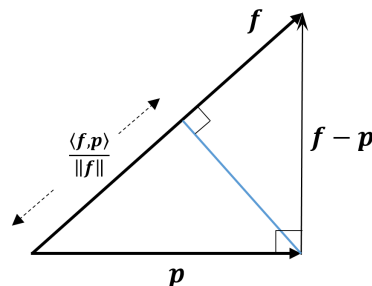


Figure 3.2 : Second projection

In LSSA method, the base function (Φ) is expressed in sine and cosine form ($\Phi = [\cos \omega_i t, \sin \omega_i t]$). Therefore, because of dependency between p and frequency, ($p(\omega_i)$),

spectrum S can be written in this form;

$$S(\omega_i) = \frac{\mathbf{f}^T \mathbf{p}(\omega_i)}{\mathbf{f}^T \mathbf{f}}, i = 1, 2, \dots, m. \quad (3.25)$$

It can be seen that, the spectral value is obtained with two orthogonal projections;

1: \mathbf{f} onto $\mathbf{M}(\Phi)$ manifold $\Rightarrow \mathbf{p}$

2: \mathbf{p} onto $\mathbf{f} \Rightarrow$ spectral value

However this procedure is done when there is no known constituent value (noise base function Φ). Often we know the noise base functions but we do not know the magnitudes of them inside the time series. In this case, our calculation space becomes smaller than the previous case (degree of freedom is lesser). Now, the Φ vector is converted to known constituents $\hat{\Phi}$ and $\hat{\mathbf{p}} = \hat{\Phi} \hat{\mathbf{X}}$ (Wells et al., 1985). Produced manifold from these base functions will be $\mathbf{M}(\hat{\Phi})$. To obtain the spectral value with known constituents, three orthogonal projection must be done;

1: \mathbf{f} onto $\mathbf{M}(\hat{\Phi})$ manifold $\Rightarrow \hat{\mathbf{p}}$.

Unlike the previous procedure, $\hat{\mathbf{p}}$ cannot projected back onto \mathbf{f} directly, because this new function cannot approximate the original function \mathbf{f} . Therefore, difference of these functions must be calculated;

$$\mathbf{g} = \mathbf{f} - \hat{\mathbf{p}} \quad (3.26)$$

2: \mathbf{g} onto $\mathbf{M}(\Phi) \Rightarrow \mathbf{r}$

3: \mathbf{r} onto $\mathbf{g} \Rightarrow$ spectral value (Wells et al., 1985)

In the Least Square Spectral Analysis program, spectrum (spectral value), i.e. the similarity ratio, is shown as percentage. It is very important to know which peaks of spectral value is statistically significant (Pagiatakis, 1999). Another parameter which is calculated by Least Square Spectral program is *Power Spectral Density (PSD)* of the time series. It is proofed that the least square spectrum can be defined as a ratio of two stochastically independent quadratic forms Q_n (noise) and Q_s (signal) (Pagiatakis, 1999);

$$S = \left[1 + \frac{Q_n}{Q_s} \right]^{-1} \quad (3.27)$$

The equation 3.27 is the inverse of *signal-to-noise* ratio (SNR). By taking the logarithm from S , power spectral density (in decibels, dB) is obtained;

$$PSD_{LS} = 10 \log_{10} \left[\frac{S}{1-S} \right] \quad (3.28)$$

Relation between spectral value and power spectral density is represented in figure 3.3. The Least Square Spectral Analysis program is *LSSA* in Fortran execution. This

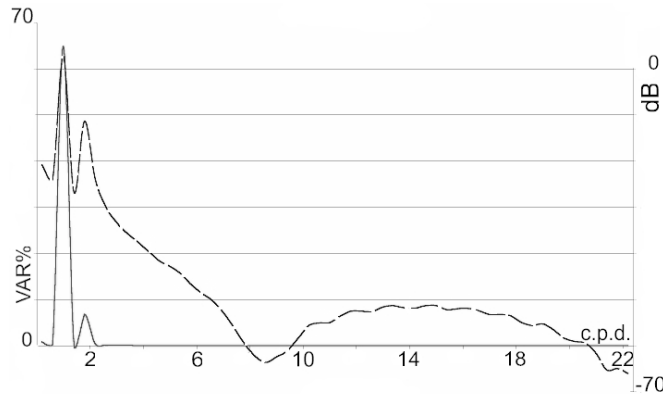


Figure 3.3 : Comparison between least square spectrum (solid line) and its power spectral density in dB (Omerbashich, 2003)

program can analyse 10000 values. Known constituents, can be divided in four groups, based on the following equation;

$$x(t) = b_0 + b_1t + \sum_{k=1}^N [A_k \cos(\omega t) + B_k \sin(\omega t)] \quad (3.29)$$

- Datum Biases (b_0)
- Linear trend (b_1t)
- Periodic Constituents with known periods (Forced periods)
- Arbitrary user-specified constituents (e.g. quadratic trend or exponential trend)

This program consist of "lssa.in", data file and execution file. After analysis, "lssa.out", "spectrum.dat", "residual.dat" and "hist.dat" are created. In order to show the time series and spectrum values, a MATLAB program was written. In this program, all applied constituents such as datum shifts, trend, forced periods and user-specified constituents are shown. Also time series without trend is represented.

3.4 Short-Time Fourier Transform (STFT)

According to Fourier series, a function can be written by summation of different function, based on their *weighted combination*:

$$f(t) = \sum_i \omega_i \Phi_i(x) = \sum_{n=1}^{\infty} \omega_n \sin(2\pi n f_0 t) \quad (3.30)$$

where the $\Phi_i(x)$ function is called *Kernel* (Sünkel, 1986). The term of weighted combination is used because in the right side of equation 3.30, ω_n shows that, what is the contribution of *sin* function to produce the *f* function (*Inner product*) (Wells et al., 1985).

The most important weakness of Fourier transform is the low resolution in a specific region (Keller, 2004). In other words, the Fourier transform cannot give desired resolution in whole of signal because *sine* functions - operate in background of it - play a *general* role through the signal. The Fourier transform is not sensitive to abrupt fluctuation. Therefore we cannot extract features through signals. However, it must be mentioned that if we want to obtain high resolution data from Fourier transform, the number of *sin* terms must be increased more and more. In figure 3.4 this case is shown.

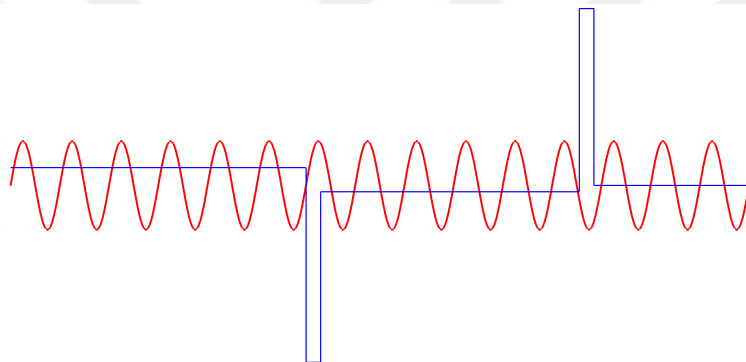


Figure 3.4 : A signal (blue) which is covered by *sine* function (red)

We try to reconstruct the blue signal based on an artificial red *sine* function. In figure 3.4, with a glance, we convolve *sine* terms and making an approximation of signal. However all signal cannot be covered by *sine* function. It is possible, if we add more terms of *sine* terms, but this operation firstly takes more time and on the other hand our computation will be more complicated.

If the *Fourier series* is written in this form (Sünkel, 1986);

$$f(t) = \sum_{n=1}^{\infty} a_n \cos(2\pi n f_0 t) + b_n \sin(2\pi n f_0 t); i = 1, 2, \dots, n \quad (3.31)$$

where,

$$a_n = \frac{1}{T} \int_0^T f(t) \cos(2\pi n f_0 t) dt \quad (3.32)$$

$$b_n = \frac{1}{T} \int_0^T f(t) \sin(2\pi n f_0 t) dt$$

If $nf_0 = \zeta$ is assumed and *sine* function is expanded to exponential series, the *Fourier Transform* will be written in this form;

$$f(\zeta) = \int_{-\infty}^{\infty} f(t)e^{-j2\pi\zeta t} dt \quad (3.33)$$

Equation 3.33 shows the efficacy of ζ frequency to form the function f . In other words, the Fourier transform formula expresses the similarity between $f(t)$ and $e^{-j2\pi\zeta t}$ parts (Inner Product theory).

By using the Least Square Spectral Analysis, the frequencies and spectrum of signal can be determined but it does not represent at what time these changes happened.

In order to evaluate signal in different times, *Short-Time Fourier Transform (STFT)* or *Windowed* are used. It can be said that by using STFT, operational range of Fourier transform will be limited.

If in equation 3.33, $2\pi\zeta = \omega$, therefore;

$$F(\omega) = \int_{-\infty}^{\infty} f(t)e^{-j\omega t} dt \quad (3.34)$$

Now, in order to localize the function $F(\omega)$, a weighting function with lower and upper boundary with specifications of *Gaussian* function is defined. This function is also centralized in zero point (figure 3.5)

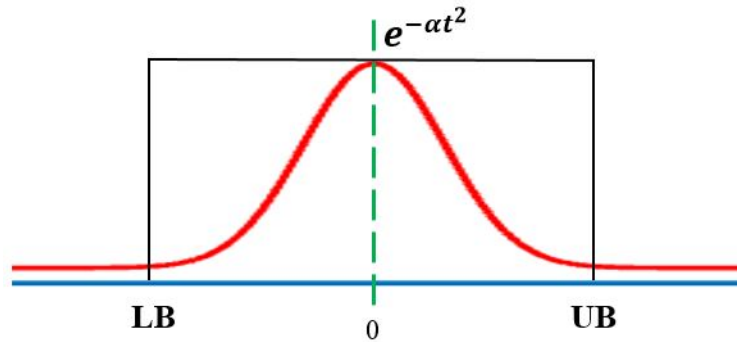


Figure 3.5 : Localized weighting function with Gaussian shape

Integration and normalization of function $e^{-\alpha t^2}$ will be $\sqrt{\frac{\alpha}{\pi}}e^{-\alpha t^2}$. On the other hand, if a function move to right or left side (*Time-shifting*), $f(t)$ function is transferred to $f(t - \tau)$ (figure 3.6)

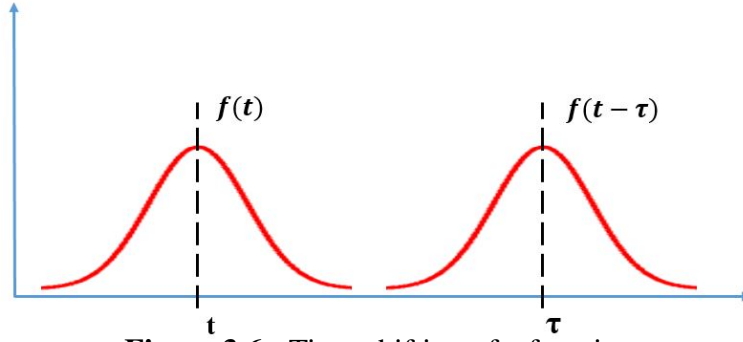


Figure 3.6 : Time-shifting of a function

Therefore Time-Shifting of the recent function will be;

$$W(t) = \sqrt{\frac{\alpha}{\pi}} e^{-\alpha t^2} \Rightarrow W(t - \tau) = \sqrt{\frac{\alpha}{\pi}} e^{-\alpha(t-\tau)^2}$$

Note: instead of using f function, W ($W(t)$ and $W(t - \tau)$) is used.

Now if $W(t - \tau)$ function is multiplied by $F(\omega)$ function, frequency in a specific time will be obtained.

$$\begin{aligned} F(\omega) &= \int_{-\infty}^{\infty} f(t) e^{-j\omega t} \sqrt{\frac{\alpha}{\pi}} e^{-\alpha(t-\tau)^2} dt \\ &= \int_{-\infty}^{\infty} f(t) e^{-j\omega t} W(t - \tau) dt \end{aligned} \quad (3.35)$$

As it is shown in equation 3.35, F not only relates to ω , but also it depends on τ . It means that, it can possible to know the location (time) of frequency.

The balance between time and frequency resolution are controlled by the size of function W (Keller, 2004). To define the window function W , lower and upper boundary was considered. If this boundary changes, the window size changes, too.

Briefly, difference between Fourier and short-time Fourier transform can be represented in the following graphs (figure 3.7).

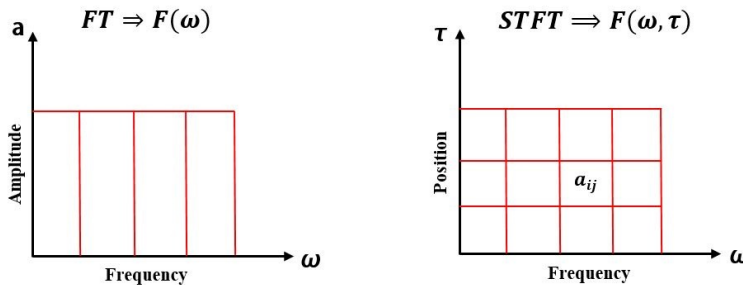


Figure 3.7 : The concept of Fourier and short-time Fourier transform (MATLAB, 2015)

The short-time Fourier transform can solve the time resolution problem rather than classic Fourier transform but this time resolution is same for all frequencies. In other

words, for different high and low frequency signals, only one time resolution (window) can use. This is not good achievement because in high frequency signal, abrupt frequency changes are happened that STFT cannot see and analyze them. Therefore different size of window must be used for high and low frequency signals. However, there is a limitation to change the window size (uncertainty principle) (Keller, 2004). It means that only one window size can move through the signal and it is not possible to change its size during computation. Thus, we can select enough small window but it is time consuming and complicated when the lower frequency signals are used. This discussion leads us to *Wavelet Theory*.

For Short-Time Fourier Transform, a *spectrogram* code in MATLAB program can be used. As it mentioned before, another name of STFT is windowed method. spectrogram function returns the STFT of the input signal and also uses window (integer number) to divide the signal into sections and perform windowing (MATLAB, 2015).

3.5 Wavelet Theory

The main Properties of Wavelet are;

1. It must be limited in time domain, accurately. It means that;
 - There is a maximum value of *Lower Boundary* that $\forall t \leq LB : \psi(t) = 0$.
 - There is a minimum value of *Upper Boundary* that $\forall t \geq UB : \psi(t) = 0$.
2. Its mean value must be zero. $\int_{-\infty}^{\infty} \psi(t) dt = 0$
3. It must have non-zero norm. $0 < \int_{-\infty}^{\infty} |\phi(t)|^2 dt < \infty$

These properties are shown in the following figure;

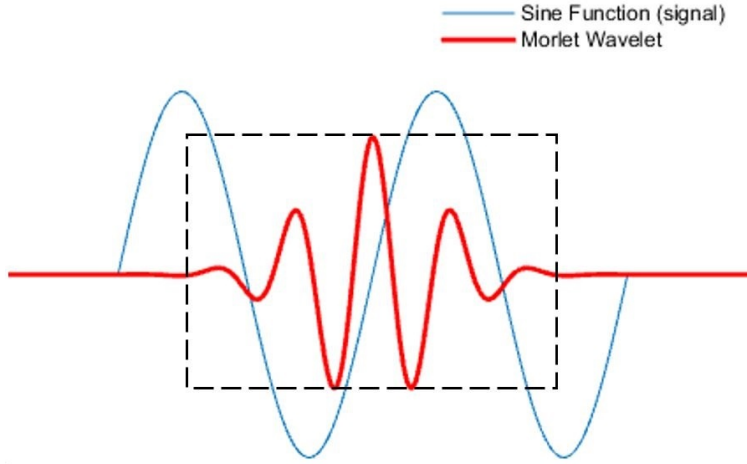


Figure 3.8 : A signal (blue) which is covered by a wavelet (Morlet wavelet). The wavelet window (black dash square) move through the signal

In order to obtain the mathematical form of wavelet, *sine* function can be written in this form;

$$a_n \cos(\omega_n t) + b_n \sin(\omega_n t) = c_n \sin(\omega_n t + \phi_n) \quad (3.36)$$

if $\omega_n = n\omega_0$, therefore;

$$c_n \sin(\omega_n t + \phi_n) = c_n \sin(n\omega_0 t + \phi_n) \quad (3.37)$$

We define a function $\psi(t)$ that $\psi(t) = \sin(\omega_0 t)$, thus, equation 3.37 will be rewritten as;

$$\begin{aligned} c_n \sin(n\omega_0 t + \phi_n), &\triangleq \psi(t) = \sin(\omega_0 t), \\ c_n \sin(n\omega_0 t + \phi_n) &= c_n \psi\left(nt + \frac{\phi_n}{\omega_0}\right) \end{aligned} \quad (3.38)$$

where, $\psi(t)$ function is called *main function*, n is Scaling and $\frac{\phi_n}{\omega_0}$ is Time Shifting. Generally, ψ is written as a function of a and b in this form (Abbasi, 1999);

$$\psi_{a,b}(t) = \frac{1}{\sqrt{a}} \psi\left(\frac{t-b}{a}\right) \quad (3.39)$$

where, a is wavelet scaling parameter and b is time shifting parameter. This time shifting and scaling are shown in figure 3.9 and 3.10.

When a is small, it means that high frequency parts of a signal can be recognized and vice versa. Also it can be said that a shows the lifetime of wavelet while b express the location of wavelet. However the story of wavelet is completed when we can answer the final question: what is the wavelet's coefficient? It means that how much

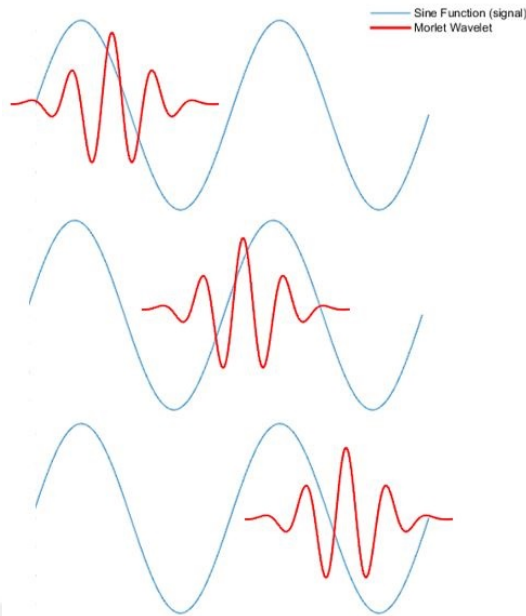


Figure 3.9 : Time-shifting of a wavelet in signal

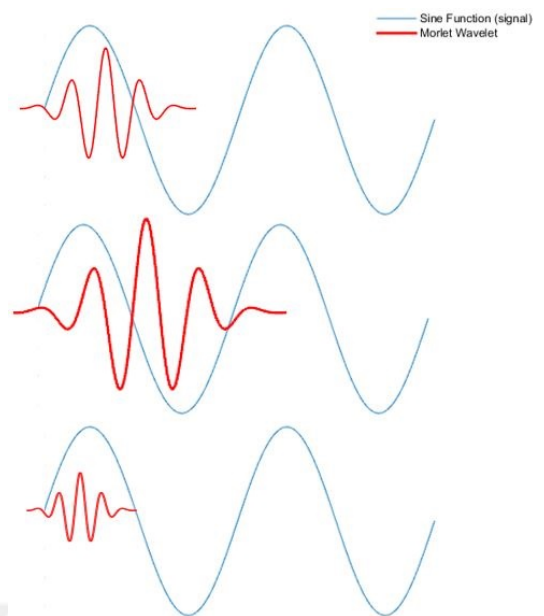


Figure 3.10 : Scaling of a wavelet in signal

is the contribution of function ψ in signal f . For this reason, as it is mentioned before, *similarity* between main signal and wavelet functions (*Inner product*) must be found;

$$c_{f,\psi}(a,b) = \int_{-\infty}^{\infty} f(t)\psi_{a,b}(t)dt \quad (3.40)$$

Like figure 3.7, principle of wavelet can be also shown. In figure 3.11 main important differences of wavelet transform with other STFT and classic Fourier transform is expressed.

$$\text{Wavelet} \Rightarrow c_{f,\psi}(a,b)$$

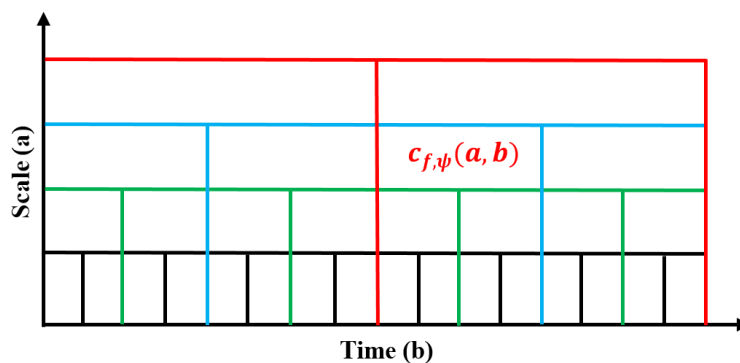


Figure 3.11 : Principle of wavelet transform

By comparing figure 3.11 and figure 3.7, it can be said that, in wavelet transform, evaluation of signal's frequency in different places or locations can be possible. For

example, some frequencies can be evaluated in two places (red parts), four places (blue parts), eight places (green parts) or sixteen places (black parts). It means that - unlike STFT - it is not necessary to calculate one scales (window) in all places. But the question is, why we use different scales? In some case we need to know about details and changes in specific time of a signal and in the other case a general view of signal's manner is enough. Therefore choosing high frequency portion (small scales) or low frequency portion (big scale) can help us to decide and evaluate of signal.

Wavelet transform can be used for *filtering*. In this situation, instead of using $f(t)$ and $\psi(t)$ in equation 3.40, their frequency properties are used ($\hat{f}(t)$ and $\hat{\psi}(t)$). In other words, Fourier transform of equation 3.40 will be applied. This application of wavelet is done by using the *Continuous Wavelet Transform (CWT)* and *Discrete Wavelet Transform (DWT)*. CWT mainly is used for feature extraction while DWT is useful for noise reduction and data comparison (Grinsted et al., 2004).

Wavelet toolbox in MATLAB is a powerful tools for analysing signals with different frequencies and noises. In this toolbox, there are different algorithms such as CWT, DWT, scalogram, wavelet coherence and etc. Also signal decomposition and denoising can be applied in different scale and resolution (MATLAB, 2015). In order to determine relationship between two time series in spectral domain, *Cross Wavelet Transform (XWT)* and *Wavelet Coherence (WTC)* of two CWT are used. XWT calculates power and relative phase in time-frequency space and WTC find significant coherence and confidence levels against noises (Grinsted et al., 2004).

XWT of two time series x_n, y_n is defined as $W^{xy} = W^x W^{y*}$ (* denotes the complex conjugation). The theoretical distribution of cross wavelet power of two time series with power spectra P_k^X and P_k^Y is;

$$D \left(\frac{|W_n^X(s)W_n^Y(s)|}{\sigma_x \sigma_y} < p \right) = \frac{Z_v(P)}{v} \sqrt{P_k^X P_k^Y} \quad (3.41)$$

where, $Z_v(P)$ is the confidence level related to the probability P for a pdf (defined by the square root of the χ^2 distribution) and $W_n^X(s), W_n^Y(s)$ are the wavelet powers. In order to determine phase difference between two time series, mean and confidence interval of the phase difference must be estimated. Because CWT cannot be localized in time completely, an edge artifacts is created in this algorithm. Therefore a *Cone of Influence (COI)* regions are defined. According to COI, a circular mean and circular

standard deviation of the phases are defined.

$$a_m = \arg(X, Y) \quad X = \sum_{i=1}^n \cos(a_i) \quad \text{and} \quad Y = \sum_{i=1}^n \sin(a_i) \quad (3.42)$$

$$s = \sqrt{-2 \ln(R/n)} \quad (3.43)$$

where, $R = \sqrt{(X^2 + Y^2)}$.

WTC is the answer of this question, how is the coherence of XWT in time frequency domain? The following equation shows the wavelet coherence of two time series;

$$R_n^2(s) = \frac{|S(s^{-1}W_n^{XY}(s))|^2}{S(s^{-1}|W_n^X(s)|^2) \cdot S(s^{-1}|W_n^Y(s)|^2)} \quad (3.44)$$

where, S is a smoothing operator. According to equation 3.44, wavelet coherence is a localized correlation coefficient in time frequency domain (Erol, 2011; Grinsted et al., 2004).

3.6 Principle Component Analysis

Principal Component Analysis (PCA) is a mathematical procedure to reduce the dimensionality of a correlated large number of data. This transformation is done by using *Principle Components* variables which are linearly uncorrelated (Jolliffe, 2002). Mathematically, PCA can be mapped a data set from a large space to a small space. It can be said that:

$$Y = Q^T X \quad Q = X \rightarrow Y, \quad Q: \text{Mapping function (e.g. vector)} \quad (3.45)$$

where X is an observation matrix and $X = (x_1, x_2, \dots, x_p), x_i \in \mathbb{R}^p, x_i = (x_{i1}, x_{i2}, \dots, x_{in})^T$ and $Q^T = (q_1, q_2, \dots, q_m)^T$ (figure 3.12). It must be mentioned that mapping function of Q^T does not change the number of dimension but it helps us to select some important and powerful dimensions. Suppose that x is a vector with p random variables that

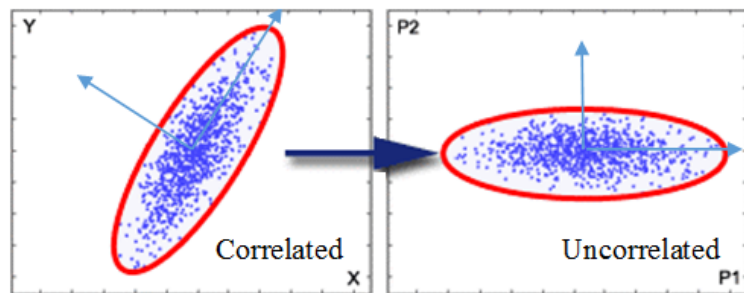


Figure 3.12 : Principle Component Analysis

each variable has variances and we want to know about the covariances (correlations) between the variables.

Linear function of the first component q_1 for the element x with maximum variance can be defined in this form:

$$q_1^T x = q_{11}x_1 + q_{12}x_2 + \dots + q_{1p}x_p = \sum_{j=1}^p q_{1j}x_j \quad (3.46)$$

If the K^{th} principle component of element x is considered,

$$z = A^T x \quad (3.47)$$

where A is the orthogonal matrix and K^{th} column is the K^{th} eigenvector of *covariance matrix* Σ . Therefore, the PCs will be an orthonormal linear transformation of x .

$$\Sigma A = A \Lambda \quad (3.48)$$

where Λ is the diagonal matrix. The following two expression can be used for representation of the above formula;

$$A^T \Sigma A = \Lambda \quad (3.49)$$

and

$$\Sigma = A \Lambda A^T \quad (3.50)$$

Geometrically, principle components can be defined as principle axis of an ellipsoid. By using equation 3.47 ($x = Az$) and equation 3.49, it can be said that, $z^T \Lambda z = const$ and this equation can be rewritten

$$\sum_{k=1}^p \frac{z_k^2}{\lambda_k} = const \quad (3.51)$$

where λ is eigenvalue. This equation shows principle axis of an ellipsoid (Jolliffe, 2002). It means that, the first principle axis (principle component) directed through greatest statistical variation. The second principle axis directed through the next great statistical variation and also orthogonal to the first one. This behavior will continue for other PCs.

Briefly, it can be said that, the aim of using PCA, finding and arranging eigenvalues from maximum to minimum in order to achieve eigenvectors (principle components) through the data set.

$$\lambda_1, \lambda_2, \lambda_3, \dots, \lambda_m, \lambda_1 \geq \lambda_2 \geq \lambda_3 \dots \geq \lambda_m, \lambda_1 = \lambda_{max}$$

$$q_1, q_2, q_3, \dots, q_m$$

Finally, selection of the most important and efficient principle components (not using all PCs) provides *Dimensionality Reduction* (Jolliffe, 2002; MATLAB, 2015).

In order to determine outliers, some statistical analysis can be used. One of these statistics is *Hotelling's T-Square* algorithm. Actually, Hotelling's T-Square is the square of the t-student testing hypothesis regarding to univariate mean.

$$t = \frac{\bar{x} - \mu}{S/\sqrt{n}} \quad (3.52)$$

Therefore,

$$t^2 = \frac{(\bar{x} - \mu)^2}{S^2/n} = n(\bar{x} - \mu)(S^2)(\bar{x} - \mu) \sim F_{1,n-1} \quad (3.53)$$

For large n , T^2 is approximately chi-square distributed (specially, when S replaced by variance-covariance matrix Σ). According to PCA algorithm, based on mapping function of eigenvectors (principle components), observations are transformed to the new *normalized space*. Therefore, all observations in new space have normal distribution ($N(0, 1) \sim Z$). By this definition, it can be said that, Hotelling's T-squared statistic is a statistical value of multivariate distance for each observation from the center of the data set (MATLAB, 2015; PennState, 2016; Santos-Fernández, 2012).

There is a MATLAB function for principle component analysis (pca function). Its output includes principle component coefficients (eigenvector), eigenvalues, new values in new dimension, Hotelling's T-squared statistic and other statistical parameters. Also by using some plot functions, *outlier detection* can be applied.

Note: In order to calculate the PCA in Matlab, Singular Value Decomposition (SVD) algorithm was used.



4. DATA ANALYSIS

In this chapter, data evaluations and processes are divided into two parts; tide-gauge and altimetry data analysis. After that, vertical land motion process will be explained. Also procedures of applying different methods will be verified, separately.

4.1 Investigation of Tide gauge data

According to table 2.1, firstly, time series of tide gauge stations was provided (in figure 4.1 - 4.10).

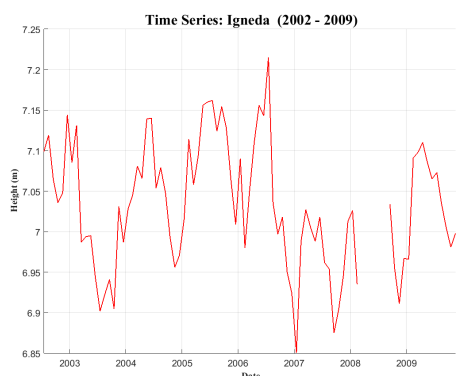


Figure 4.1 : Time series of Igneđa

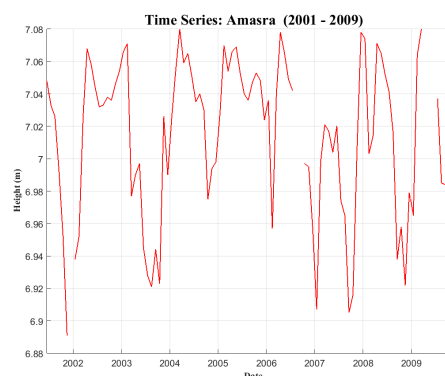


Figure 4.2 : Time series of Amasra

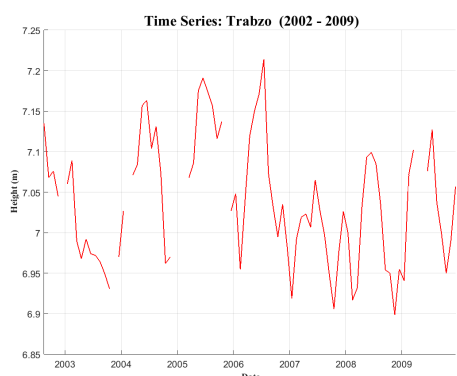


Figure 4.3 : Time series of Trabzon

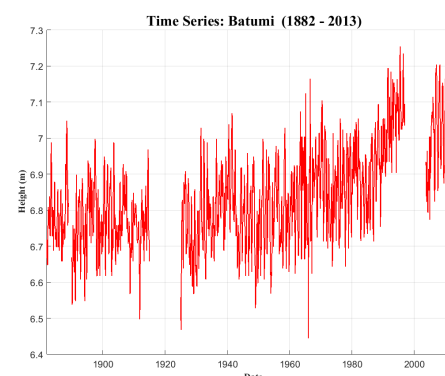


Figure 4.4 : Time series of Batumi

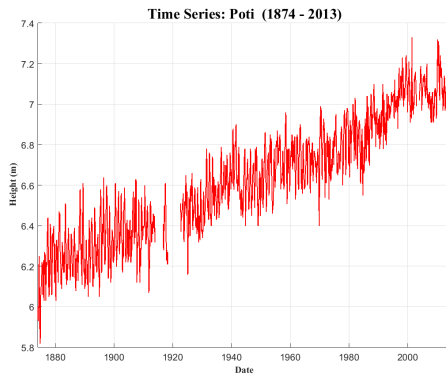


Figure 4.5 : Time series of Poti

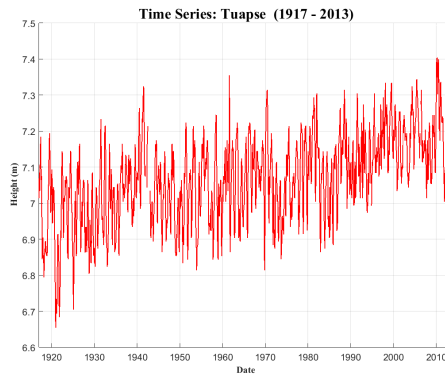


Figure 4.6 : Time series of Tuapse

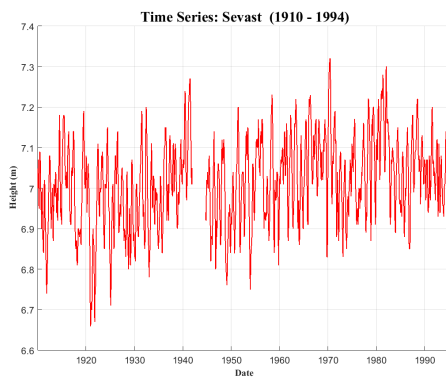


Figure 4.7 : Time series of Sevastopol

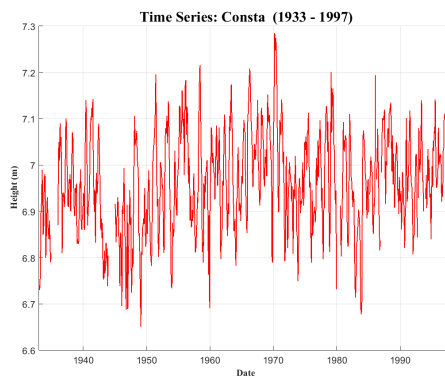


Figure 4.8 : Time series of Constantza

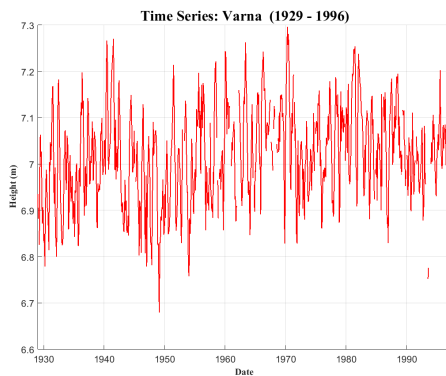


Figure 4.9 : Time series of Varna

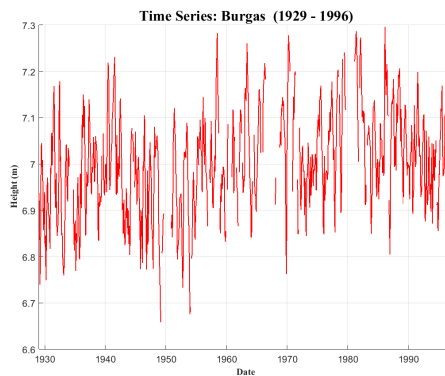


Figure 4.10 : Time series of Bourgas

Generally, calculation and analysing time series with different characteristics (such as, time duration, number of gaps, noises or spikes and etc.) are difficult and complicated. Also, in our case, time series duration are not coincided with each other, in some stations. Therefore, for obtaining confident and reliable results, it must be applied different algorithms to detect various behaviours of data sets.

In this study, in order to determine tidal constituents, following steps was applied;

1. Obtaining tidal constituents based on LSSA method and result evaluation with defined tidal constituents in literature
2. Outlier detection by using PCA method
3. Repeat the first step with modified data from the second step (after remove outliers)

4.1.1 Spectral analysis with LSSA

In order to get accurate understanding and correct representing of figures in LSSA procedure, whole data was not investigated in one spectral band and the best spectral bands - after try and error in several times - was selected based on following status;

- Short time series (i.e. smaller than 100 data (Igneada, Amasra and Trabzon)) into one spectral bands:
 - 2 - 100 cycle per month
- Long time series (i.e. bigger than 100 data (other stations)) into three spectral bands:
 - 2 - 8 cycle per month
 - 9 - 14 cycle per month
 - 15 - 800 cycle per month

Also, time series with trend and residual was calculated.

$$Residual = Time\ series - (Datum\ shift, Trend, Forced\ periods)$$

All time series (with linear trend), residuals and spectral analysis are represented in *Appendix A*. Along with figures of each tide gauge station, table of spectral result is provided, too. In spectral analysis figures, spectrum (black line), 99% confidence level (violet line) and calculated constituents (red point) is shown. Beside of some constituent, its period is also written.

Spectral tables include, calculated constituents (1st column), period in month (2nd column), amplitude and its accuracy in meter (3rd and 4th column), phase and its accuracy in degree (5th and 6th column) and finally spectrum in percent.

When the results of LSSA are compared to the real tidal constituents, (table 4.1), it

can be seen that 2 constituent are very close to the real long period constituent. These constituents are *Solar semiannual* (S_{sa}) and *Solar annual* (S_a).

Table 4.1 : Diurnal and long period tidal constituents (NOAA, 2016a)

Diurnal	Darwin Symbol	Period (hr)	Speed (°/hr)
Lunar diurnal	K_1	23.9345	15.0411
Lunar diurnal	O_1	25.8193	13.9430
Lunar diurnal	OO_1	22.3061	16.1391
Solar diurnal	S_1	24.0000	15.0000
Smaller lunar elliptic diurnal	M_1	24.8412	14.4921
Smaller lunar elliptic diurnal	J_1	23.0985	15.5854
Larger lunar evectional diurnal	P	26.7231	13.4715
Larger lunar elliptic diurnal	Q_1	26.8684	13.3987
Larger elliptic diurnal	$2Q_1$	28.0062	12.8543
Solar diurnal	P_1	24.0659	14.9589
Long period	Darwin Symbol	Period (hr)	Speed (°/hr)
Lunar monthly	M_m	661.3112	0.5444
Solar semiannual	S_{sa}	4383.0763	0.0821
Solar annual	S_a	8766.1527	0.0411
Lunisolar synodic fortnightly	M_{sf}	354.3671	1.0159
Lunisolar fortnightly	M_f	327.8599	1.0980

However, in some cases, there are a lot of constituents that are not included in the table 4.1. There are many reasons for this incompatibility such as, shallower, rivers, side-effect of deep oceanic (Pawlowicz et al., 2002), noises and etc. Evaluation of causes of these effects is not subject of this study; however, finding the fundamental and the common tidal constituents between time series is included. It must be mentioned that, there are some other long periods such as, nodal tide (18.6 years), but because these periods cannot be detected in all time series, they are not considered. In order to determine the amplitude and phase of each significant values (i.e. it is called *fidelity* in LSSA program), these periods or frequencies must be forced into LSSA program, again. Based on obtained amplitude and phase of semiannual and annual periods -as the most important tidal constituent of monthly tide gauge time series analysis- and also trend of each time series, which are represented in tables A.1 - A.10 in Appendix A, (they are summarized in table 4.2), related figures are prepared (figures 4.11, 4.12 and 4.13). In the amplitude-phase figures, size of arrow shows the

magnitude of amplitude and its direction shows the phase value (the same direction of trigonometry angle).

Table 4.2 : Amplitude and phase of semiannual and annual periods of tide gauge stations

	Solar Semiannual		Solar Annual	
	Amplitude (mm)	Phase (deg)	Amplitude (mm)	Phase (deg)
Igneada	-	-	42.2	313.6
Amasra	-	-	30.8	345.4
Trabzon	-	-	58.5	344.3
Batumi	30.3	49.5	60.5	218.8
Poti	33.9	42.3	86.4	172.9
Tuapse	38.6	54.4	72.7	173.7
Sevastopol	31.0	37.7	76.3	169.9
Constantza	18.7	37.3	68.0	221.5
Varna	20.7	27.6	67.0	177.6
Burgas	21.1	36.8	71.2	177.9

Amplitude-Phase Map of Solar Semiannual (S_{sa}) Period

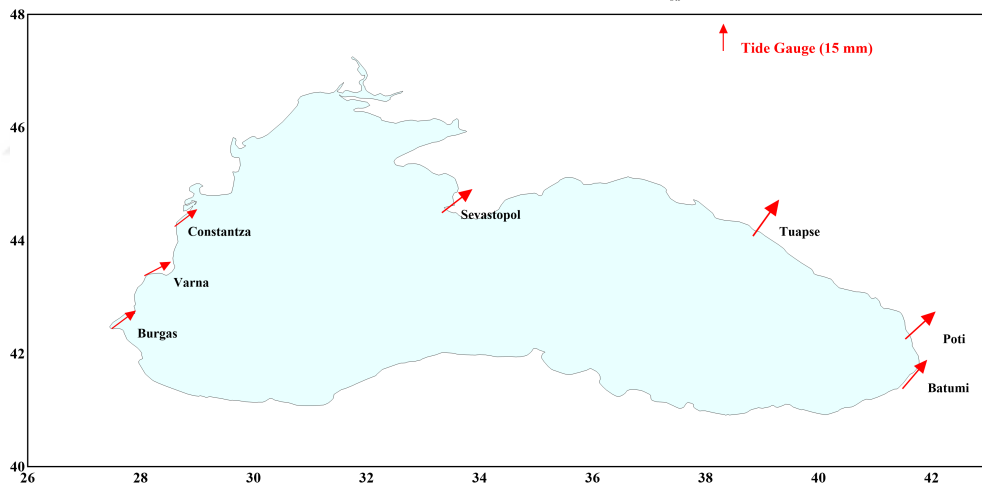


Figure 4.11 : Amplitude and phase map of Solar Semiannual (S_{sa}) periods of tide gauge stations

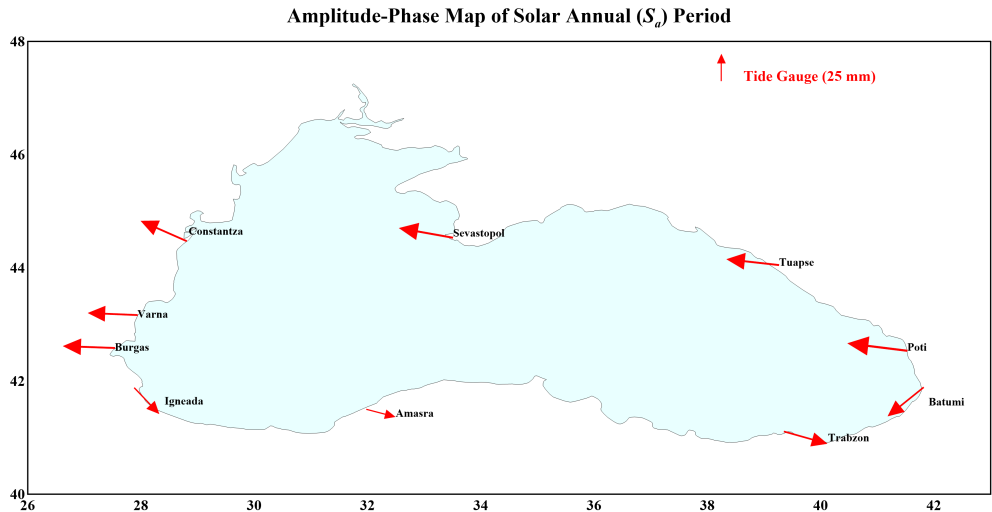


Figure 4.12 : Amplitude and phase map of Solar Annual (S_a) periods of tide gauge stations

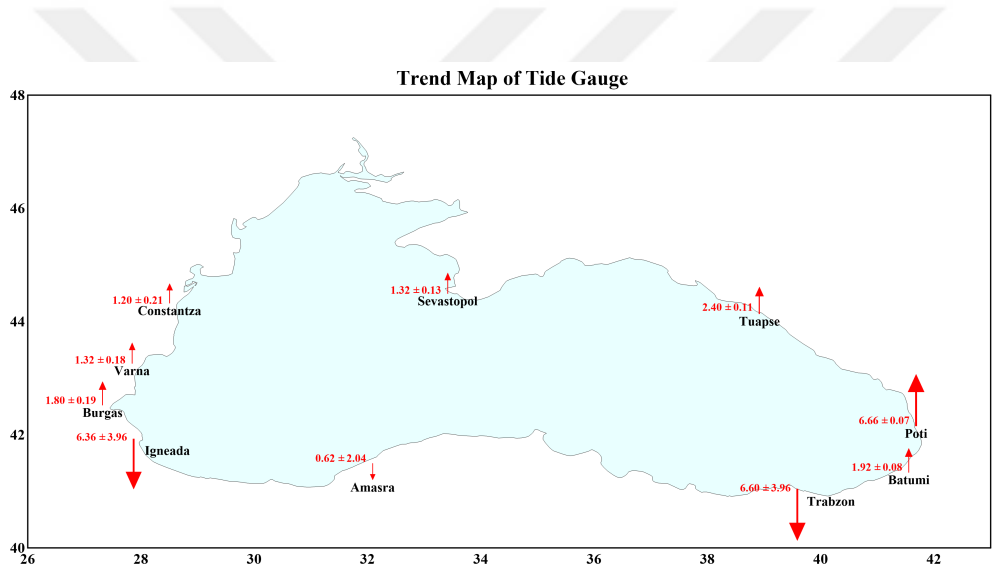


Figure 4.13 : Trend map related to tide gauge stations (mm/year)

Between all parameters which affect the tidal constituents in LSSA method (of course that all represented constituents in table A.1 - A.10 of Appendix A, is not natural constituents), detecting and eliminating noises are important for us. Noise can be spikes or can change the spectrum of a tidal constituents which must be eliminated from time series. One of the methods to eliminate the noises is outlier detection methods and one of the algorithms is Principle Component Analysis.

4.1.2 PCA method

In the previous method, each data set can be analysed separately and there is no any restriction to use them. However, in order to apply the PCA methods, all input variables (in this case time series) must have the same time frame. Therefore, all previously

applied series for LSSA, are not suitable for this methods.

For selecting suitable time series for PCA algorithm, two key points was considered;

1. Smallest number of gaps through data set
2. Long time observation in station

Based on these key points and according to time duration and number of gaps of each station (table 2.1), the following stations was selected (table 4.3).

Table 4.3 : Investigation of time series for Principle Component Analysis

	First date	Last date	Values	Void data	Valid data
Batumi	1882	2013	1584	212	1372
Tuapse	1917	2013	1157	12	1145
Varna	1929	1996	816	40	776
Bourgas	1929	1996	816	112	704

However, Bourgas has large gaps (112 gaps in 816 data) and also it is very near to Varna tide gauge station. Therefore, Bourgas tide-gauge data was not considered in analyses. Selection of time series for Principle Component Analysis was provided based on “Varna” data set. Therefore, we must have 816 monthly data. Batumi is also has very gaps (212 gaps in 1372 data), but all gaps are out of the range of 1929-1997. Selected time series are shown in the following table (table 4.4)

Table 4.4 : Selected of time series for Principle Component Analysis

	First date	Last date	Values	Void data	Valid data
Batumi	1929	1996	816	0	816
Tuapse	1929	1996	816	9	807
Varna	1929	1996	816	40	776

Note that the gaps in the time series were filled using interpolation with "Moving Average" method.

In PCA algorithm, rows show the observations and columns show the variables (3 time series). In this case, we have a matrix with 816×3 dimension. The PCA results' figures are in Appendix B. Firstly, statistics of each time series was calculated (Appendix B, figure B.1 (Boxplot)). In the next step, correlation between variables are calculated. According to Eigenvector formula;

$$Rq = \lambda q \quad (4.1)$$

where q is eigenvector, λ is eigenvalue and R is the correlation matrix (square matrix) and with other specifications which was described in section 3.6, necessary parameters for PCA was calculated. Briefly, in this study, PCA algorithm includes the following parameters;

- Eigenvector: 3×3 matrix
- Eigenvalue: 3×1 matrix. This value is arranged from largest to smallest value
- Observations in new space: 816×3 matrix. Each column of this matrix shows each components and this components are arranged from largest to smallest one (based on eigenvalue).

In fact, it can be said that, PCA shows a relation between all variables in a new space. Therefore, position of each variable in this new space, is important. Figures in Appendix B (B.2 to B.5) show the relation between PCs and position of each variables. After this computation and applying Hotelling's T-Square statistic with 3σ , 20 points are defined as outlier which are listed below;

15/02/1949	16/01/1960	15/02/1960	17/08/1961	16/01/1966
17/12/1973	16/04/1976	17/11/1985	18/07/1991	15/02/1993
17/04/1993	18/05/1993	17/06/1993	18/07/1993	17/08/1993
17/09/1993	17/10/1993	17/11/1993	17/11/1994	17/07/1996

Figures (B.6 to B.8) in Appendix B, represent the original time series and their modifications which was specified with outliers (green circles). Now, outliers are eliminated from data sets and Least Square Spectral Analysis are evaluated, again.

Appendix C includes the residual figures (figure C.1 to C.3) and table of new spectrum (table C.1 to C.3).

According to result of this process, which is summarized in table 4.5, it can be seen that, spectrum value for solar semiannual and annual tidal constituents are increased (except Tuapse). On the other hand, after forced periods to LSSA program for each time series, residuals are decreased.

Table 4.5 : Comparison between tidal constituents before and after applying PCA for three tide gauge data

~ Solar Semiannual (S_{sa})	Before PCA		After PCA	
	Period(mon.)	Spec.(%)	Period(mon.)	Spec.(%)
Batumi	6.0000	4.86	6.0000	5.49
Tuapse	6.0000	8.31	6.0000	8.13
Varna	6.0000	2.22	6.0000	2.27
~ Solar Annual (S_a)	Before PCA		After PCA	
	Period(mon.)	Spec.(%)	Period(mon.)	Spec.(%)
Batumi	11.9983	25.43	11.9926	26.22
Tuapse	11.9869	27.32	11.9869	27.09
Varna	11.9755	23.48	11.9812	24.25

It should be noticed that, these 20 eliminated points (which is called outliers) are not in the gap of time series. If so, only the result of Varna must be better but Batumi with any gaps is obtained better result, too.

4.1.3 CWT, XWT and WTC

In this method, in order to select station in each side of Blacksea, Sevastopol station is also included. Again, because Turkish coastal stations have short time series (Igneada, Amasra and Trabzon), these stations was not added to this analysis. Based on table 2.1 and figure 4.7, Sevastopol has 32 gaps and these gaps are in early 50s. Thus time series of Sevastopol was modified for analysis. Table 4.6 shows selected stations with their modification.

Table 4.6 : Selected of time series for Principle Component Analysis

	First date	Last date	Values	Void data	Valid data
Batumi	1925	1996	864	0	864
Tuapse	1917	2013	1157	12	1145
Varna	1929	1996	816	40	776
Sevastopol	1944	1994	604	0	604

Appendix D represents the result of this method.

In the resultant figures, there are some important points which must be considered;

- White regions in CWT images (figures D.1, D.4, D.7, D.10, D.13 and D.16) and lighter shade regions in XWT and WTC images (figures D.2, D.3, D.5, D.6, D.8, D.9, D.11, D.12, D.14, D.15, D.17 and D.18), represent the edge artifacts. Black line around white and lighter shade regions show the COI.

- The thick black contour determines the 5% significant level against red noise.
- In XWT and WTC images, arrows show the phase relationships. Right and left arrows represent in-phase and anti-phase relationships and up and down arrows show the 90° and 270° phase relationships (Erol, 2011; Grinsted et al., 2004).

According to this results, it can be said that applied CWT for all time series and applied XWT and WTC for each pair series (Sevastopol-Batumi, Sevastopol-Tuapse, Sevastopol-Varna, Tuapse-Batumi, Tuapse-Varna and Batumi-Varna) show, firstly, 95% confidence level for semiannual and annual constituents are determined and also annual constituents have more powerful spectrum than the semiannual one. Secondly, all relative phase relationships are in-phase with each others even in Sevastopol-Tuapse very close relationship can be seen.

4.2 Investigation of satellite altimetry data

In this section, besides of using spectral analysis and outlier detection, procedures of altimetry data preparation is also explained. For this reason, altimetry data are divided into two parts; gridded and along-track altimetry data. Note that, applying outlier detection and wavelet analysis for along-track data is not possible.

4.2.1 Grid Altimetry Data

Grid altimetry data includes 8289 daily grid data between 1993 to 2015 for Blacksea region (~23 year). Table 4.7 shows some specifications of this grid data.

Table 4.7 : Specification of grid altimetry data in Blacksea

Grid Size	56×120×8289
Total Nodes	6720
Filled Nodes	3249
Blanked Nodes	3471
Resolution	7' 30" (~ 13.5km)
Longitude	27° 3' 45" - 41° 56' 15"
Latitude	40° 3' 45" - 46° 56' 15"

At the first step, Based on location of each tide gauge station (table 4.8), all of these coordinates are extracted in grid data due to form the time series.

Table 4.8 : Coordinates of each tide gauge stations in Blacksea

	North	Eest
Igneada	41° 53' 0.0"	28° 01' 0.0"
Amasra	41° 26' 0.0"	32° 14' 0.0"
Trabzon	41° 0.0' 0.0"	39° 44' 0.0"
Batumi	41° 38' 0.0"	41° 42' 0.0"
Poti	42° 10' 0.0"	41° 41' 0.0"
Tuapse	44° 06' 0.0"	39° 04' 0.0"
Sevastopol	44° 37' 0.0"	33° 32' 0.0"
Constantza	44° 10' 0.0"	28° 40' 0.0"
Varna	43° 11' 0.0"	27° 55' 0.0"
Bourgas	42° 29' 0.0"	27° 29' 0.0"

Therefore there are 10 time series with 8289 values (except of Bourgas with 8 gaps and Igneada with 23 gaps). This key point is very important because in all previous tide gauge evaluation methods the most important handicaps are either existence of many gaps through time series or having a short time series (e.g. Igneada, Amasra and Trabzon) which affect their obtained results.

For these time series, like the previous analysis, LSSA, outlier detection and wavelet transform are applied.

4.2.1.1 LSSA Method

The result of applying LSSA are represented in Appendix E (each time series and solar semiannual and annual periods). Because procedure of calculating and obtaining the spectral values was described in section 4.1.1, then it is not explained again.

According to table 4.1, and due to having very long time series, it is expected that other long tidal periods such as, M_f (Lunisolar fortnightly, 13.66 days), M_{sf} (Lunisolar synodic fortnightly, 14.77 days), M_m (Lunar monthly, 27.55 days) and M_{sm} (31.81 days) must be extracted. However, the smallest period which is seen in most of series is ~ 34 days.

According to table E.1 to E.10 which are summarized in table 4.9, amplitude-phase map of semiannual and annual tidal constituents and also trend map of time series are shown in figures 4.14, 4.15 and 4.16.

Table 4.9 : Amplitude and phase of semiannual and annual periods of extracted time series from grid data

	Solar Annual		Solar Semiannual	
	Amplitude (mm)	Phase (deg)	Amplitude (mm)	Phase (deg)
Igneada	23.2	139.1	13.6	332.7
Amasra	26.2	127.6	22.5	340.5
Trabzon	26.9	140.4	24.7	359.3
Batumi	31.6	151.7	25.1	346.9
Poti	27.7	149.8	24.7	350.4
Tuapse	38.8	118.1	19.5	0.3
Sevastopol	31.8	122.1	17.9	340.7
Constantza	28.3	105.0	15.9	274.5
Varna	25.2	133.8	16.0	313.7
Bourgas	24.0	164.5	17.3	315.4

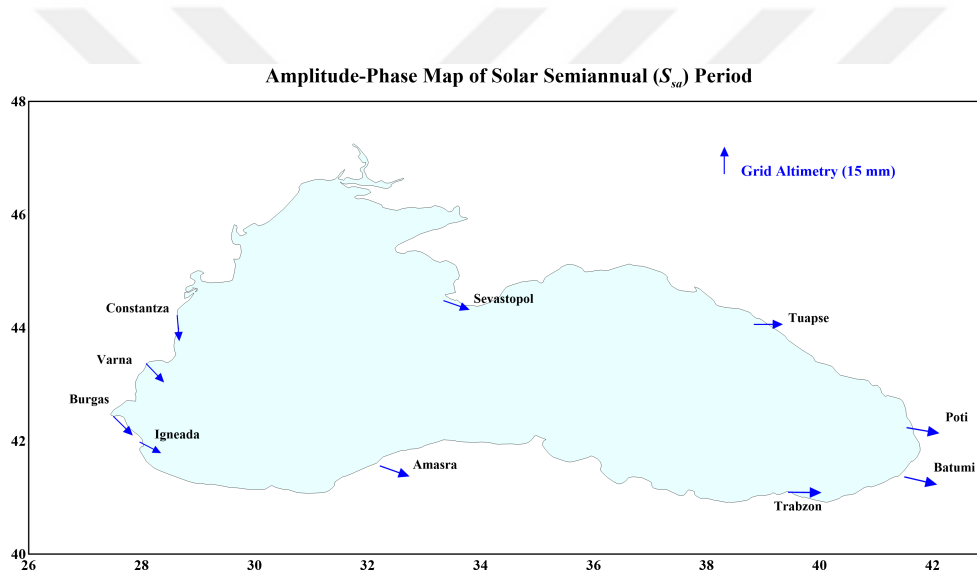


Figure 4.14 : Amplitude and phase map of Solar Semiannual (S_{sa}) periods, extracted from grid altimetry data

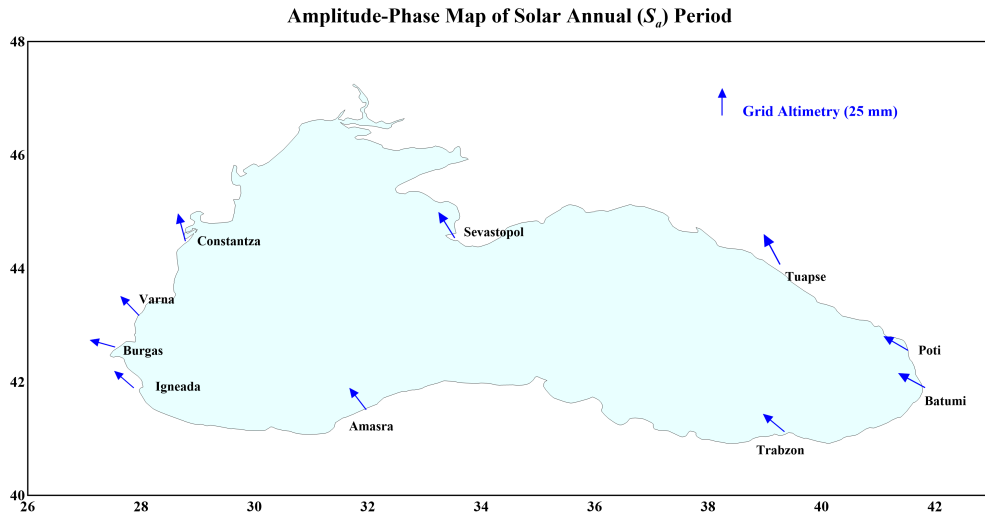


Figure 4.15 : Amplitude and phase map of Solar Annual (S_a) periods, extracted from grid altimetry data

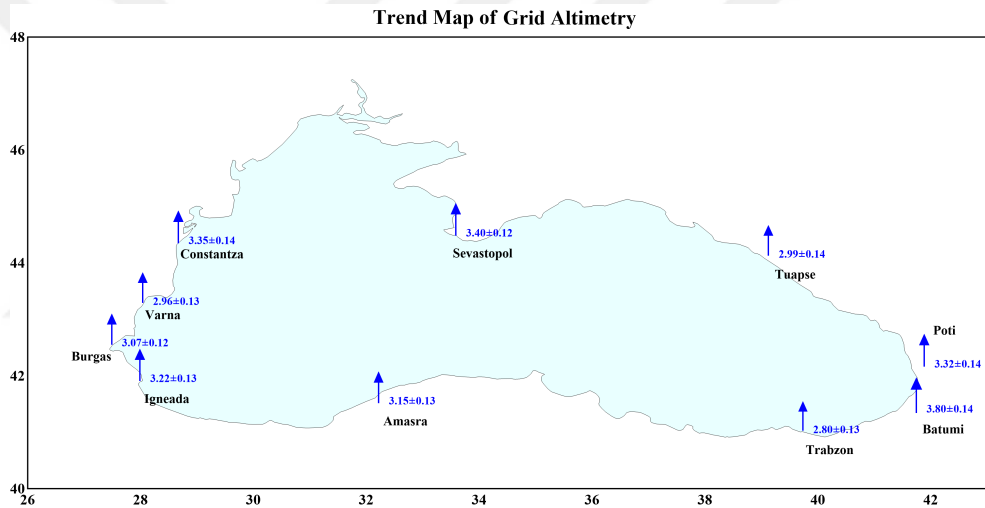


Figure 4.16 : Trend map extracted from grid altimetry data (mm/year)

4.2.1.2 PCA Method

As it mentioned in section 4.1.2, for PCA analysis, all time series must have the same time frame without any gaps. Therefore, because nearest grid points of Bourgas and Igneada have 8 and 23 gaps during whole time series, in all time series these values are removed. Thus, time series with 8266 data are extracted.

By applying PCA method and Hotelling's T-Square statistic with 3σ , 127 points are detected as outliers. The results of this process which involves the boxplot of all time series and different dimensions of principle components are represented in Appendix F. Also, comparison between semiannual and annual tidal constituents before and after applying PCA algorithm is shown in table 4.10.

As expected, the spectral values after removing outliers with PCA, mostly are increased (except of Poti and Batumi).

Table 4.10 : Comparison between tidal constituents before and after applying PCA for extracted grid altimetry data

~ Solar Semiannual (S_{sa})	Before PCA		After PCA	
	Period(day)	Spec.(%)	Period(day)	Spec.(%)
Igneada	183.1346	1.64	183.7241	2.01
Amasra	182.5491	4.37	182.5491	4.47
Trabzon	182.5491	5.34	182.5491	5.40
Batumi	182.5491	4.78	182.5491	4.79
Poti	182.5491	4.49	182.5491	4.45
Tuapse	182.5491	2.67	182.5491	2.78
Sevastopol	182.5491	2.91	183.1347	2.93
Constantza	183.7241	1.75	183.7241	1.75
Varna	183.1347	2.21	183.1347	2.31
Burgas	183.1347	2.88	183.1347	3.04
~ Solar Annual (S_a)	Before PCA		After PCA	
	Period(day)	Spec.(%)	Period(day)	Spec.(%)
Igneada	364.2662	4.74	364.2662	5.01
Amasra	364.2662	5.75	364.2662	6.03
Trabzon	364.2662	5.65	364.2662	5.85
Batumi	364.2662	8.59	364.2662	8.47
Poti	364.2662	6.57	364.2662	6.64
Tuapse	364.2662	12.38	364.2662	12.42
Sevastopol	364.2662	9.49	364.2662	9.98
Constantza	364.2662	5.32	364.2662	5.96
Varna	364.2662	5.30	364.2662	5.70
Burgas	361.9565	5.38	361.9565	5.58

4.2.1.3 Wavelet Transform Analysis

Evaluation of wavelet transform is applied based on two strategies. Firstly, in order to compare the obtained results from wavelet analysis of tide gauge (section 4.1.3) and grid altimetry, the same four stations (Sevastopol, Tuapse, Batumi and Varna) are selected and evaluated. These results are represented in Appendix G, figures G.1 - G.18. The second evaluation is related to compare the wavelet analysis of tide gauge time series and extracted time series of grid altimetry for each station. These results can be seen in figures G.19 - G.36 of Appendix G.

It must be mentioned that, in second comparison procedure, because tide gauges have monthly time intervals, all extracted time series from daily grid are reduced to monthly time series. In order to provide synchronization between tide gauge and monthly grid

altimetry, since MSL of tide gauge data which are distributed by PSMSL was prepared in middle day of each month, therefore, for extraction of monthly grid data, the same criterion was applied. Thus, we have monthly time series with 276 data.

Another important point is that, because altimetry data started from 1993, some wavelet analysis comparison for stations of tide gauge and altimetry data are not possible. These stations are Sevastopol (1910 - 1994), Constantza (1933 - 1997), Varna (1929 - 1996) and Bourgas (1929 - 1996).

At the final step of grid altimetry data evaluation, a regional trend map of Blacksea based on grid data is prepared. This map, figure 4.17, includes trend of monthly time series for each pixel of grid data. It means that, there are time series with 276 values for 6720 pixels or points (56×120) and trend of these time series are calculated.

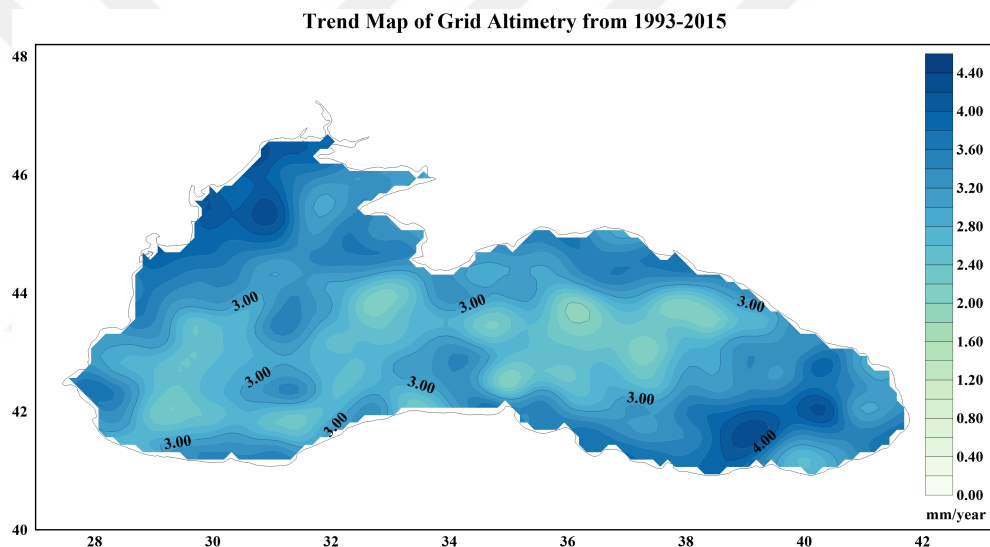


Figure 4.17 : Regional trend map extracted from grid altimetry data (mm/year)

4.2.2 Along-Track Altimetry Data

In this section, for analysis of along-track altimetry data (as it mentioned before), Topex/Poseidon, Jason-1, Jason-2 and Geosat Follow On (GFO) satellites are selected. The main reason of using different tracks is selection of nearest along-track data from the tide gauge stations. It is important to note that, during 2002-2012, there were prepared interlaced paths for Topex/Poseidon and Jason-1 that these new tracks are also considered in this study.

Figure 4.18 shows the T/P, J1, J2, GFO and T/P-J1 interlaced tracks pass through the Blacksea.

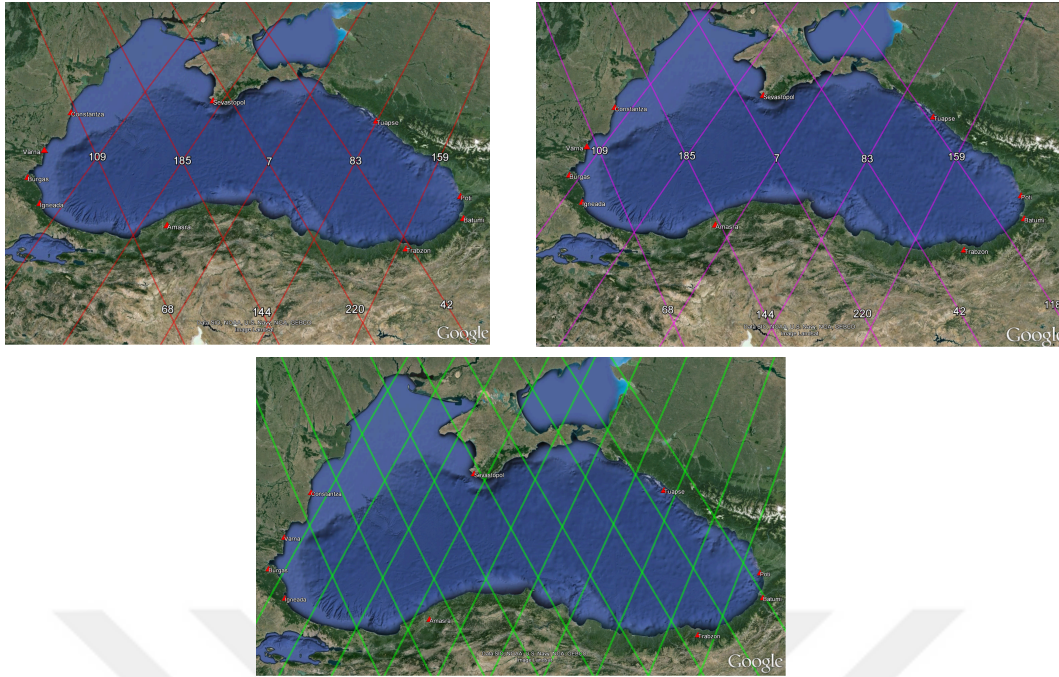


Figure 4.18 : Along-Tracks of T/P, J1 and J2 (top left), T/P, J1 interlaced (top right) and GFO (bottom)

Some statistical specification of tracks are shown in table 4.11

Table 4.11 : Statistical specifications of along-track altimetry data

	Time span	Number of NetCDF file	Number of Records	Number of Paths
T/P	1992-2002	2803	170571	9
J1	2002-2008	1909	126225	9
J2	2008-2015	2057	137396	9
GFO	2000-2008	1791	112054	19
T/P Interlaced	2002-2005	875	51157	10
J1 Interlaced	2009-2012	952	64727	10
Paths' Numbers				
T/P-J1-J2	7-42-68-83-109-144-159-185-220			
GFO	14-25-72-83-100-111-158-169-186-244-255-330 341-388-399-416-427-474-485			

Also, figure 4.19 shows the differences between these tracks based on tide gauge station's adjacency.

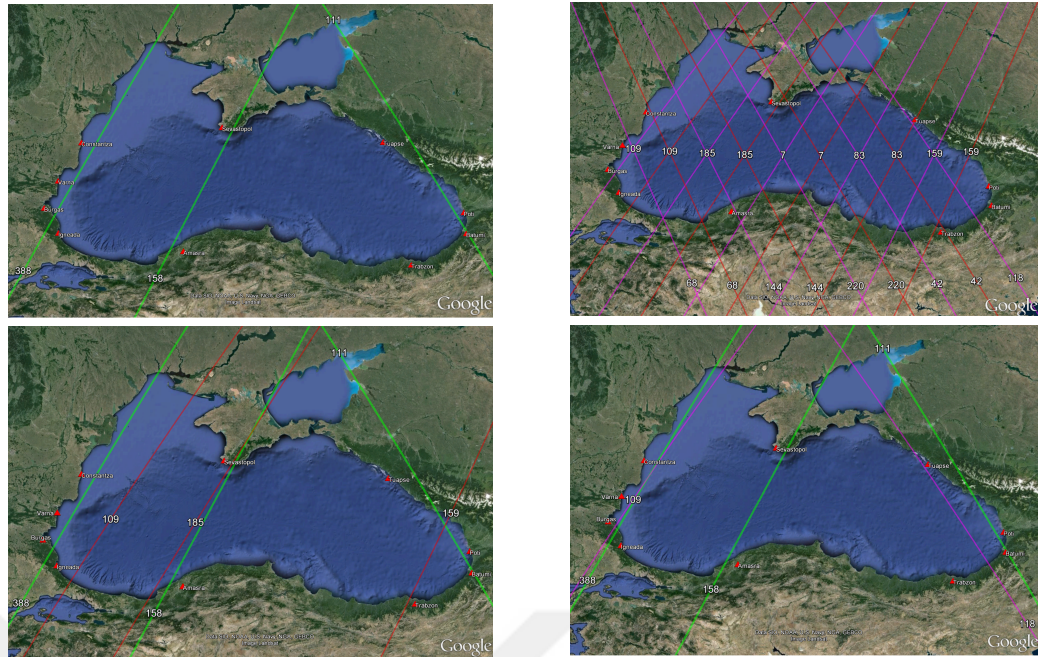


Figure 4.19 : Required tracks of GFO (top left), differences between tracks of T/P-J1-J2 and T/P-J1 interlaced (top right), T/P-J1-J2 and GFO (bottom left) and T/P-J1 interlaced and GFO (bottom right)

According to figures 4.18 and 4.19, for each tide gauge stations, following tracks are selected (table 4.12);

Table 4.12 : Selected tracks for each tide gauge station

	T/P-J1-J2	GFO	T/P-J1 interlaced
Igneada	109	388	-
Amasra	-	158	144
Trabzon	42-159	-	-
Batumi	-	111	-
Poti	-	111	-
Tuapse	83	-	-
Sevastopol	185	-	-
Constantza	68	-	-
Varna	-	388	109
Burgas	-	388	109

Distribution of along-track data of these missions from start to end point of each path are represented in Appendix H, figures H.1 - H.30. The first and second figures of each station in Appendix H was prepared based on Latitude-SLA, Longitude-SLA and Longitude-Latitude parameters.

As can be seen in these figures, in each latitude and longitude, we faced with a time series. In other words, there are three dimension data for each point, latitude, longitude

and time. Therefore, time series of each point of tracks must be extracted.

In order to select required track point, the minimum distance from stations is considered. This strategy is also applied for stations which have two tracks from their sides (Igneaada, Amasra, Trabzon, Varna and Bourgas) (table 4.12). Finally, time series of these nearest points of each along-tracks are prepared, too. These results are shown in the third figures of each station in Appendix H and table 4.13.

Table 4.13 : Extracted and selected time series of nearest track's point of tide gauge from along-track

	Tracks	Valid data	Time span
Igneaada	109	612	1992-2015
	388	40	2000-2008
Amasra	158	157	2000-2012
	144	105	2002-2012
Trabzon	42	184	1992-2015
	159	369	1992-2015
Batumi	111	7	2001-2008
Poti	111	71	2000-2008
Tuapse	83	172	1992-2015
Sevastopol	185	773	1992-2015
Constantza	68	448	1992-2015
	388	184	2002-2012
Varna	109	102	2000-2008
	388	73	2002-2012
Burgas	109	83	2000-2008

In this table, Based on obtained statistical results, selected points and their time series are shown with red colors.

For these time series, because of the large number of gaps and lack of appropriate time frame, only Least Square Spectral analysis are applied. In Appendix I, evaluation results of selected time series with amplitude and phase of semiannual and annual periods of tidal constituents are shown (figures and tables I.1 - I.9). It must be mentioned that, due to obtain the amplitude and phase of constituents, the semiannual and annual periods are forced into LSSA program while these periods are not significant.

The results of amplitude-phase map of semiannual and annual tidal constituents are shown in figures 4.20 and 4.21

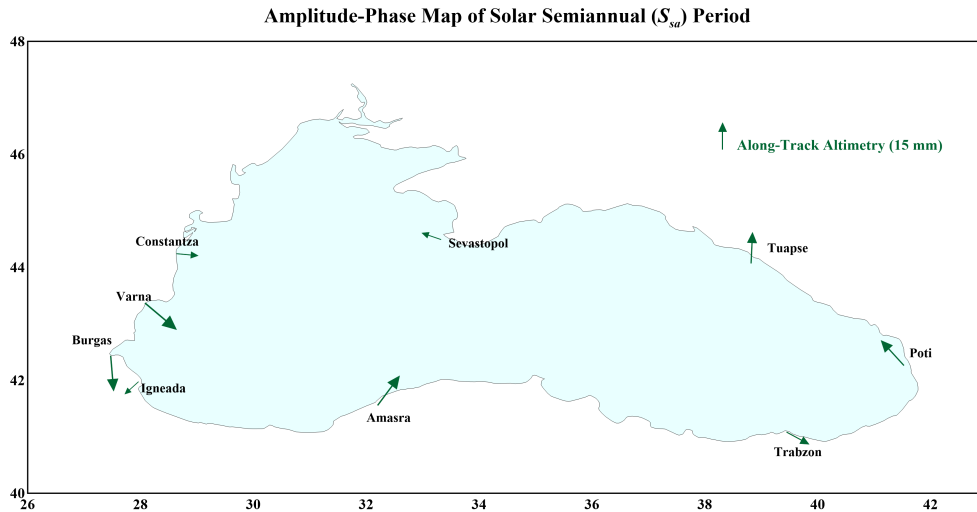


Figure 4.20 : Amplitude and phase map of Solar Semiannual (S_{sa}) periods, extracted from along-track data

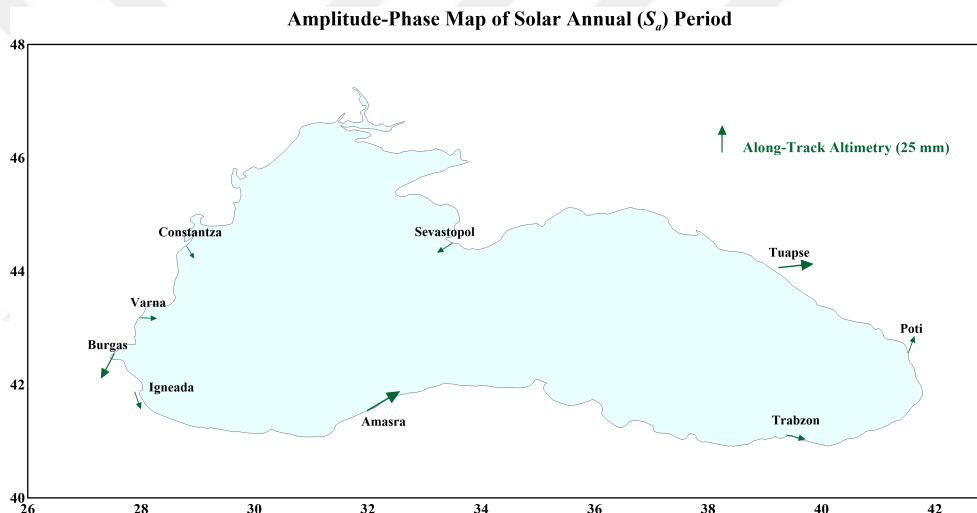


Figure 4.21 : Amplitude and phase map of Solar Annual (S_a) periods, extracted from along-track data

Since the obtained trend of stations are not significant, the trend map is not created. These trend are; Igneada: 2.274 ± 0.67 mm/year, Amasra: 5.074 ± 9.72 mm/year, Trabzon: 1.916 ± 1.49 mm/year, Poti: 10.29 ± 10.29 mm/year, Tuapse: 13.39 ± 5.29 mm/year, Sevastopol: 3.636 ± 0.51 mm/year, Constantza: 4.212 ± 1.28 mm/year, Varna: 9.504 ± 7.88 mm/year and Burgas: 22.68 ± 13.36 mm/year.

Finally, a map of mean sea level anomaly from along-track data is provided. To form this map, mean value for time series of each point through tracks are calculated. The following figure shows this result (figure 4.22).

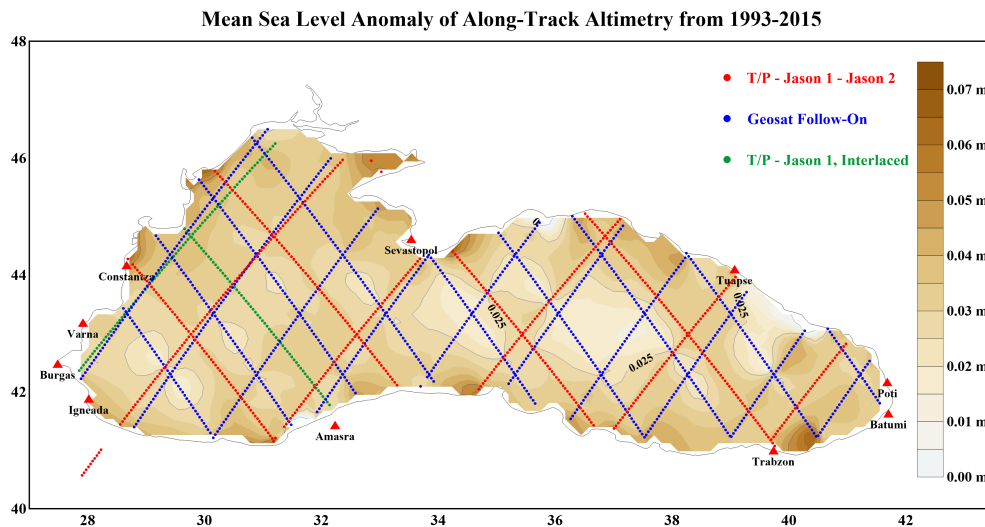


Figure 4.22 : Mean Sea Level Anomaly, extracted from along-track data

4.3 Vertical Land Motion Determination

In this section, Vertical Land Motion (VLM) are calculated based on difference between altimetry and tide gauge data. In order to accuracy evaluation of obtained VLM, GPS vertical velocity data are also considered. This procedure, as it was explained in previous sections, needs time series with the same time span. Therefore, Igneada, Amasra, Trabzon, Batumi, poti and Tuapse stations are selected.

Comparing of two type data sets are significant when they are defined in the same condition. In other words, for altimetry data, tidal and atmospheric effects are considered and removed. Therefore, these effects must be considered in tide gauge data, too. In this study, only tidal effects are removed and atmospheric effects are not determined and considered for tide gauges. As can be seen in along-track data, these time series are not appropriate for evaluation of VLM in this study and only grid altimetry data are applied. It should be noted that, only monthly time series of grid altimetry data can be used.

Due to remove tidal effects, for each time series, semiannual and annual tidal periods are forced to LSSA algorithm and then obtained results are compared with altimetry data. These analysis are shown in Appendix J.

GPS data are received from 3 services (it was mentioned before). Unfortunately, for all tide gauge stations, GPS data are not available. In table 4.14, GPS data for some stations and other specifications are shown.

Table 4.14 : GPS stations related to tide gauges in Blacksea

Station	Data service	Station name	Distance (Km)
Igneada	CORS-TR	KARB-SARY	~50
Amasra	CORS-TR	KURU	~50
Trabzon	CORS-TR	TRBN	~2
Constantza	EUREF PM	COST	
Sevastopol	SOPAC	EVPA-CRAO	~45

After calculation of difference between altimetry and tide gauge data in same stations, their trends are determined. This trend shows the regional vertical land motions based on considered time span.





5. RESULTS

Obtained results from LSS analysis for tide gauges can be summarized in table 5.1.

Table 5.1 : Calculated periods and spectrums of semiannual and annual tidal constituents of all considered tide gauge stations

	S_a		S_{sa}	
	period(mon)	Spec.(%)	period(mon)	Spec.(%)
Igneada	12.180	18.05	-	-
Amasra	11.896	20.20	-	-
Trabzon	11.827	29.54	-	-
Batumi	11.976	17.64	6.000	3.82
Poti	11.998	30.96	6.000	4.58
Tuapse	11.993	25.34	6.000	7.12
Sevastopol	11.993	28.74	6.000	4.55
Constantza	11.987	20.38	6.000	1.65
Varna	11.976	23.48	6.000	2.22
Bourgas	11.981	23.97	6.000	1.85
Actual values	12.001 month		6.000 month	

Accordinging these results, two questions can be asked;

1. Why there is no semiannual constituent (S_{sa}) for Igneada, Amasra and Trabzon?
2. Why LSSA can compute the period of semiannual constituent (S_{sa}), exactly but annual constituent (S_a) is not exactly the same with actual value?

In order to answer the first question, it must be mentioned to the spectral values of semiannual constituent. Based on definition of the confidence level in LSSA (section 3.3), confidence level mainly related to the degree of freedom value that it is also related to the number of data in time series (table 5.2). As can be seen in this table, in short time series this value is large. Therefore because spectral values of semiannual constituent are small (according the other stations (between 1.65 to 7.12 in percent, table 5.1), in Igneada, Amasra and Trabzon the spectral value of this constituent is placed below the 99% confidence level line and then this value was eliminated.

Table 5.2 : Relation between confidence level and number of data in time series

Station	99 % confidence level	Number of data in time series
Igneada	11.9	83
Amasra	10.8	97
Trabzon	12.3	80
Batumi	0.7	1372
Poti	0.6	1584
Tuapse	0.8	1145
Sevastopol	1.0	988
Constantza	1.4	741
Varna	1.3	776
Bourgas	1.3	704

In second question, main incompatibility reasons, are selection the *size of period band* and also selection of *number of spectral values in band* in LSSA program. In most of time series, in order to extract the annual constituent, period band of 9-14 month with 1000 number of spectral values were selected (except Igneada, Amasra and Trabzon). It means that with changing the period band and number of spectral values, results must be changed. At the first examination, the period band of Sevastopol station was changed from 9-14 to 2-30 (figure 5.1 (a)). This changing extracts exact annual constituent period (12.000 month) but changes the period of semiannual constituents, too (from 6.000 to 6.007). In the next examination number of spectral values change from 1000 to 5000 (figure 5.1 (b)). In this case both periods of annual and semiannual constituents was changes.

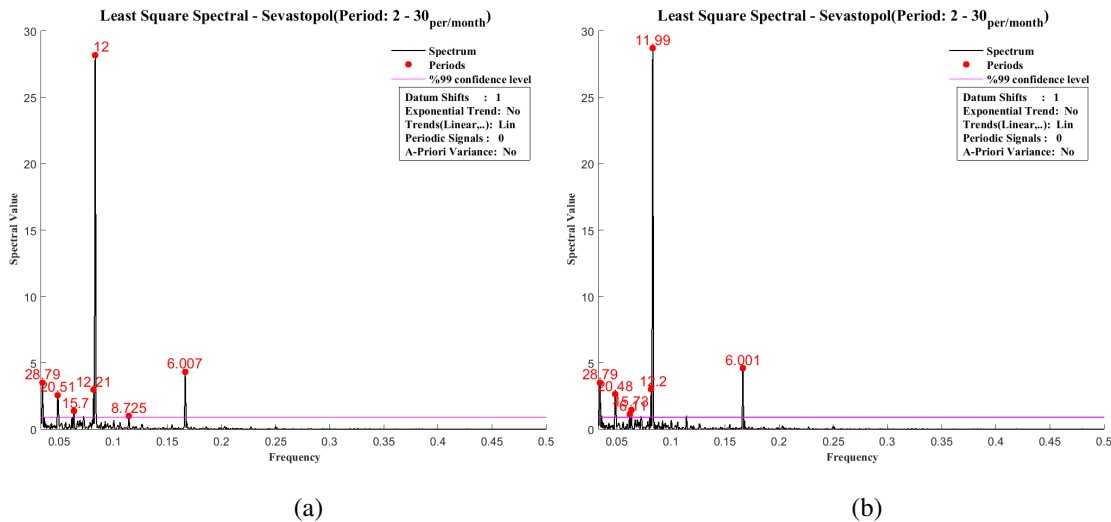


Figure 5.1 : Examples of changing spectral values using different period band (a) and different number of spectral value (b)

Extracted time series from grid altimetry data are very important criterion to evaluate the LSSA algorithm. As can be seen in table 5.3, firstly, increasing the number of observations means that obtaining more precise and convergent periods.

Table 5.3 : Calculated periods and spectrums of semiannual and annual tidal constituents of extracted time series from grid altimetry data

	S_a		S_{sa}	
	period(day)	Spec.(%)	period(day)	Spec.(%)
Igneada	364.2662	4.74	183.1347	1.64
Amasra	364.2662	5.75	182.5491	4.37
Trabzon	364.2662	5.65	182.5491	5.34
Batumi	364.2662	8.59	182.5491	4.78
Poti	364.2662	6.57	182.5491	4.49
Tuapse	364.2662	12.38	182.5491	2.67
Sevastopol	364.2662	9.49	182.5491	2.91
Constantza	364.2662	5.32	183.7241	1.75
Varna	364.2662	5.30	183.1347	2.21
Bourgas	361.9565	5.38	183.1347	2.88
Actual values	365.273 day		182.620 day	

It proves that, long time series can detect low periods of tidal constituents (e.g. semiannual) (question 1). However, there is another question that, if a time series with large number of data can detect tidal periods precisely, but why these periods are not accurate? The answer of this question can be summarized on data characters and locations. Grid data means that interpolation data and these values cannot cover our considered accuracy for detection of tidal periods. On the other hand, these grid points are not exactly at the same point of tide gauge stations. Therefore, other effects can be changed the behaviour of grid point during time. Unfortunately, along-track data could not help us to evaluate the grid altimetry data.

Another discussed results are amplitude-phase of tidal periods and their trends for stations which are obtained from tide gauge, grid and along-track altimetry data. According to tables 4.2 and 4.9 and also figures 4.11, 4.12, 4.13, 4.14, 4.15 and 4.16, each types of time series represents a uniform behaviour. However, there is an incompatibility between tide gauge and grid data (because of low accuracy of along-tracks, these results cannot be evaluated). Difference between number of observations in each time series can be considered as a reason for this non-uniformly

manner. Following figures show amplitude-phase of semiannual and annual tidal periods, figure 5.2, 5.3, and trend map, figure 5.4, for all studied data sets.

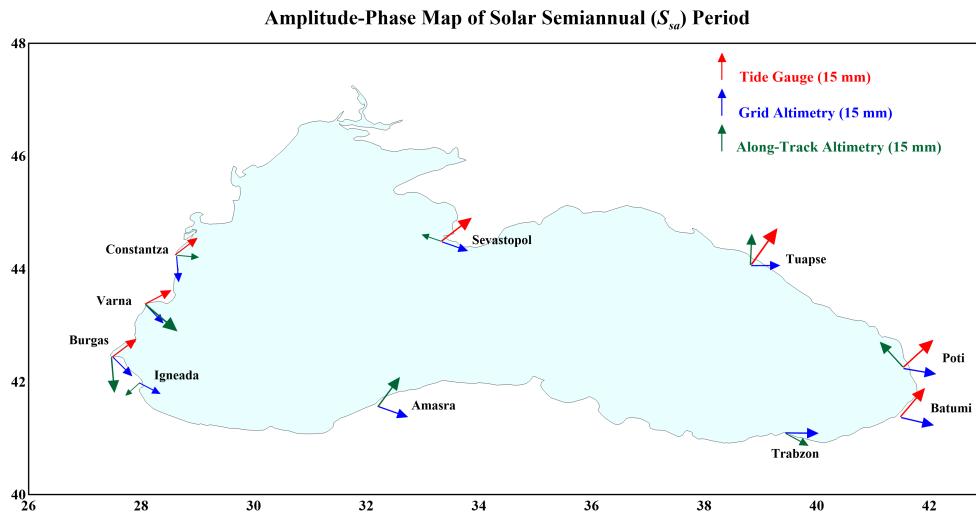


Figure 5.2 : Amplitude and phase map of Solar semiannual (S_{sa}) periods, for all data sets

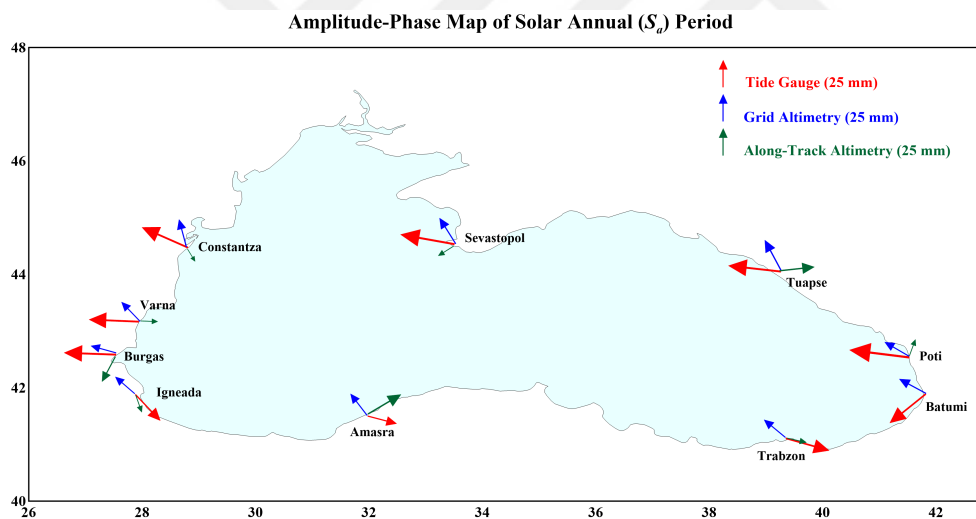


Figure 5.3 : Amplitude and phase map of Solar Annual (S_a) periods, for all data sets

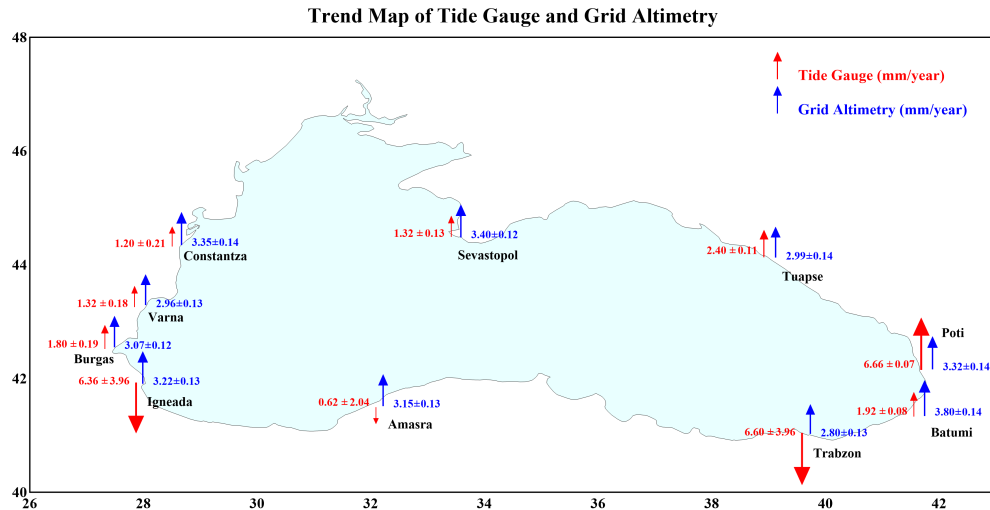


Figure 5.4 : Trend map of time series from tide gauge and grid altimetry data (mm/year)

Moreover, since the tidal periods in each station are little different, thus some disagree of direction are seen in tide gauge stations and extracted time series from grid data (figure 5.2 and 5.3). In figure 5.4, the main problem of using short time series can be seen. Trend of all tide gauge and altimetry data are positive, but Igneada, Amasra and Trabzon with short time span in tide gauge data represent the negative trend. In other words, the short time series cannot detect and observe the correct behavior of sea level. In evaluation of PCA method for tide gauge data, it seems that two reasons can affect the results after elimination of 20 points as outlier points;

1. Having data set without gaps
2. Having data set without abrupt anomalies (spikes)

In Varna, Forty gaps was filled and some of these points was detected as outliers. Result of this process provided, firstly, more powerful spectrum (2.27 and 24.25 instead of 2.22 and 23.48 for semiannual and annual constituents, respectively (table 5.4)). On the other hand, calculated annual constituent was approached to actual one (11.9812 instead of 11.9755). This assumption was completed when Batumi time series was evaluated. Batumi does not have any gaps in this time interval and also elimination of outliers was improved the power of its spectral values (5.49 and 26.22 instead of 4.86 and 25.43 for semiannual and annual constituents, respectively (table 5.4)). However, it must be mentioned that time series of Varna does not have very significant spike (figure B.6) while this event is happened in Tuapse and Batumi time series (figure B.7,

B.8). Tuapse has less number of gaps compared with Varna but it has great spikes, mostly in middle part of its time series (this condition is also seen in Batumi time series). It seems that for this reason (spikes) spectral values of semiannual and annual constituents is not improved in Tuapse.

Results of PCA for grid altimetry are more homogenously and precisely than the tide gauge data. Using very large time series without gaps is the main important reasons for obtaining this result. From table 5.4, it can be seen that, detection of 127 outliers and removing them, extract more powerful spectral values for tidal constituents compared with original data set.

These improvements approve that, by detecting and removing outliers which are defined by PCA algorithm, more powerful spectrum for each tidal periods will be obtained.

Table 5.4 : Comparison between tidal constituents before and after applying PCA for tide gauge stations and extracted grid altimetry data

TIDE GAUGE	~ Solar Semiannual (S_{sa})	Before PCA		After PCA	
		Period(mon.)	Spec.(%)	Period(mon.)	Spec.(%)
	Batumi	6.0000	4.86	6.0000	5.49
	Tuapse	6.0000	8.31	6.0000	8.13
	Varna	6.0000	2.22	6.0000	2.27
TIDE GAUGE	~ Solar Annual (S_a)	Before PCA		After PCA	
		Period(mon.)	Spec.(%)	Period(mon.)	Spec.(%)
	Batumi	11.9983	25.43	11.9926	26.22
	Tuapse	11.9869	27.32	11.9869	27.09
	Varna	11.9755	23.48	11.9812	24.25
GRID ALTIMETRY	~ Solar Semiannual (S_{sa})	Before PCA		After PCA	
		Period(day)	Spec.(%)	Period(day)	Spec.(%)
	Igneada	183.1346	1.64	183.7241	2.01
	Amasra	182.5491	4.37	182.5491	4.47
	Trabzon	182.5491	5.34	182.5491	5.40
	Batumi	182.5491	4.78	182.5491	4.79
	Poti	182.5491	4.49	182.5491	4.45
	Tuapse	182.5491	2.67	182.5491	2.78
	Sevastopol	182.5491	2.91	183.1347	2.93
	Constantza	183.7241	1.75	183.7241	1.75
	Varna	183.1347	2.21	183.1347	2.31
	Burgas	183.1347	2.88	183.1347	3.04
GRID ALTIMETRY	~ Solar Annual (S_a)	Before PCA		After PCA	
		Period(day)	Spec.(%)	Period(day)	Spec.(%)
	Igneada	364.2662	4.74	364.2662	5.01
	Amasra	364.2662	5.75	364.2662	6.03
	Trabzon	364.2662	5.65	364.2662	5.85
	Batumi	364.2662	8.59	364.2662	8.47
	Poti	364.2662	6.57	364.2662	6.64
	Tuapse	364.2662	12.38	364.2662	12.42
	Sevastopol	364.2662	9.49	364.2662	9.98
	Constantza	364.2662	5.32	364.2662	5.96
	Varna	364.2662	5.30	364.2662	5.70
	Burgas	361.9565	5.38	361.9565	5.58

Achievements of wavelet applications is also confirmed the results of LSS analysis. According to CWT and XWT procedures for tide gauge data (see figures in Appendix D), annual constituents are more significant than the semiannual constituents. Another important results is that, by comparing the obtained XWT of Sevastopol-Batumi (figure D.2), Sevastopol-Tuapse (figure D.5), Sevastopol-Varna (figure D.8) and Tuapse-Varna (figure D.14), it can be seen that, between periods of 28-32 month, there is a small

significant level. These significant levels are located between years of 1953-1960. Based on the spectral values of these periods in LSSA results, Sevastopol has period of 28.79 month with 3.51% spectral value, Tuapse has period of 32.97 month with 2.42% spectral value and other Batumi and Varna does not have any spectral value in this periods while a small significant level is represented in Batumi-Varna (figure D.17). Therefore, it can be said that, sometimes some spectral values can be detected by wavelet analysis while they are not significant in LSSA. Also according to phase relationships in XWT and WTC analysis, it shows that, all applied time series in this method have the same behaviours. This event is shown with right-side arrows which represent in-phase behaviours.

In CWT, XWT and WTC analysis for daily time series of grid data which are applied on Sevastopol, Tuapse, Batumi and Varna (same stations which are selected for wavelet analysis in tide gauge data), annual periods are more powerful than the semiannual one (i.e. compatible with the LSSA results). Also, in all of these stations, semiannual and annual tidal constituents show the same manner (in-phase) (figure G.1 - G.18) . However, when daily data are reduced to monthly data and these data are compared with tide gauges, results change, slightly (figures G.19 - G.36).

As expected, short time series do not have semiannual and annual tidal periods, accurately in wavelet analysis. However, this character is also seen in altimetry data (Igneada, Amasra and Trabzon) (figures G.19 - G.27). On the other hand, in these stations behaviours of constituents are not exactly same (not in-phase). Even, this character can be seen in the large time series such as Poti and Tuapse (figures G.31 - G.36).

Final step of this study is determination of VLM. Table 5.5 and figure 5.5 show the result of this analysis based on section 4.3 explanations.

Table 5.5 : Comparing the VLM between GPS and calculated altimetry-tide gauge data

Station	GPS vertical velocity	Altimetry - Tide Gauge
Igneada	-1.52 ± 0.48	-8.26 ± 2.88
Amasra	-1.85 ± 0.25	-4.44 ± 2.4
Trabzon	-1.25 ± 0.28	-17.4 ± 2.52
Batumi	-	14.52 ± 1.44
Poti	-	4.68 ± 1.08
Tuapse	-	1.92 ± 1.08
Constantza	5.70 ± 1.80	-
Sevastopol	-0.60 ± 0.30	-

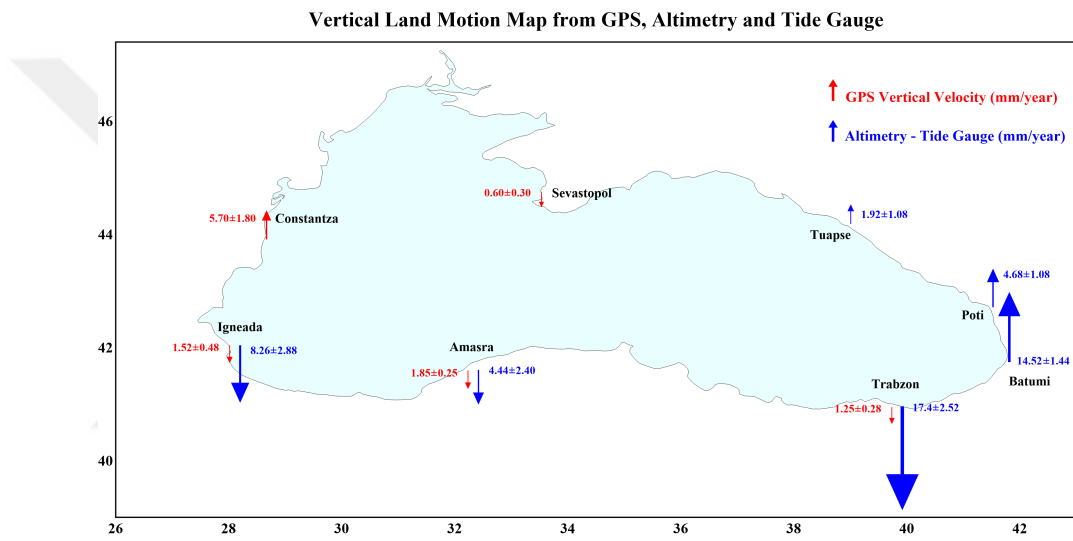


Figure 5.5 : Vertical land motion map from GPS and altimetry-tide gauge data



6. CONCLUSIONS AND RECOMMENDATIONS

In this study, Tide gauge and satellite altimetry data for Blacksea region was considered. There are 10 tide gauge stations in this area with different time series duration. Longest time series belongs to Poti with 1584 recorded data which is started from 1874 and shortest time series are Igneada and Trabzon with 80 and 83 data which are recorded from 2002. These monthly time series are received from PSMSL services. On the other hand, satellite altimetry data of the Blacksea region is also evaluated. Considered altimetry data includes Sea Level Anomaly (SLA) of 23 years grid data which are analyzed daily and monthly, separately. On the other hand, along-track data from Topex/Poseidon, Jason-1, Jason-2, GFO and Topex/Poseidon-Jason1 interlaced missions are also evaluated. These data was received from AVISO (Ssalto/Duacs) altimetry services. In order to compare behaviour of tide gauge and altimetry data, from each grid and along-track of altimetry data, time series of each stations (i.e. applied in tide gauge processing) was extracted and provided.

In order to detect tidal constituent or other significant periods, spectral analysis, such as LSSA and wavelet algorithm, was applied. The most important advantages of using LSSA instead of harmonic analysis can be summarized in one characteristics of time series which is divided to equally spaced or unequally spaced. LSSA is not sensitive to gaps (unequally spaced) while for harmonic analysing, there should not be any gaps in time series. This ability of LSSA help us to use data sets with no any modification process (i.e. filling gaps) by applying different algorithms. Besides of LSSA, wavelet method with some abilities (localization of time and changing the spectral power during time series), can extract and detect significant period or frequency of a signal or time series.

One of the other applied algorithms in this study was PCA. By transforming data series into new space with principle components and also using Hotelling's T-Square statistic, it can be detect some points which are far from the center of this new space. Based on this assumption, 20 points of selected three tide gauge stations (Tuapse,

Batumi and Varna) and 127 points of extracted time series from grid altimetry data for 10 considered stations were detected as outliers and again, this new time series was interred into LSSA and new results was compared with applied previous LSSA. It must be mentioned that, the most important effective fields of PCA algorithm is dimensional reduction. In other words, PCA can solve a problem with more variables (principle components) and it can select more powerful principle components (the first few components), therefore a problem with multi dimensional spaces is reduced into smallest one. This condition can be seen when 10 time series of altimetry data are applied.

According to the results of spectral analysis of tide gauge stations of Blacksea, it can be said that, short time series (in this study, Igneada, Amasra and Trabzon), cannot ability to show the tidal constituents with low spectral values, particularly, in case of semiannual tidal constituent. CWT and XWT are also confirmed this result. Moreover, by using wavelet method, it can be seen that, sea level changes have the same behaviours in sevastopol, Batumi, Tuapse and varna. This assertion is proved with phase relations of these stations which mostly shows the in-phase manner during the coincided time intervals.

In applied PCA algorithm, although, some improvement can be seen in results of the solar annual and semiannual periods and its spectral values of Varna and Batumi tide gauge time series after elimination of outliers, but existence of spikes and abrupt changes in this monthly time series is caused some discrepancies in final results.

Another important results in LSS analysis is that, although, LSSA is efficient in unequally spaced time series with high level noises (e.g. this study) and there is no need to smooth any spikes before analysis, but distinction between spikes an high level noises is very important because it can be distort the obtained spectrum (Hui and Pagiatakis, 2004).

Although, using grid altimetry data can provide more observation for each tide gauge stations but since these interpolated data are not exactly located at the same point, some represented behaviours of these two type data sets are different. However, some obtained results from grid data are very valuable. Representing the same semiannual and annual tidal periods with mostly same spectral values is one of them. Another important result can be seen in obtained more powerful spectral values for tidal periods

after applying PCA algorithm.

In this study, it is tried to use along-track data as a touchstone to fill the gaps of grid drawback. However, lack of precise cover of this data provides another problems. Because these data have some errors in coastal regions, original data do not have very useful information. This condition can be seen in Batumi station. This station has 131 years tide gauge data while there are only 7 observation in nearest point of considered track. Therefore using coastal processing along-track data will be more appropriate.

Finally, in case of VLM evaluation, in order to obtain more accurate results, atmospheric corrections must be applied on tide gauge data. These information and corrections for Turkish coasts' tide gauges can be obtained from TUDES.





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APPENDICES

APPENDIX A : Results of Least Square Spectral Analysis for Tide Gauge Stations

APPENDIX B : Result of Principle Component Analysis for Tide Gauge Stations

APPENDIX C : LSSA after Removing Outliers by PCA for Tide Gauge Stations

APPENDIX D : Results from Wavelet Analysis for Tide Gauge Stations

APPENDIX E : Results of Least Square Spectral Analysis for Grid Altimetry

APPENDIX F : Result of Principle Component Analysis for Grid Altimetry

APPENDIX G : Results from Wavelet Analysis for Grid Altimetry

APPENDIX H : Results of Along-Track Analysis

APPENDIX I : Result of Principle Component Analysis for Along-Track data

APPENDIX J : Result of Vertical Land Motion Analysis



APPENDIX A

• IGNEADA

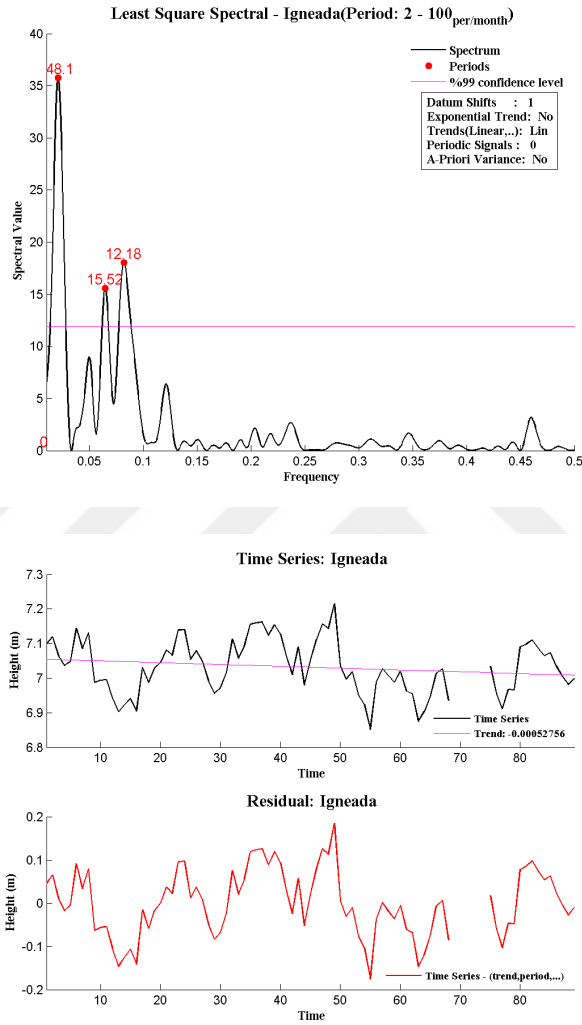


Figure A.1 : Spectrum (top) and residual (bottom) figures of Igneada time series

Table A.1 : Amplitude and phase of linear trend and detected constituents with their accuracies for Igneada

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		-0.00053	0.000331			
Cons_1	48.0982	0.062668	0.008006	290.5348	0.4606	35.77
Cons_2	15.5172	0.036591	0.007725	116.8915	0.4434	15.59
$\simeq S_a^{-1}$	12.1800	0.042199	0.007749	313.6098	0.4388	18.05

¹Solar annual

• AMASRA

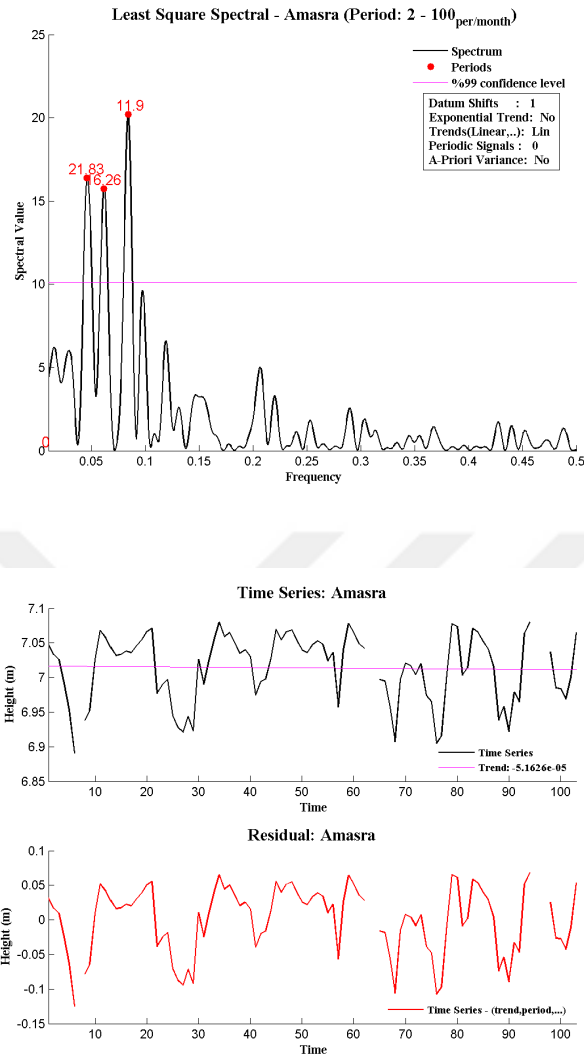


Figure A.2 : Spectrum (top) and residual (bottom) figures of Amasra time series

Table A.2 : Amplitude and phase of linear trend and detected constituents with their accuracies for Amasra

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		-5.2E-05	0.00017			
Cons_1	21.8313	0.02266	0.00528	265.581	0.311	16.38
Cons_2	16.2598	0.02308	0.00535	12.487	0.308	15.72
$\simeq S_a^1$	11.8957	0.03081	0.00528	345.368	0.299	20.20

¹Solar annual

• TRABZON

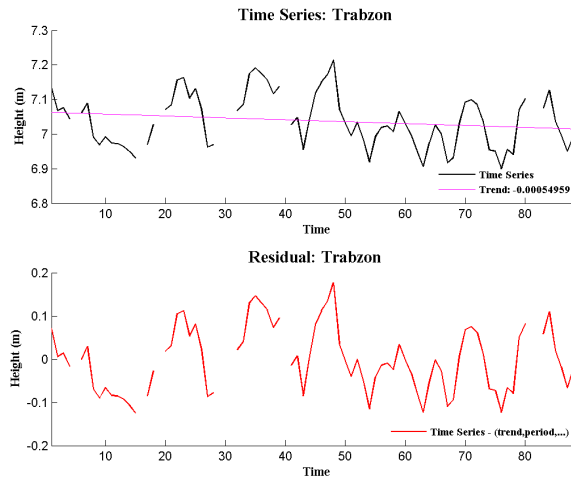
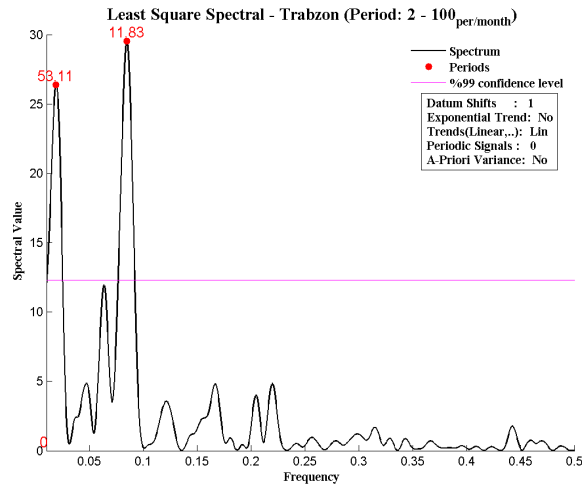


Figure A.3 : Spectrum (top) and residual (bottom) figures of Trabzon time series

Table A.3 : Amplitude and phase of linear trend and detected constituents with their accuracies for Trabzon

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		-0.00055	0.00033			
Cons_1	53.1100	0.055402	0.008511	261.4741	0.4895	26.37
$\simeq S_a^{-1}$	11.8267	0.058537	0.008481	344.2733	0.4613	29.54

¹Solar annual

• **BATUMI**

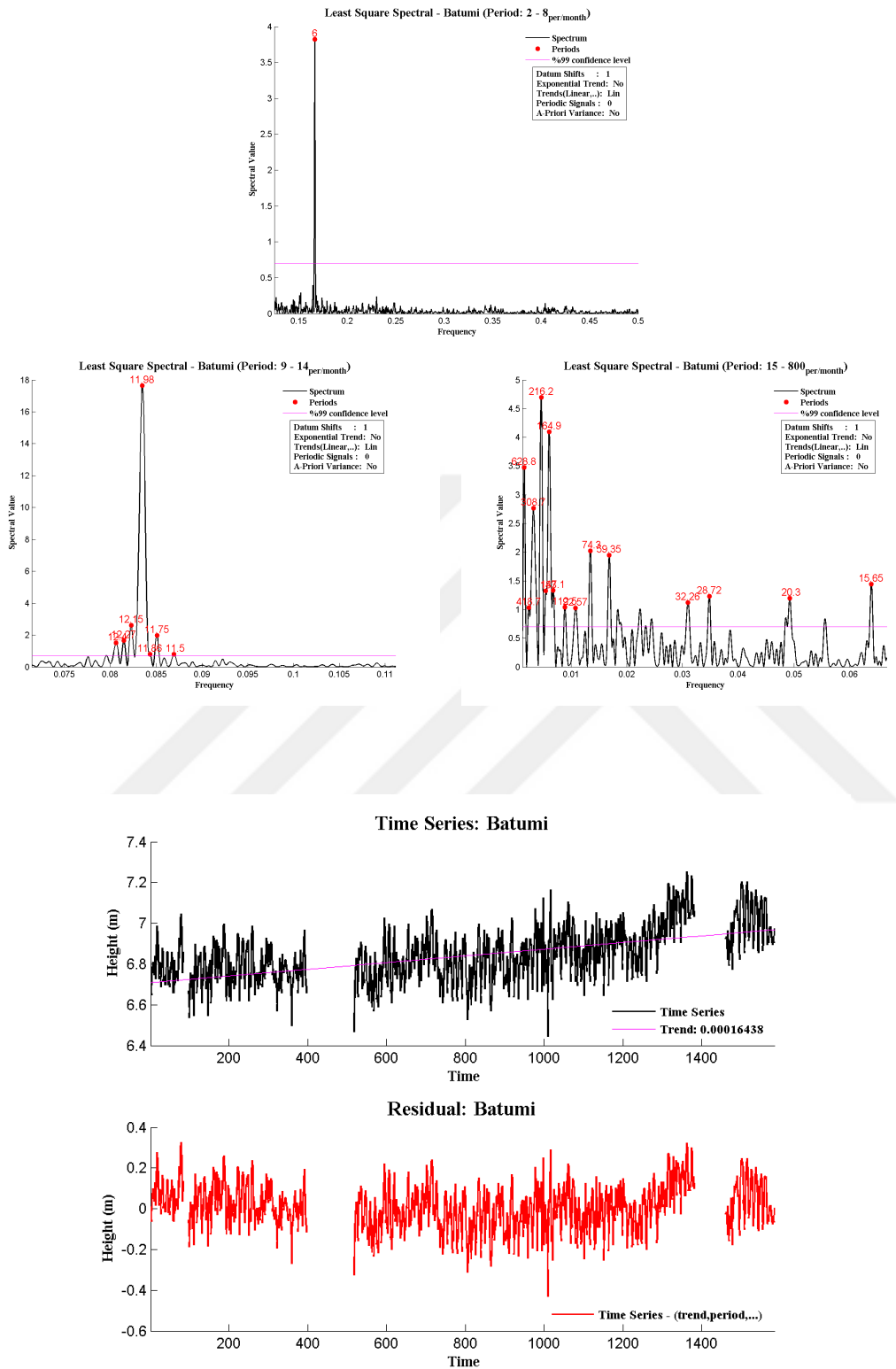


Figure A.4 : Spectrum (top) and residual (bottom) figures of Batumi time series

Table A.4 : Amplitude and phase of linear trend and detected constituents with their accuracies for Batumi

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		0.000164	6.6E-06			
$\simeq S_{sa}^1$	6.0000	0.03032	0.00325	49.538	0.186	3.82
Cons_1	12.4002	0.01382	0.00335	352.055	0.192	1.51
Cons_2	12.2732	0.01014	0.00337	76.379	0.194	1.66
Cons_3	12.1547	0.01728	0.00335	147.686	0.192	2.61
$\simeq S_a^2$	11.9755	0.06046	0.00333	218.840	0.192	17.64
Cons_4	11.7518	0.01236	0.00331	266.756	0.190	1.98
Cons_5	628.8380	0.02527	0.00389	77.762	0.179	3.48
Cons_6	308.7311	0.02467	0.00334	99.855	0.198	2.77
Cons_7	216.1613	0.02791	0.00340	55.845	0.196	4.70
Cons_8	164.8633	0.02835	0.00331	63.127	0.191	4.10
Cons_9	74.2987	0.02224	0.00329	77.017	0.189	2.03
Cons_10	59.3526	0.02140	0.00329	31.541	0.189	1.95

¹Solar semiannual

²Solar annual

• *POTI*

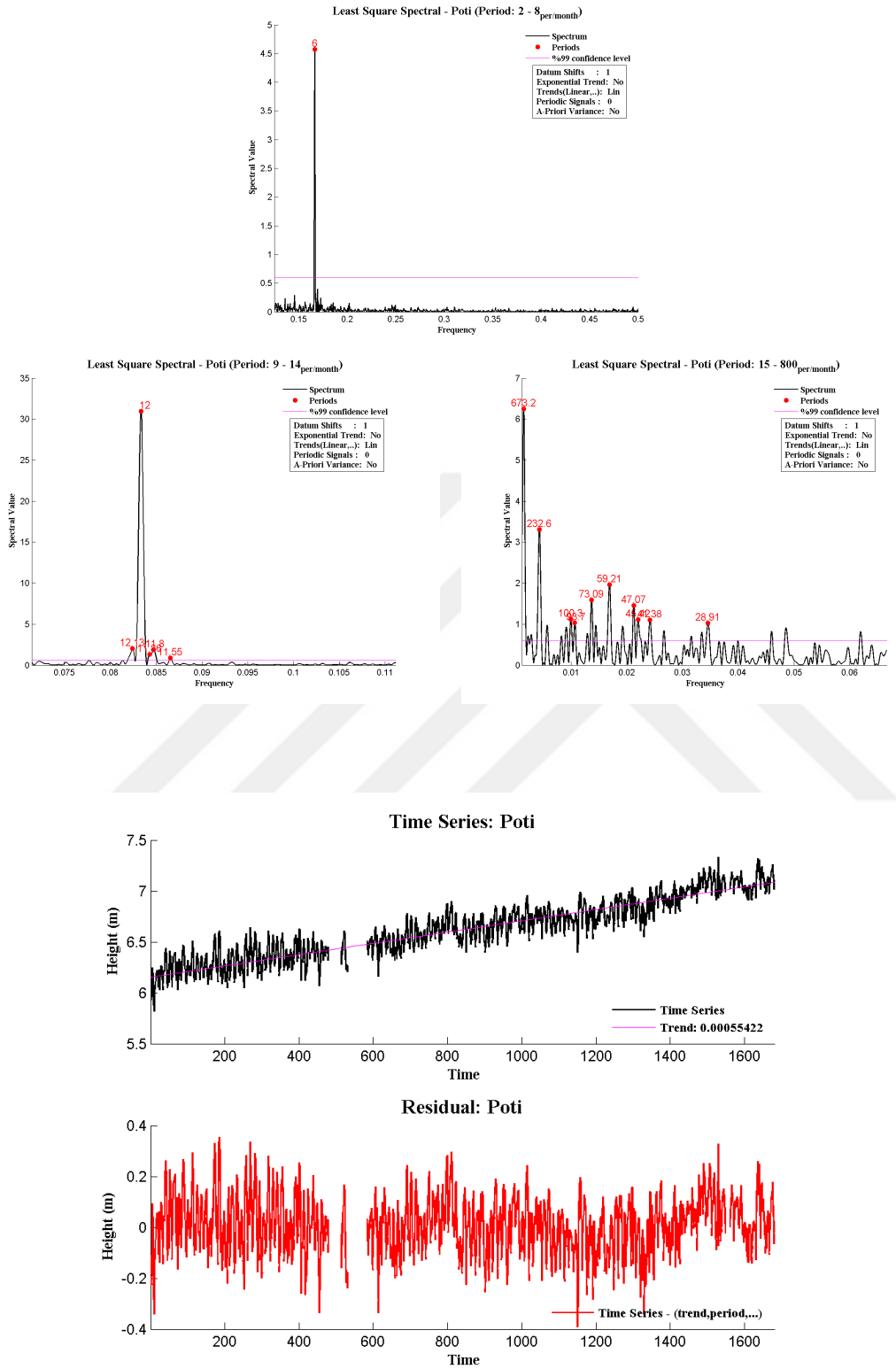


Figure A.5 : Spectrum (top) and residual (bottom) figures of Poti time series

Table A.5 : Amplitude and phase of linear trend and detected constituents with their accuracies for Poti

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		0.000554	5.74E-06			
$\simeq S_{sa}^1$	6.0000	0.03385	0.00288	42.2616	0.1650	4.58
Cons_1	12.1313	0.00594	0.00295	140.7101	0.1691	2.05
$\simeq S_a^2$	11.9983	0.08637	0.00299	172.9285	0.1713	30.96
Cons_2	11.8014	0.01186	0.00293	311.9888	0.1673	1.89
Cons_3	673.1527	0.03835	0.00307	104.1430	0.1618	6.25
Cons_4	232.6108	0.02777	0.00293	135.0776	0.1635	3.31
Cons_5	73.0906	0.01610	0.00289	225.0284	0.1675	1.59
Cons_6	59.2147	0.02145	0.00291	249.8854	0.1654	1.97



¹Solar semiannual

²Solar annual

• TUAPSE

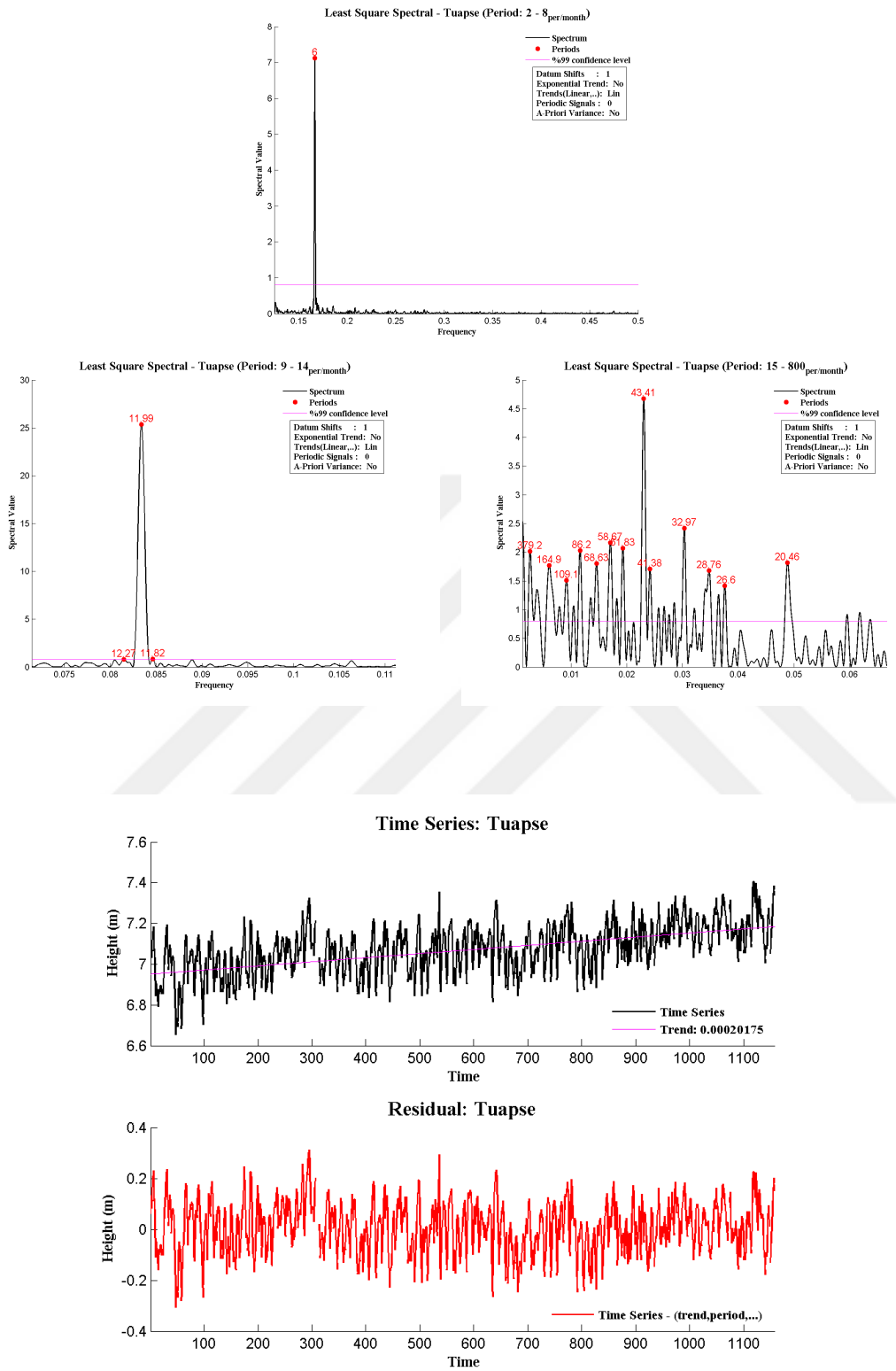


Figure A.6 : Spectrum (top) and residual (bottom) figures of Tuapse time series

Table A.6 : Amplitude and phase of linear trend and detected constituents with their accuracies for Tuapse

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		0.000202	9.01E-06			
$\simeq S_{sa}^1$	6.0000	0.038593	0.002869	54.3723	0.1644	7.12
$\simeq S_a^2$	11.9925	0.07273	0.002869	173.6663	0.1644	25.34
Cons_1	379.2028	0.021133	0.002973	251.8852	0.1659	2.01
Cons_2	164.8633	0.019156	0.002896	248.8395	0.1667	1.77
Cons_3	109.0869	0.014513	0.00293	308.8952	0.1649	1.51
Cons_4	86.1995	0.019345	0.002902	65.9152	0.1667	2.03
Cons_5	68.6271	0.017267	0.002904	129.1164	0.1658	1.80
Cons_6	58.6691	0.018868	0.00289	38.902	0.1672	2.17
Cons_7	51.8254	0.016643	0.002912	185.9543	0.1662	2.07
Cons_8	43.4063	0.027495	0.002932	267.5415	0.1682	4.68
Cons_9	41.3847	0.013129	0.002935	333.3295	0.1678	1.71
Cons_10	32.9739	0.020483	0.002869	50.149	0.165	2.42
Cons_11	28.7552	0.017763	0.002869	73.2157	0.1649	1.68

¹Solar semiannual

²Solar annual

• SEVASTOPOL

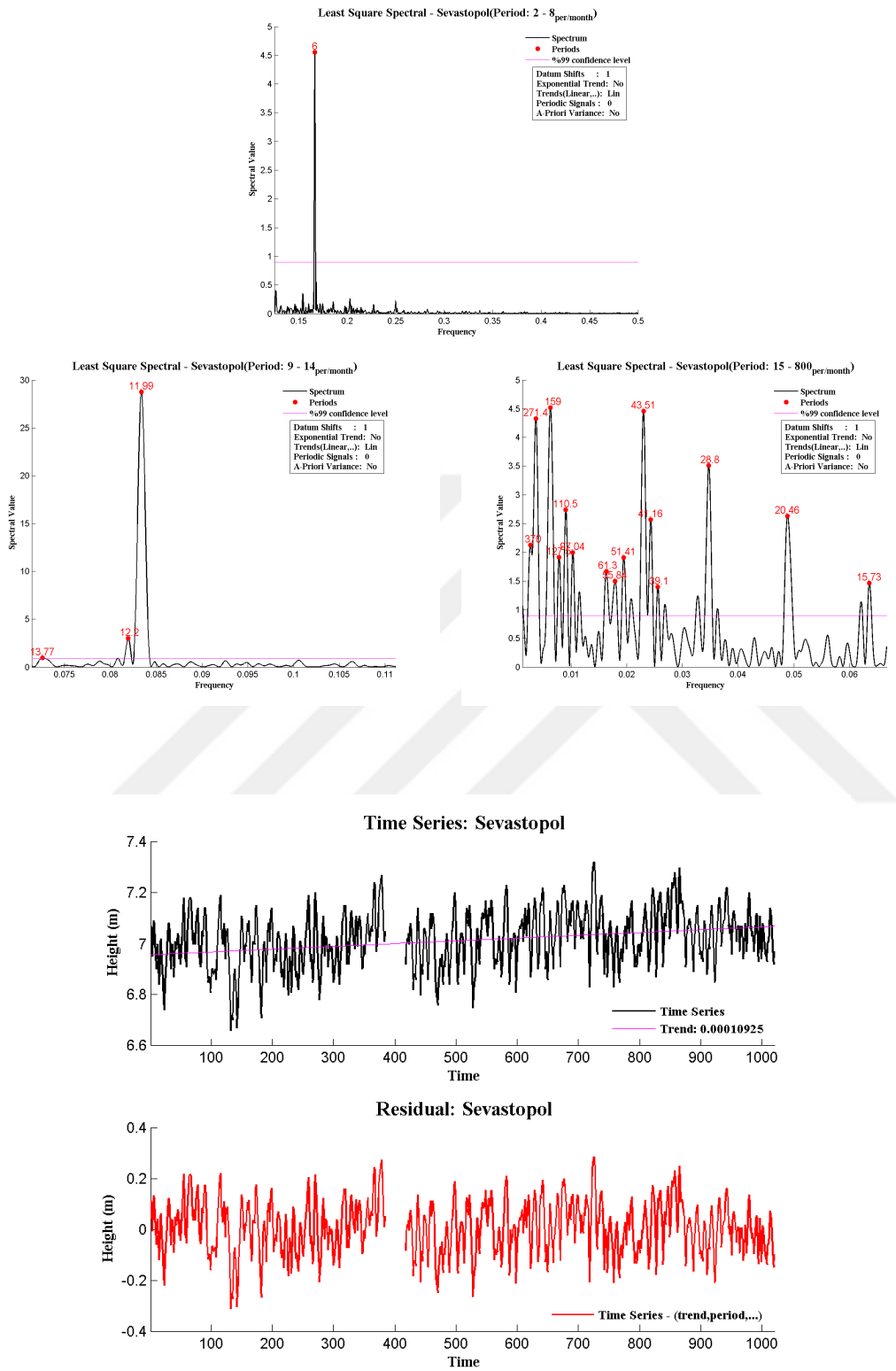


Figure A.7 : Spectrum (top) and residual (bottom) figures of Sevastopol time series

Table A.7 : Amplitude and phase of linear trend and detected constituents with their accuracies for Sevastopol

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		0.000109	1.09E-05			
$\simeq S_{sa}^1$	6.0000	0.03101	0.00278	37.7316	0.1594	4.55
Cons_1	12.2018	0.00958	0.00287	148.6005	0.1643	3.00
$\simeq S_a^2$	11.9926	0.07628	0.00286	169.8698	0.1645	28.74
Cons_2	370.0222	0.02034	0.00292	353.3494	0.1615	2.12
Cons_3	271.4451	0.02822	0.00285	108.8088	0.1674	4.33
Cons_4	159.0308	0.03049	0.00295	132.8950	0.1691	4.52
Cons_5	127.4645	0.00823	0.00297	192.2582	0.1719	1.91
Cons_6	110.5067	0.01955	0.00301	202.4430	0.1667	2.74
Cons_7	97.0358	0.01341	0.00293	278.4284	0.1684	2.00
Cons_8	61.3048	0.01900	0.00288	34.2675	0.1655	1.67
Cons_9	55.8397	0.01846	0.00297	355.3264	0.1698	1.50
Cons_10	51.4071	0.01574	0.00290	42.0349	0.1659	1.91
Cons_11	43.5052	0.02768	0.00287	231.6635	0.1660	4.46
Cons_12	41.1618	0.01897	0.00291	350.8999	0.1645	2.57
Cons_13	28.7986	0.02556	0.00279	35.5622	0.1600	3.51
Cons_14	20.4625	0.02225	0.00279	155.0157	0.1595	2.63

¹Solar semiannual

²Solar annual

• *CONSTANTZA*

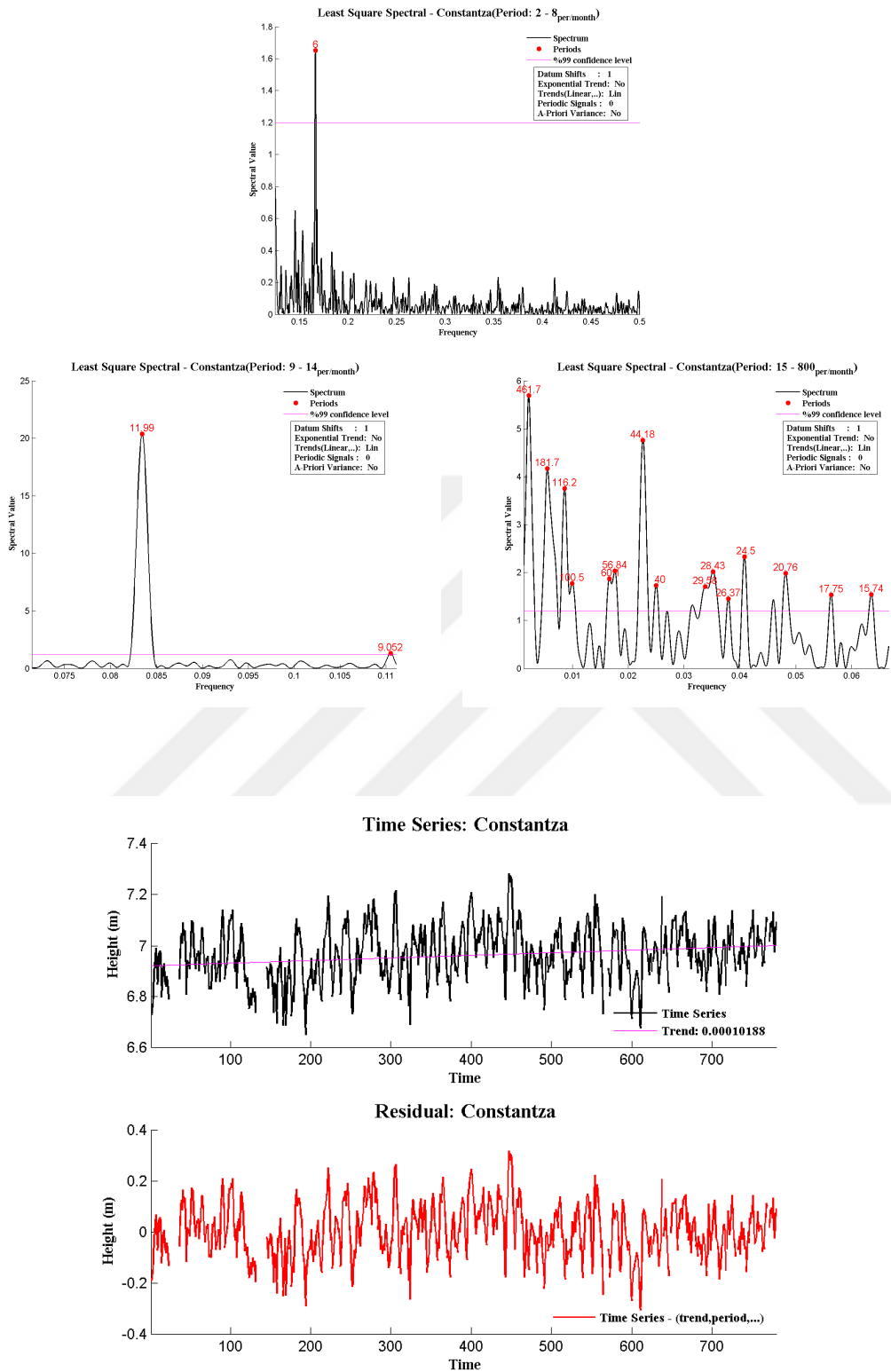


Figure A.8 : Spectrum (top) and residual (bottom) figures of Constantza time series

Table A.8 : Amplitude and phase of linear trend and detected constituents with their accuracies for Constantza

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		0.000102	1.74E-05			
$\simeq S_{sa}^1$	6.0000	0.01875	0.00362	37.3455	0.2077	1.65
$\simeq S_a^2$	11.9869	0.06802	0.00363	156.2250	0.2080	20.38
Cons_1	461.6770	0.04001	0.00393	299.1365	0.2096	5.69
Cons_2	181.7212	0.02854	0.00373	155.1190	0.2135	4.17
Cons_3	116.2209	0.02779	0.00372	257.3690	0.2085	3.76
Cons_4	100.4807	0.01251	0.00364	184.8954	0.2124	1.77
Cons_5	60.0995	0.01733	0.00385	267.0218	0.2263	1.87
Cons_6	56.8364	0.02150	0.00394	301.8090	0.2226	2.03
Cons_7	44.1844	0.02870	0.00370	70.0388	0.2084	4.76
Cons_8	39.9984	0.01754	0.00366	232.5389	0.2096	1.73
Cons_9	29.5789	0.01941	0.00364	102.7204	0.2089	1.71
Cons_10	28.4343	0.02269	0.00364	241.4047	0.2102	2.02
Cons_11	24.5045	0.02151	0.00365	213.7898	0.2090	2.33
Cons_12	20.7571	0.02152	0.00365	251.6256	0.2079	1.98
Cons_13	17.7529	0.02038	0.00365	197.6204	0.2082	1.53
Cons_14	15.7416	0.02006	0.00365	182.1502	0.2077	1.54

¹Solar semiannual

²Solar annual

• VARNA

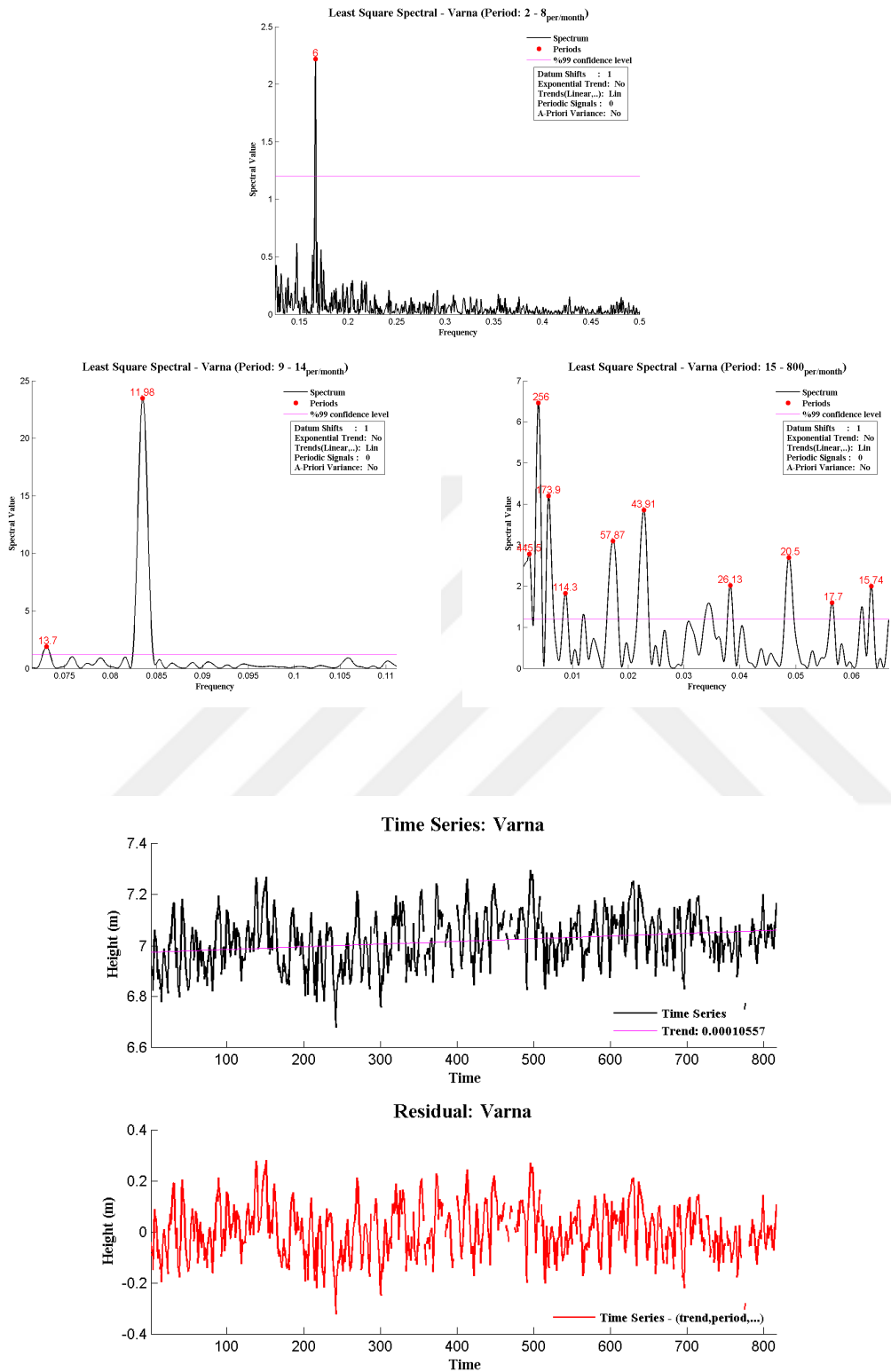


Figure A.9 : Spectrum (top) and residual (bottom) figures of Varna time series

Table A.9 : Amplitude and phase of linear trend and detected constituents with their accuracies for Varna

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		0.000106	1.52E-05			
$\simeq S_{sa}^1$	6.0000	0.02072	0.00330	27.6273	0.1881	2.22
Cons_1	13.6954	0.01774	0.00330	75.7653	0.1894	1.89
$\simeq S_a^2$	11.9755	0.06702	0.00331	177.6148	0.1885	23.48
Cons_2	445.5271	0.02525	0.00351	32.5591	0.2050	2.78
Cons_3	255.9870	0.03358	0.00347	195.1937	0.2032	6.46
Cons_4	173.8657	0.02372	0.00347	273.0071	0.1942	4.20
Cons_5	114.3086	0.02259	0.00336	105.7645	0.1888	1.83
Cons_6	57.8694	0.02443	0.00329	224.9216	0.1908	3.10
Cons_7	43.9051	0.03031	0.00330	114.7361	0.1902	3.85
Cons_8	29.0615	0.01736	0.00331	39.2050	0.1889	1.59
Cons_9	26.1300	0.02254	0.00332	82.8840	0.1880	2.02
Cons_10	20.5010	0.02313	0.00330	88.4092	0.1897	2.70
Cons_11	17.6954	0.01657	0.00332	127.1577	0.1887	1.60
Cons_12	16.1679	0.01628	0.00341	230.0754	0.1934	1.50
Cons_13	15.7383	0.01637	0.00338	231.6330	0.1948	2.00

¹Solar semiannual

²Solar annual

• BOURGAS

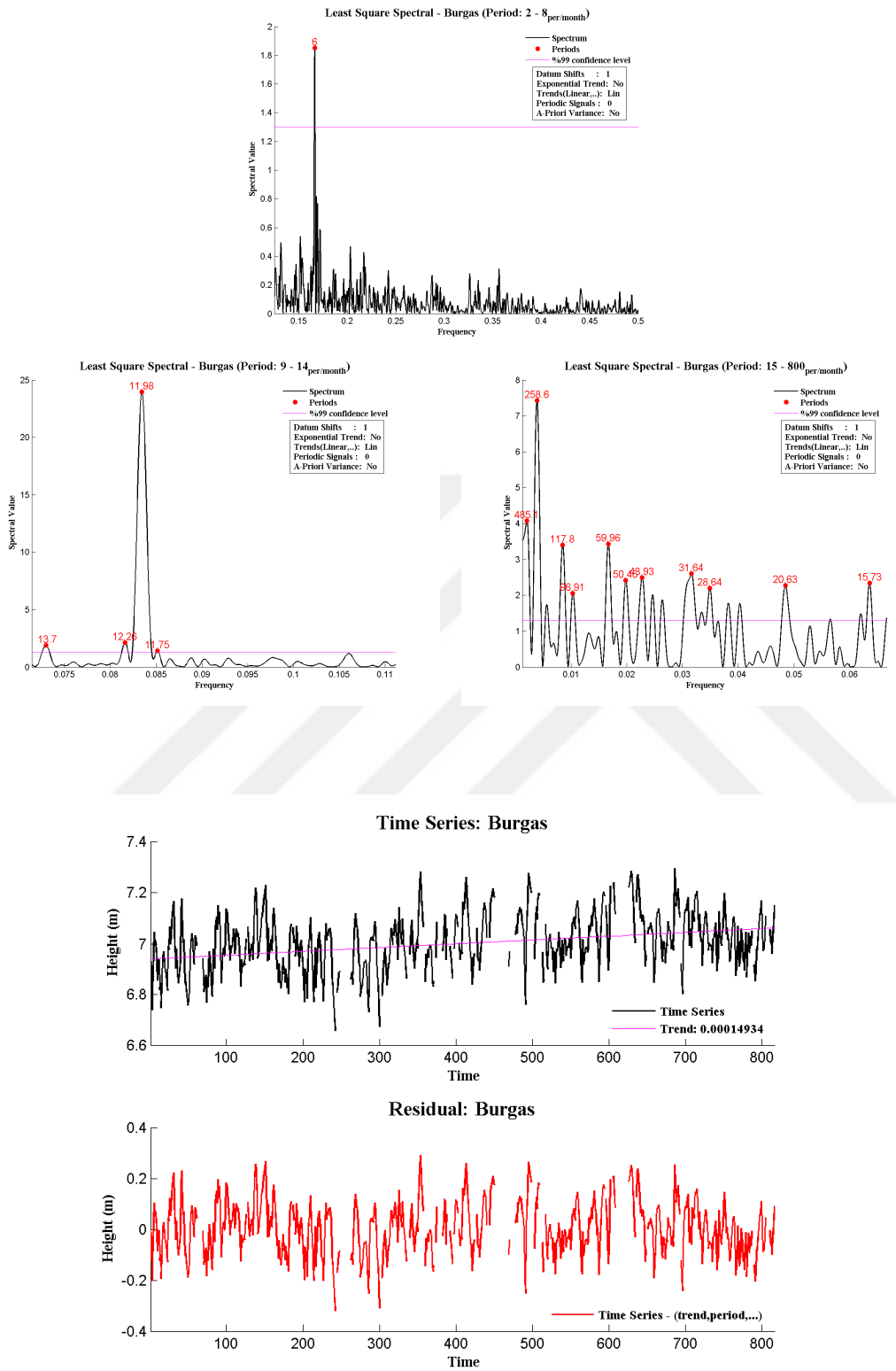


Figure A.10 : Spectrum (top) and residual (bottom) figures of Bourgas time series

Table A.10 : Amplitude and phase of linear trend and detected constituents with their accuracies for Bourgas

	Period(mon)	Amp.(m)	sigma(m)	Phase(°)	sigma(°)	Spec.(%)
Trend (m)		0.000149	1.62E-05			
$\simeq S_{sa}^1$	6.0000	0.02105	0.00338	36.7695	0.1922	1.85
Cons_1	13.7028	0.01556	0.00340	55.0458	0.1950	1.90
Cons_2	12.2553	0.00380	0.00353	160.0653	0.2016	2.13
$\simeq S_a^2$	11.9812	0.07119	0.00352	177.9432	0.2025	23.97
Cons_3	485.1239	0.03165	0.00382	14.9707	0.2316	4.08
Cons_4	258.5857	0.03721	0.00364	195.4390	0.2394	7.43
Cons_5	177.5003	0.01032	0.00368	250.4250	0.2146	1.74
Cons_6	117.8338	0.01922	0.00372	45.6473	0.2166	3.40
Cons_7	96.9127	0.01074	0.00363	143.7372	0.2209	2.06
Cons_8	59.9580	0.02581	0.00344	182.6787	0.2094	3.44
Cons_9	50.4567	0.01383	0.00348	309.7710	0.2057	2.41
Cons_10	43.9304	0.02358	0.00360	119.8643	0.2155	2.50
Cons_11	40.5933	0.01416	0.00384	237.0175	0.2225	2.02
Cons_12	37.9147	0.01210	0.00362	282.8312	0.2074	1.88
Cons_13	31.6362	0.02608	0.00358	32.2382	0.2042	2.60
Cons_14	29.9030	0.02505	0.00365	307.2894	0.2140	1.53
Cons_15	28.6368	0.02245	0.00355	83.9107	0.2071	2.20
Cons_16	26.1569	0.01716	0.00356	83.3996	0.2039	1.79
Cons_17	24.8148	0.01866	0.00353	161.2336	0.2042	1.77
Cons_18	20.6338	0.02225	0.00345	60.1841	0.1977	2.27
Cons_19	15.7286	0.02060	0.00340	206.2632	0.1954	2.34

¹Solar semiannual

²Solar annual



APPENDIX B

- *BOXPLOT*

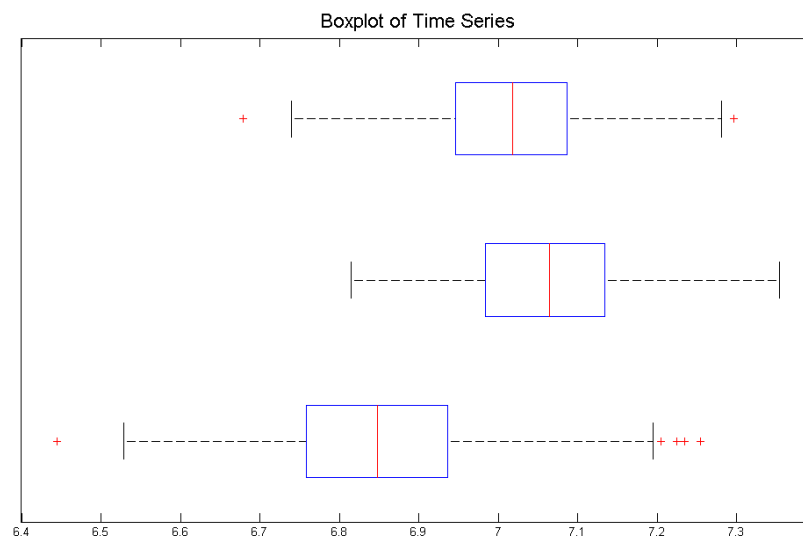


Figure B.1 : Boxplot of 3 time series, Varna(top) - Tuapse(middle) - Batumi(bottom)

On each box, the central mark is the median (red line), the edges of the box are the 25th and 75th percentiles, the whiskers extend to the most extreme data points not considered outliers, and outliers are plotted individually (+).

- *PRINCIPLE COMPONENTS*

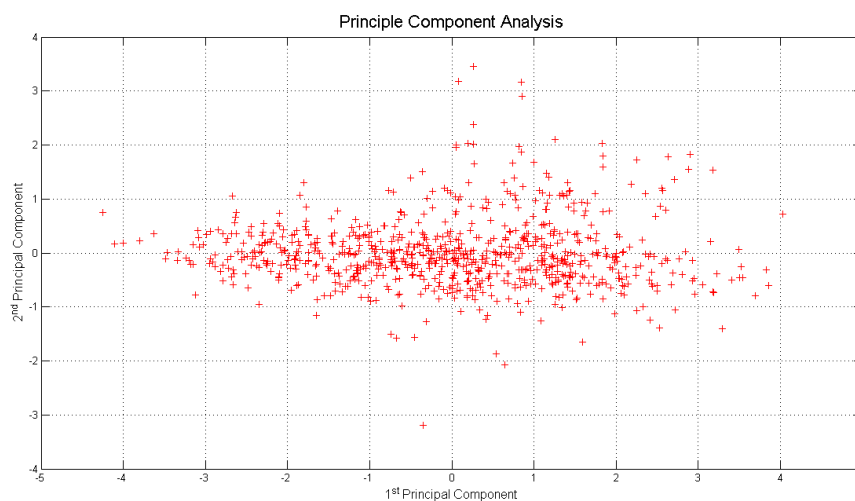


Figure B.2 : First and second principle components

- *2D PRINCIPLE COMPONENTS*

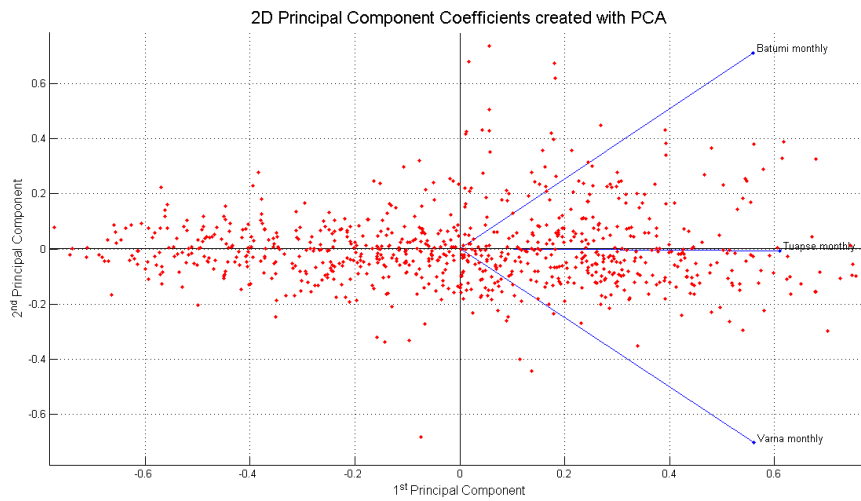


Figure B.3 : 2 dimension of first and second principle components with direction of data sets

- *3D PRINCIPLE COMPONENTS*

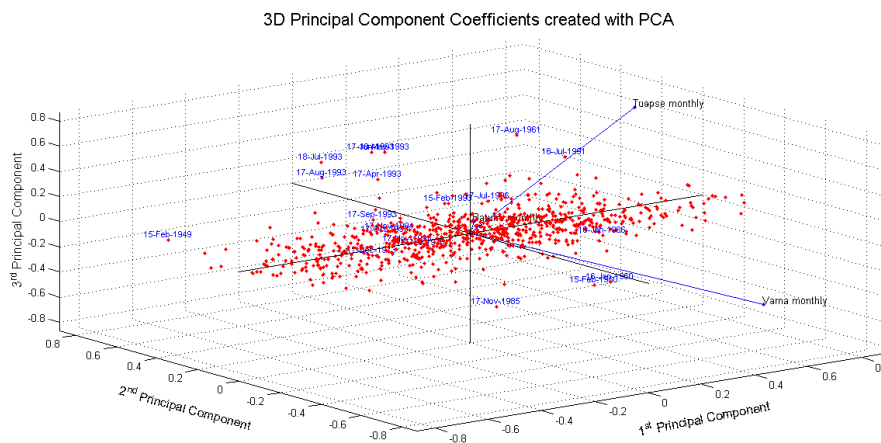


Figure B.4 : 3 dimension of first, second and third principle components with direction of data sets

In these figure, direction of each data set and its length (blue line) are shown. They show the amount of contribution of each variable and also their geometric contributions in the new space (2 dimension for two components and 3 dimension for whole).

The below figure shows distribution of data in new space based on PC.

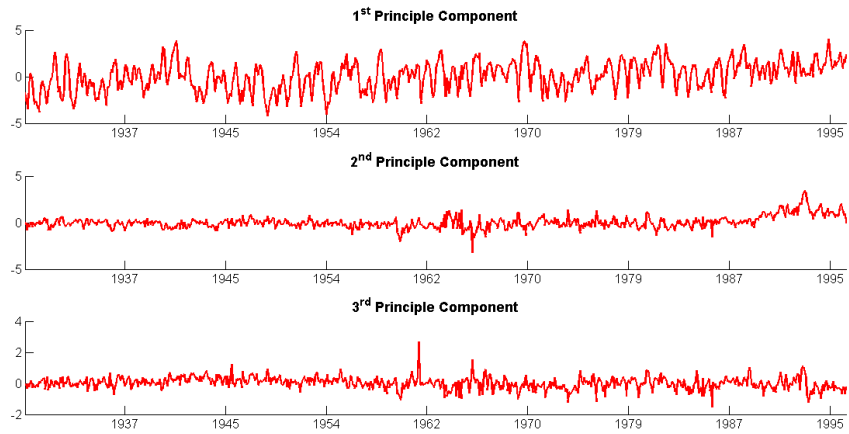


Figure B.5 : Distribution of data sets through new space by principle components



• *TIME SERIES WITH OUTLIERS*

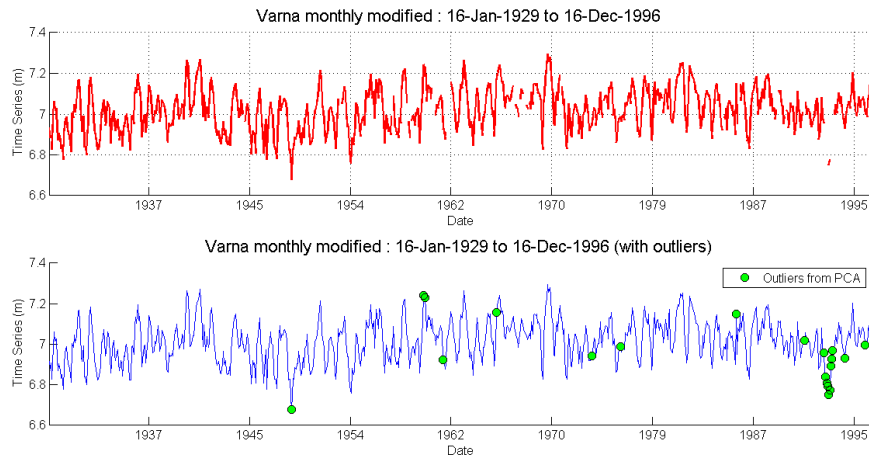


Figure B.6 : Original time series of Varna (top) with outliers (bottom) between 16-Jan-1929 and 16-Dec-1996

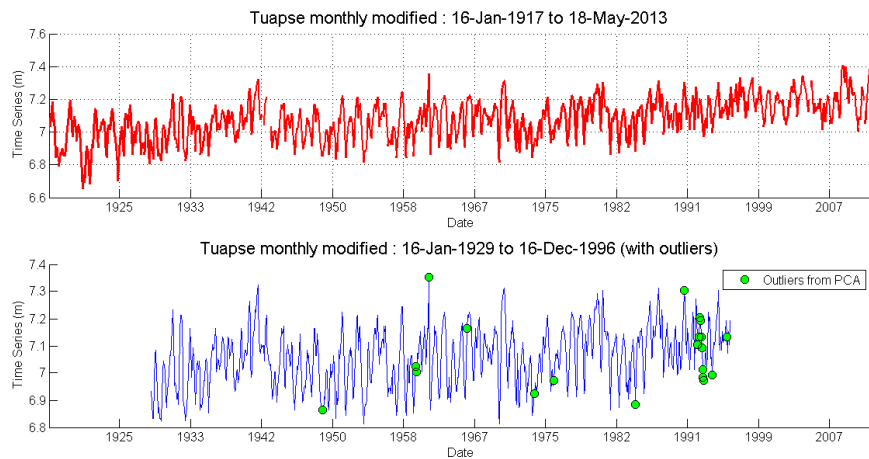


Figure B.7 : Original time series of Tuapse (top). Modified series between 16-Jan-1929 and 16-Dec-1996 with outliers (bottom)

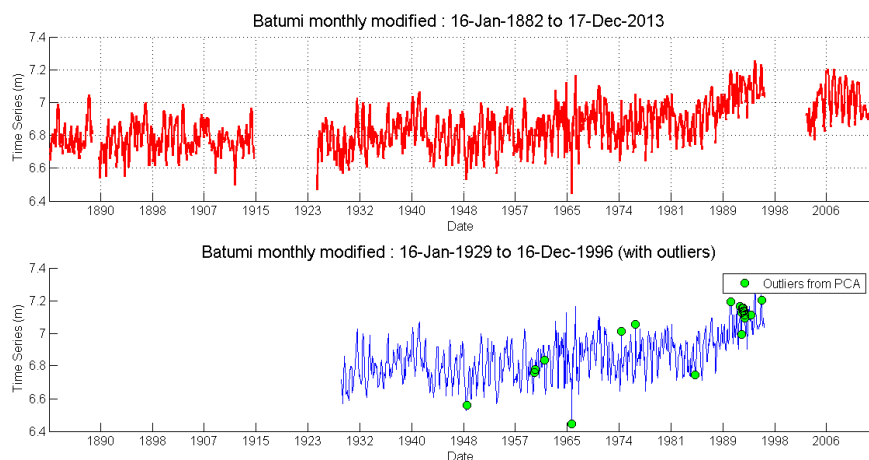


Figure B.8 : Original time series of Batumi (top). Modified series between 16-Jan-1929 and 16-Dec-1996 with outliers (bottom)

APPENDIX C

- VARNA

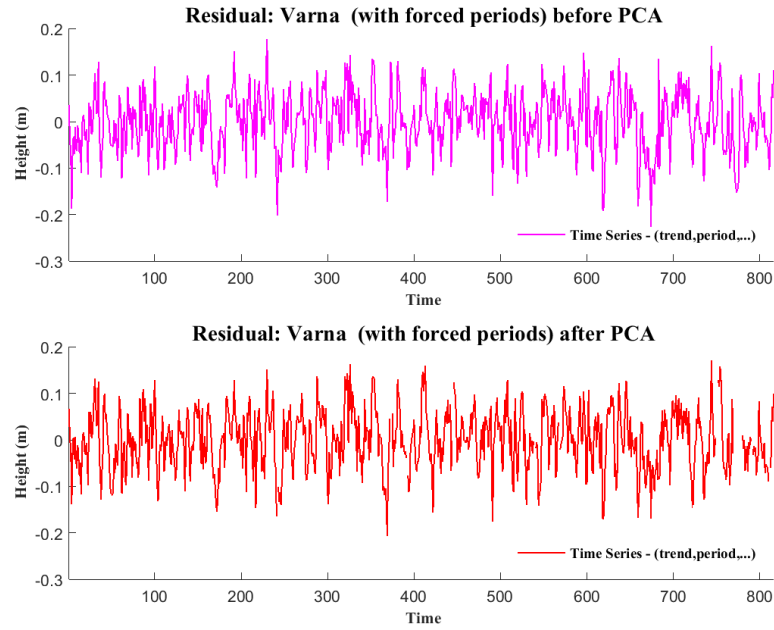


Figure C.1 : Residual graphs before (top) and after (bottom) applying PCA in Varna
Table C.1 : Comparison between tidal constituents before and after applying PCA in Varna

	Befor PCA		After PCA	
	Period(mon.)	Spec.(%)	Period(mon.)	Spec.(%)
$\simeq S_{sa}$ ¹	6.0000	2.22	6.0000	2.27
Cons_1	13.6954	1.89		
$\simeq S_a$ ²	11.9755	23.48	11.9812	24.25
Cons_2	445.5271	2.78	430.4690	2.83
Cons_3	255.9870	6.46	254.2834	5.46
Cons_4	173.8657	4.20	172.6870	4.19
Cons_5	114.3086	1.83	113.7979	1.74
Cons_6	57.8694	3.10	82.6566	1.58
Cons_7	43.9051	3.85	57.4345	2.78
Cons_8	29.0615	1.59	44.0316	3.45
Cons_9	26.1300	2.02	26.1569	1.89
Cons_10	20.5010	2.70	20.4571	2.23
Cons_11	17.6954	1.60	16.1884	1.57
Cons_12	16.1679	1.50	15.7351	1.51
Cons_13	15.7383	2.00		

¹Solar semiannual

²Solar annual

• TUAPSE

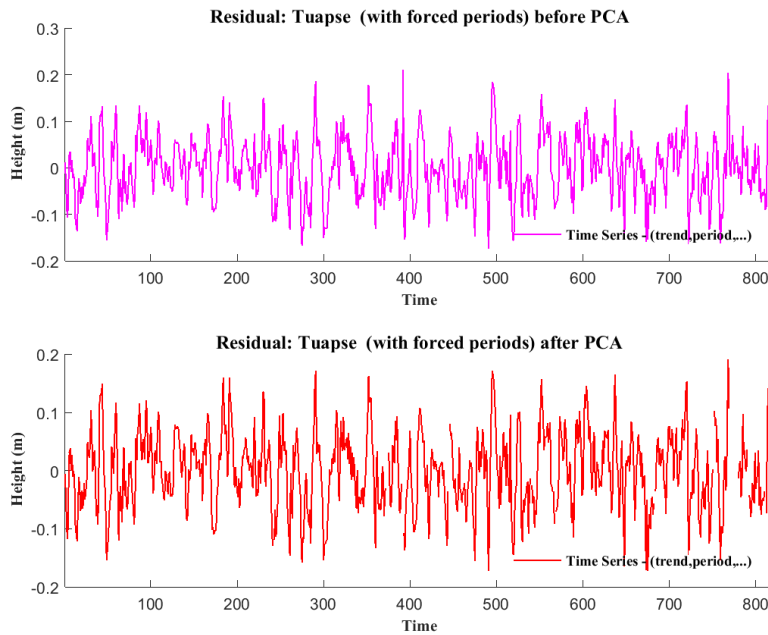


Figure C.2 : Residual graphs before (top) and after (bottom) applying PCA in Tuapse

Table C.2 : Comparison between tidal constituents before and after applying PCA in Tuapse

	Befor PCA		After PCA	
	Period(mon.)	Spec.(%)	Period(mon.)	Spec.(%)
$\simeq S_{sa}^1$	6.0000	8.31	6.0000	8.13
$\simeq S_a^2$	11.9869	27.32	11.9869	27.09
Cons_1	294.4558	3.14	296.7426	2.93
Cons_2	158.3716	4.61	159.0308	4.71
Cons_3	112.4582	2.11	112.1282	2.03
Cons_4	82.4781	2.11	82.1236	2.28
Cons_5	59.9110	3.73	59.7237	3.35
Cons_6	43.7292	2.97	43.7042	3.20
Cons_7	40.4002	2.01	40.3788	1.83
Cons_8			29.5675	1.59

¹Solar semiannual

²Solar annual

• *BATUMI*

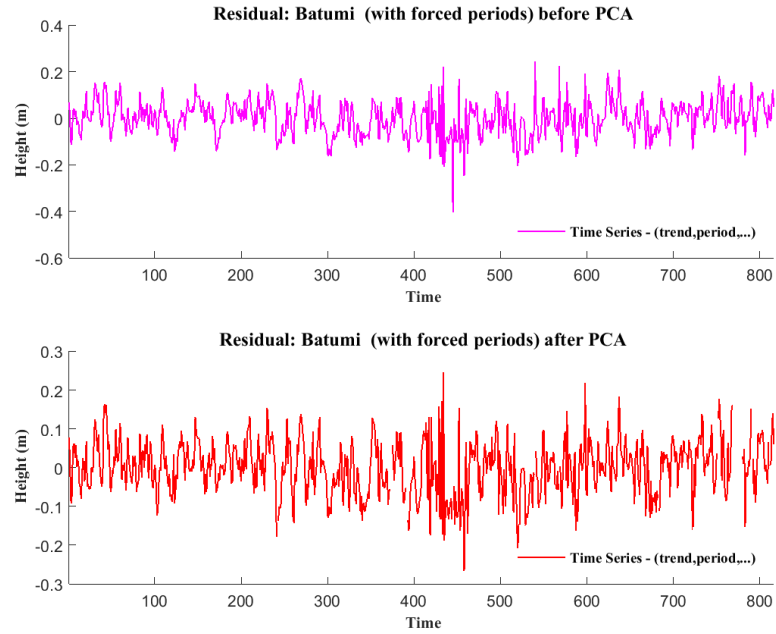


Figure C.3 : Residual graphs before (top) and after (bottom) applying PCA in Batumi

Table C.3 : Comparison between tidal constituents before and after applying PCA in Batumi

	Befor PCA		After PCA	
	Period(mon.)	Spec.(%)	Period(mon.)	Spec.(%)
$\simeq S_{sa}^1$	6.0000	4.86	6.0000	5.49
$\simeq S_a^2$	11.9983	25.43	11.9926	26.22
Cons_1	343.4165	10.68	341.8802	10.01
Cons_2	223.1032	3.60	222.4538	2.45
Cons_3	161.0416	4.77	161.7232	4.34
Cons_4	94.1660	2.22	94.8674	2.20
Cons_5	32.5942	1.95	59.2147	2.13
Cons_6	20.1019	1.87	43.4804	1.98
Cons_7	15.7092	1.78	40.2512	1.54
Cons_8			32.8605	1.79
Cons_9			26.0676	1.72
Cons_10			15.7286	2.06

¹Solar semiannual

²Solar annual



APPENDIX D

• SEVASTOPOL & BATUMI

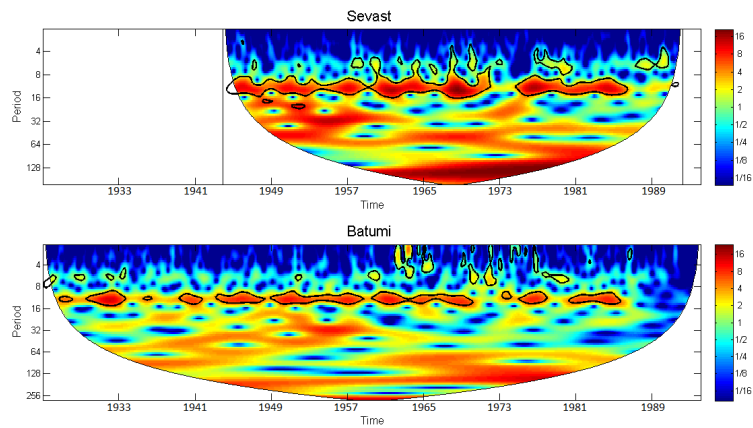


Figure D.1 : Continuous Wavelet Transform comparison between Sevastopol and Batumi

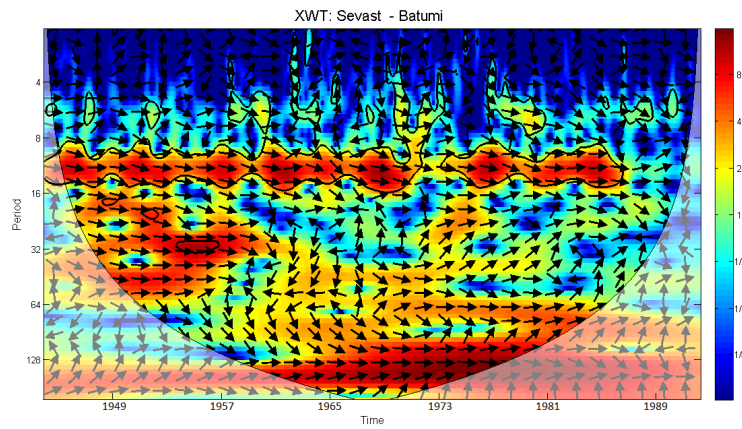


Figure D.2 : Cross Wavelet Transform of Sevastopol and Batumi

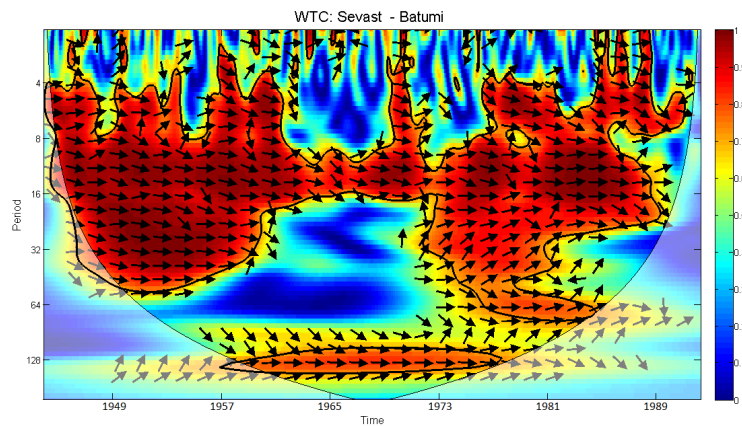


Figure D.3 : Wavelet Coherence Transform of Sevastopol and Batumi

• SEVASTOPOL & TUAPSE

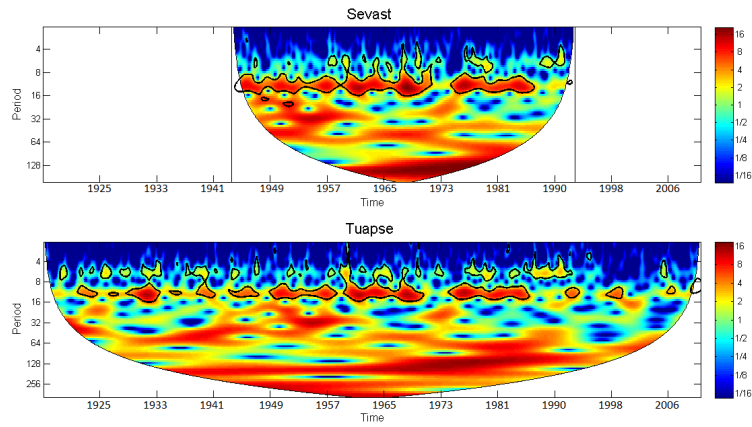


Figure D.4 : Continuous Wavelet Transform comparison between Sevastopol and Tuapse

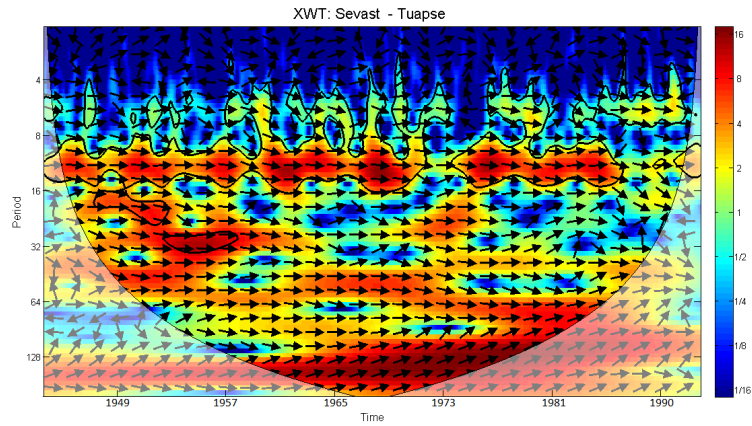


Figure D.5 : Cross Wavelet Transform of Sevastopol and Tuapse

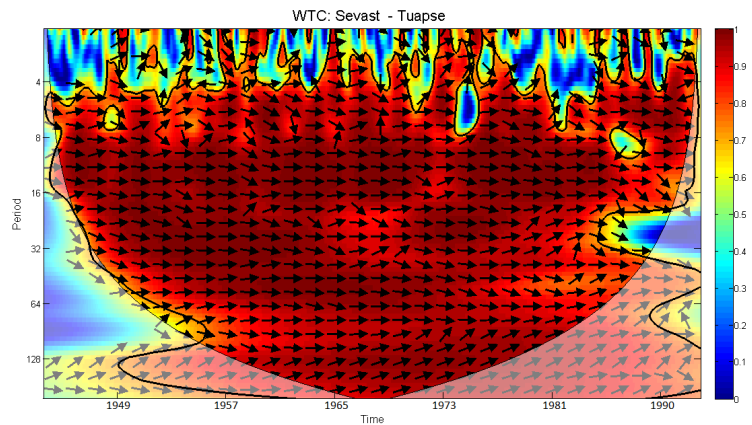


Figure D.6 : Wavelet Coherence Transform of Sevastopol and Tuapse

• *SEVASTOPOL & VARNA*

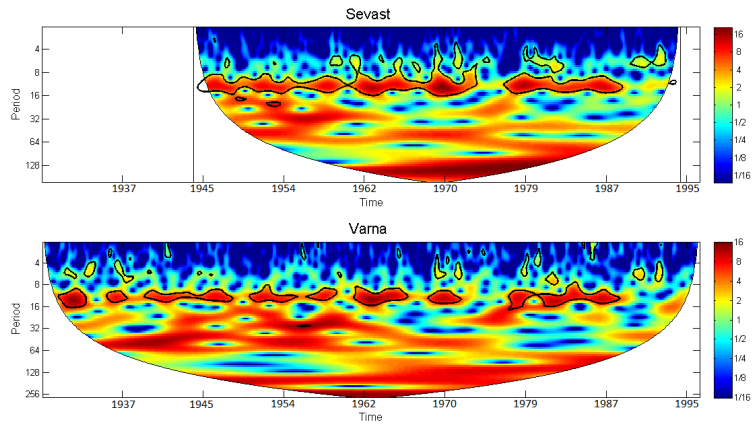


Figure D.7 : Continuous Wavelet Transform comparison between Sevastopol and Varna

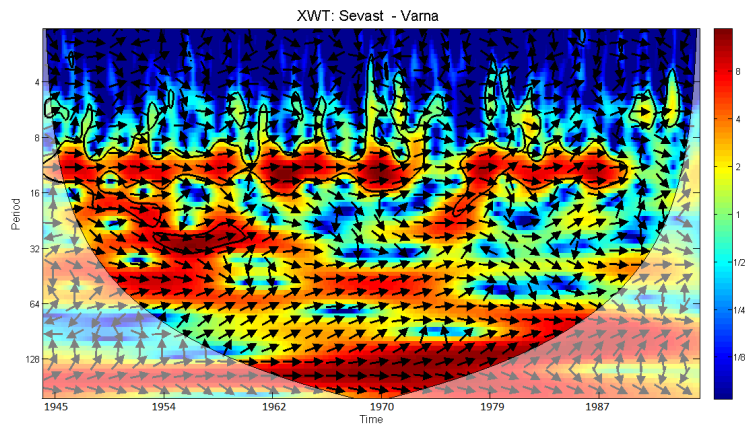


Figure D.8 : Cross Wavelet Transform of Sevastopol and Varna

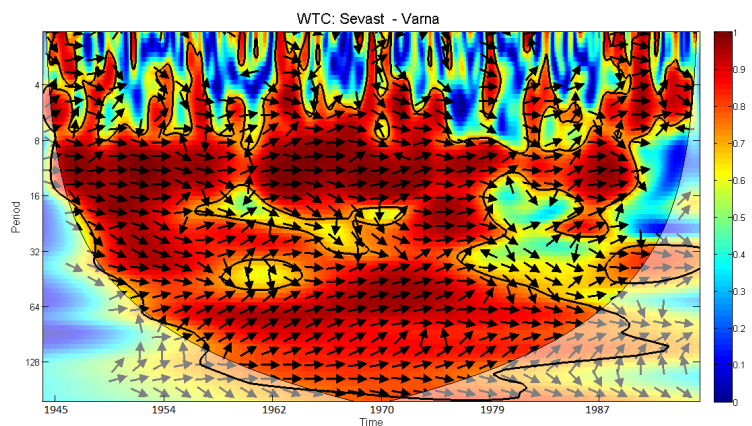


Figure D.9 : Wavelet Coherence Transform of Sevastopol and Varna

• *TUAPSE & BATUMI*

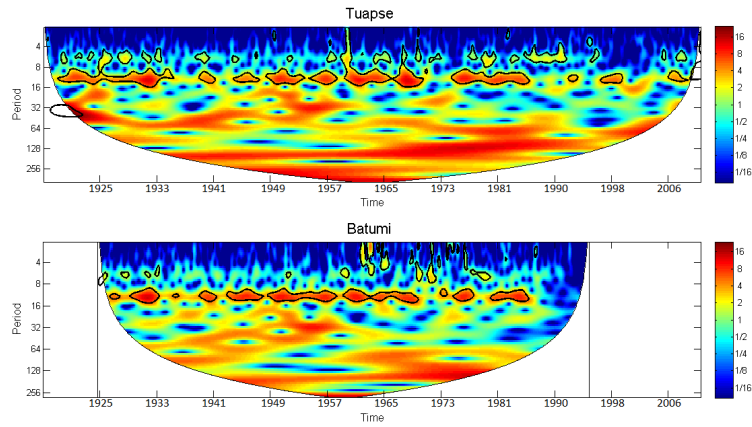


Figure D.10 : Continuous Wavelet Transform comparison between Tuapse and Batumi

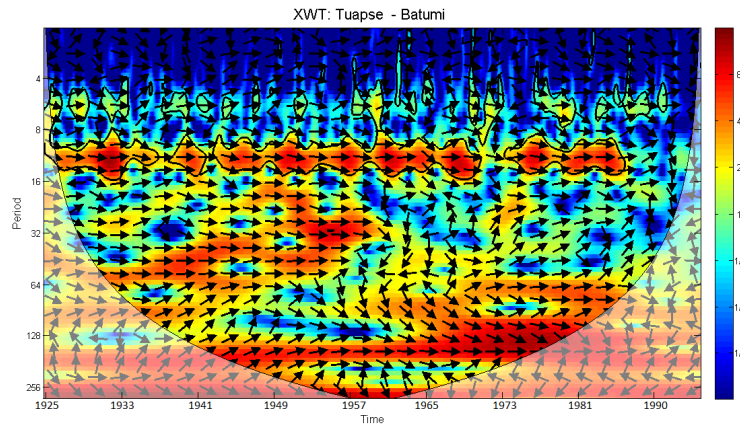


Figure D.11 : Cross Wavelet Transform of Tuapse and Batumi

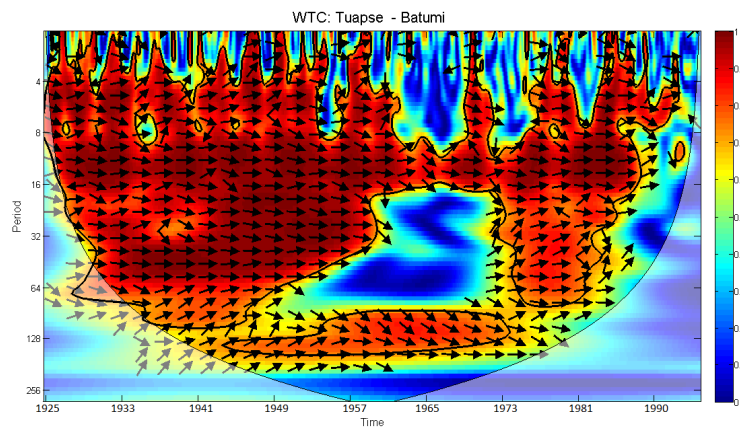


Figure D.12 : Wavelet Coherence Transform of Tuapse and Batumi

- *TUAPSE & VARNA*

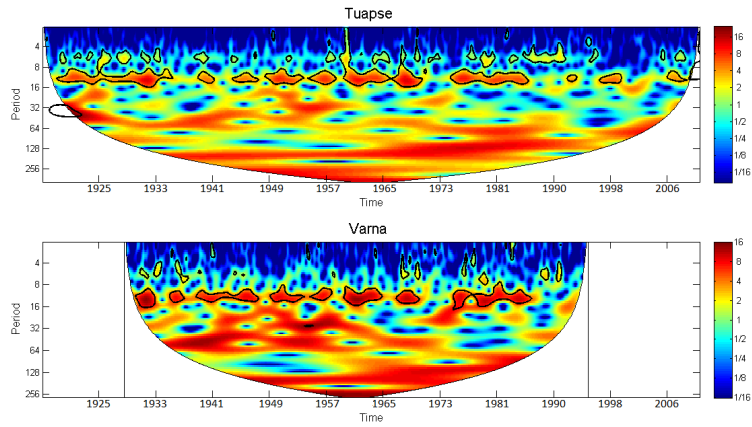


Figure D.13 : Continuous Wavelet Transform comparison between Tuapse and Varna

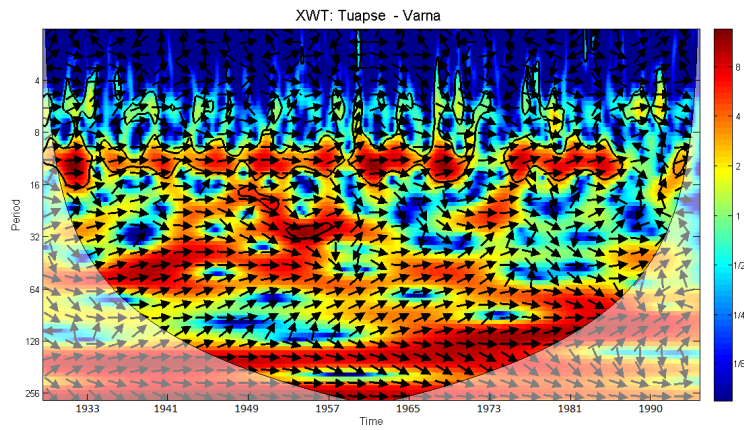


Figure D.14 : Cross Wavelet Transform of Tuapse and Varna

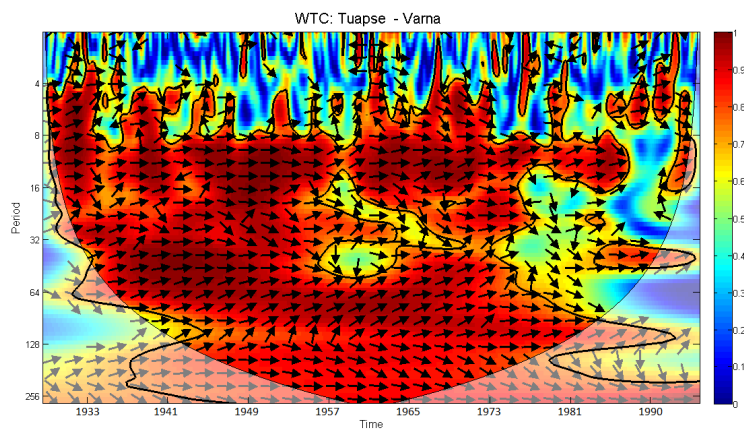


Figure D.15 : Wavelet Coherence Transform of Tuapse and Varna

• *BATUMI & VARNA*

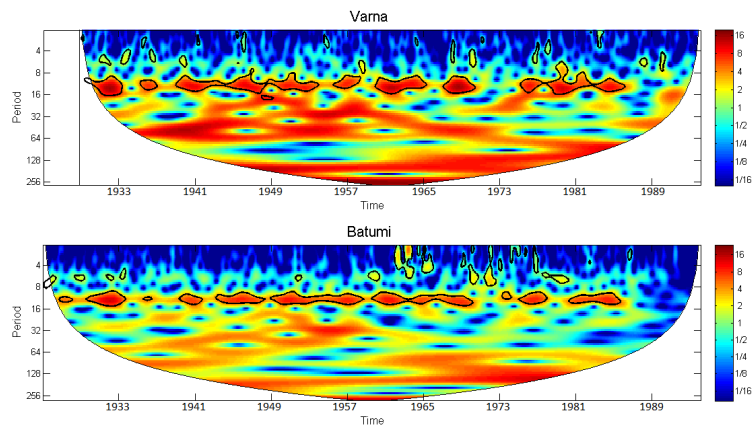


Figure D.16 : Continuous Wavelet Transform comparison between Batumi and Varna

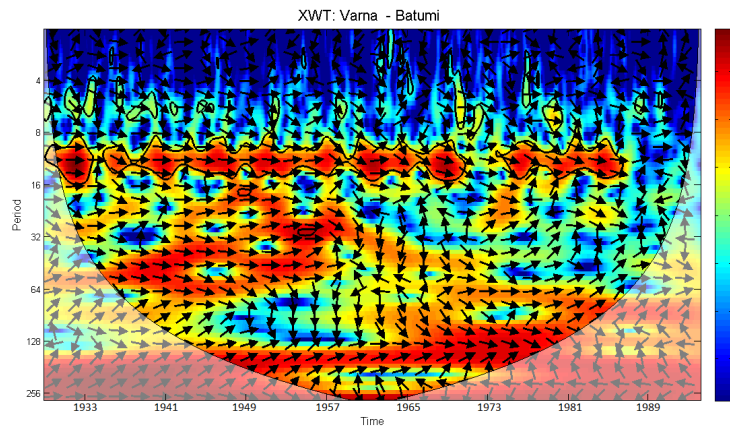


Figure D.17 : Cross Wavelet Transform of Batumi and Varna

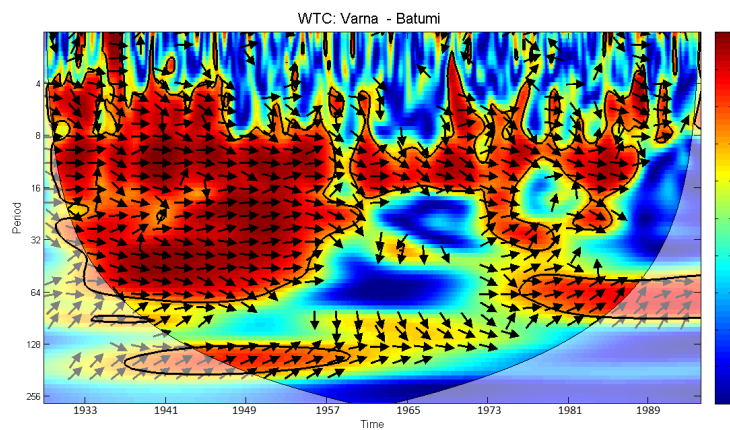


Figure D.18 : Wavelet Coherence Transform of Batumi and Varna

APPENDIX E

• IGNEADA

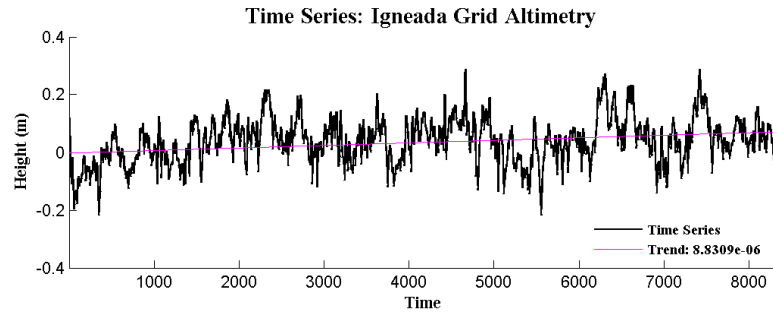


Figure E.1 : Extracted time series from grid altimetry for Igneada

Table E.1 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Igneada

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		8.83E-06	3.48E-07			
$\simeq S_a$	364.2662	0.0232	0.0008	139.086	0.048	4.74
$\simeq S_{sa}$	183.1347	0.0136	0.0008	332.674	0.047	1.64

• AMASRA

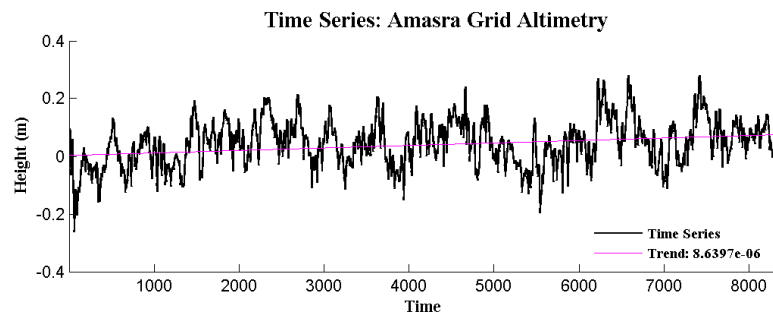


Figure E.2 : Extracted time series from grid altimetry for Amasra

Table E.2 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Amasra

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		8.64E-06	3.52E-07			
$\simeq S_a$	364.2662	0.02620	0.00080	127.562	0.046	5.75
$\simeq S_{sa}$	182.5491	0.02246	0.00079	340.503	0.045	4.37

• *TRABZON*

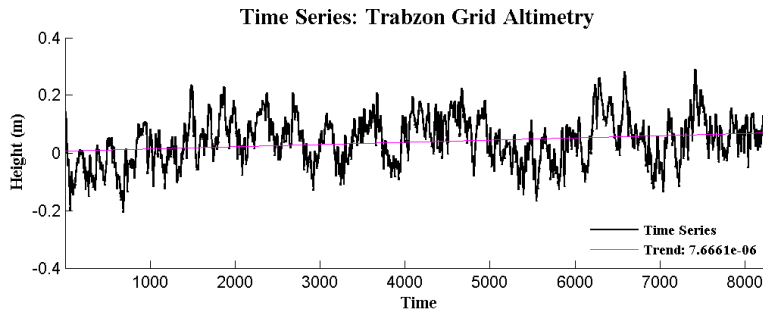


Figure E.3 : Extracted time series from grid altimetry for Trabzon

Table E.3 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Trabzon

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		7.67E-06	3.67E-07			
$\simeq S_a$	364.2662	0.02691	0.00084	140.371	0.048	5.65
$\simeq S_{sa}$	182.5491	0.02468	0.00085	359.335	0.049	5.34

• *BATUMI*

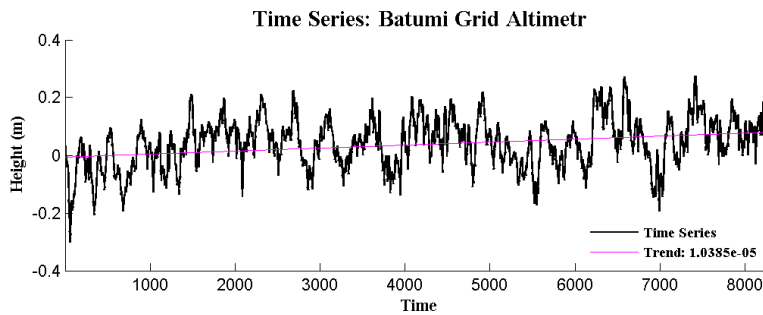


Figure E.4 : Extracted time series from grid altimetry for Batumi

Table E.4 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Batumi

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		1.04E-05	3.78E-07			
$\simeq S_a$	364.2662	0.03164	0.00085	151.670	0.049	8.59
$\simeq S_{sa}$	182.5491	0.02510	0.00082	346.853	0.047	4.78

- *POTI*

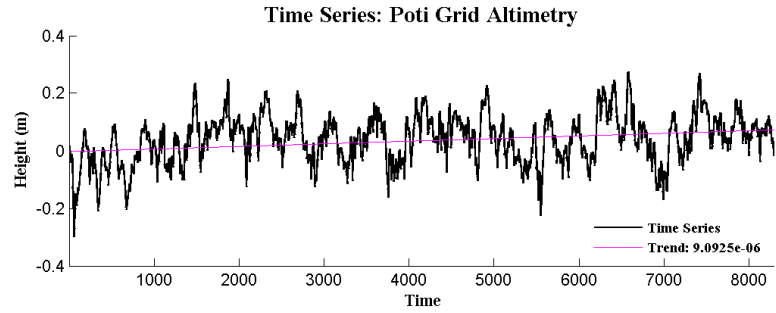


Figure E.5 : Extracted time series from grid altimetry for Poti

Table E.5 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Poti

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		9.09E-06	3.77E-07			
$\simeq S_a$	364.2662	0.02768	0.00090	149.842	0.051	6.57
$\simeq S_{sa}$	182.5491	0.02465	0.00087	350.378	0.050	4.49

- *TUAPSE*

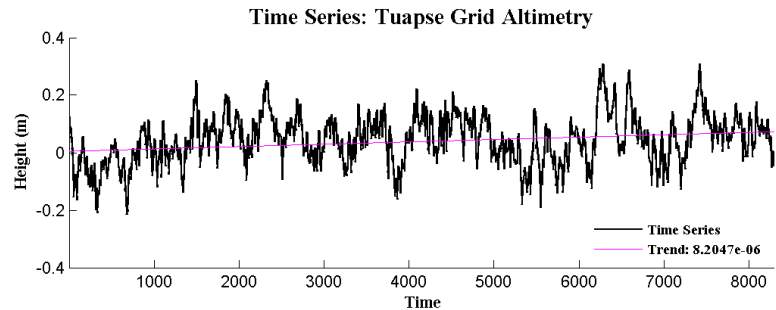


Figure E.6 : Extracted time series from grid altimetry for Tuapse

Table E.6 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Tuapse

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		8.2E-06	3.8E-07			
$\simeq S_a$	364.2662	0.03881	0.00090	118.143	0.052	12.38
$\simeq S_{sa}$	182.5491	0.01952	0.00088	0.288	0.050	2.67

• SEVASTOPOL

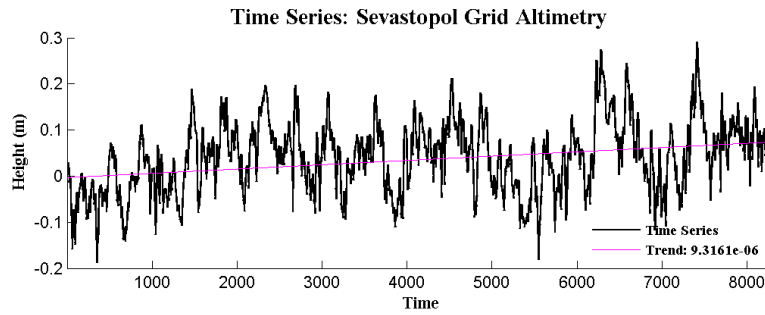


Figure E.7 : Extracted time series from grid altimetry for Sevastopol

Table E.7 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Sevastopol

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		9.32E-06	3.39E-07			
$\simeq S_a$	364.2662	0.03179	0.00078	122.126	0.044	9.49
$\simeq S_{sa}$	182.5491	0.01787	0.00077	340.739	0.044	2.91

• CONSTANTZA

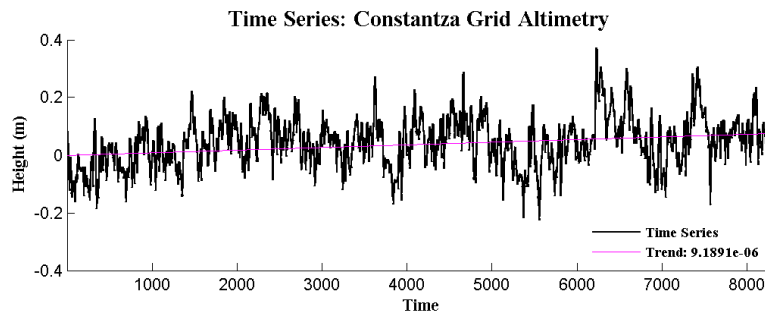


Figure E.8 : Extracted time series from grid altimetry for Constantza

Table E.8 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Constantza

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		9.19E-06	3.86E-07			
$\simeq S_a$	364.2662	0.02830	0.00094	104.956	0.054	5.32
$\simeq S_{sa}$	183.7241	0.01587	0.00093	274.544	0.053	1.75

- VARNA

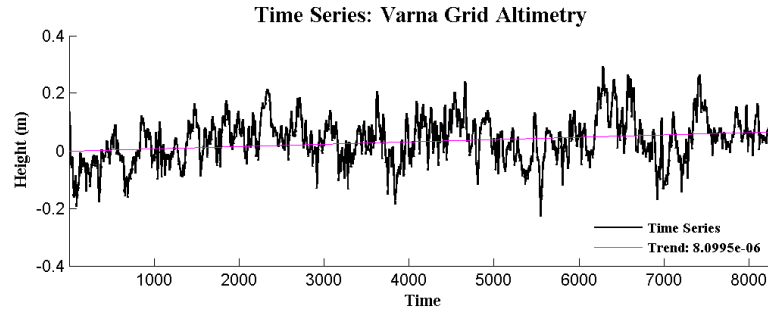


Figure E.9 : Extracted time series from grid altimetry for Varna

Table E.9 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Varna

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		8.1E-06	3.53E-07			
$\simeq S_a$	364.2662	0.02524	0.00085	133.819	0.048	5.30
$\simeq S_{sa}$	183.1347	0.01604	0.00084	313.668	0.048	2.21

- BOURGAS

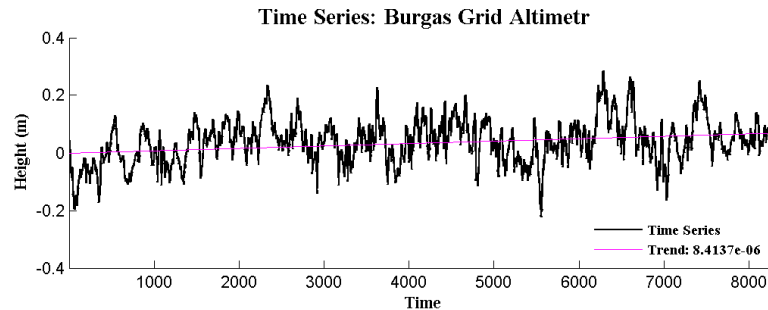


Figure E.10 : Extracted time series from grid altimetry for Bourgas

Table E.10 : Calculated semiannual and annual tidal constituents using LSSA for grid altimetry data of Bourgas

	Period(day)	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)	Spec.(%)
Trend (m)		8.41E-06	3.37E-07			
$\simeq S_a$	361.9565	0.02398	0.00078	164.511	0.045	5.38
$\simeq S_{sa}$	183.1347	0.01733	0.00078	315.411	0.044	2.88



APPENDIX F

- *BOXPLOT*

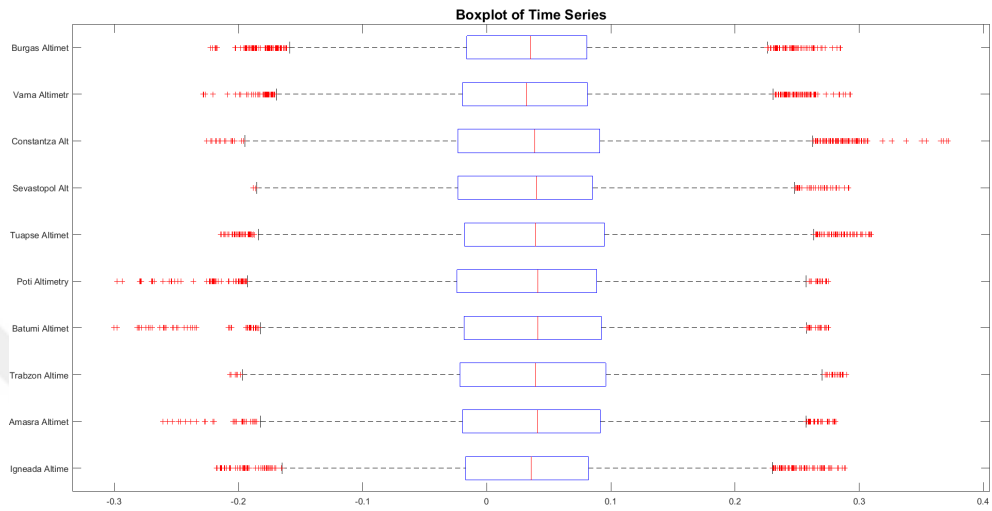


Figure F.1 : Boxplot of 10 time series, extracted from grid altimetry

- *2D PRINCIPLE COMPONENTS*

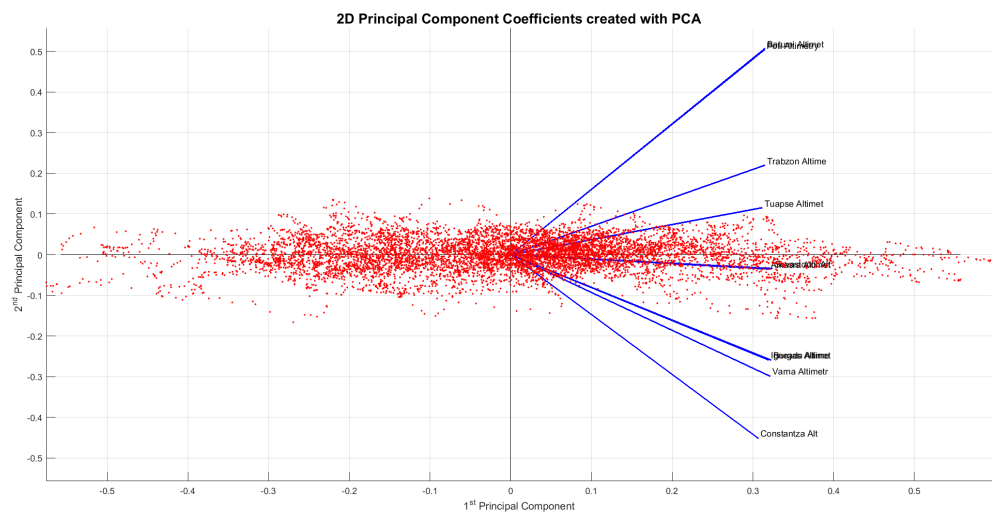


Figure F.2 : 2 dimension of first and second principle components with data sets' direction

• 3D PRINCIPLE COMPONENTS

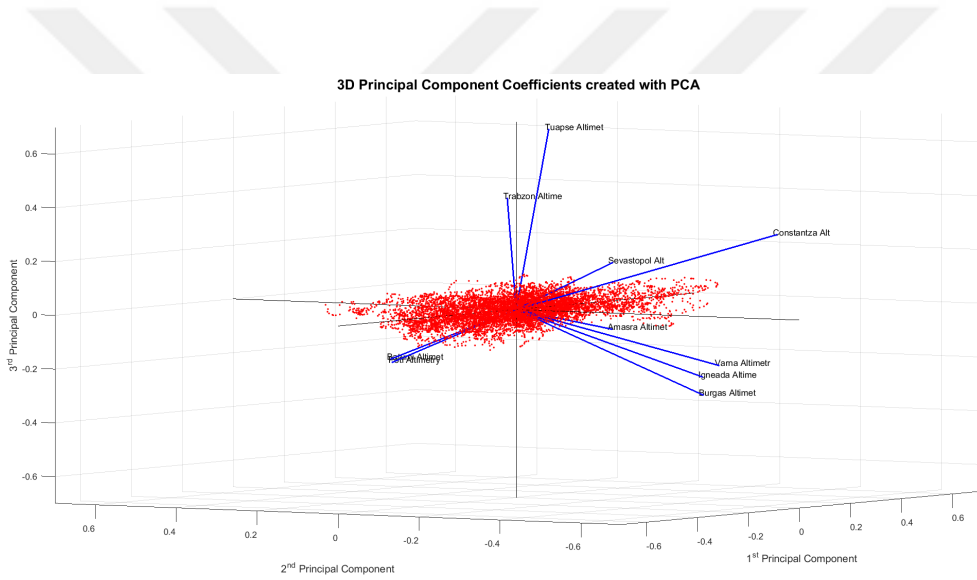
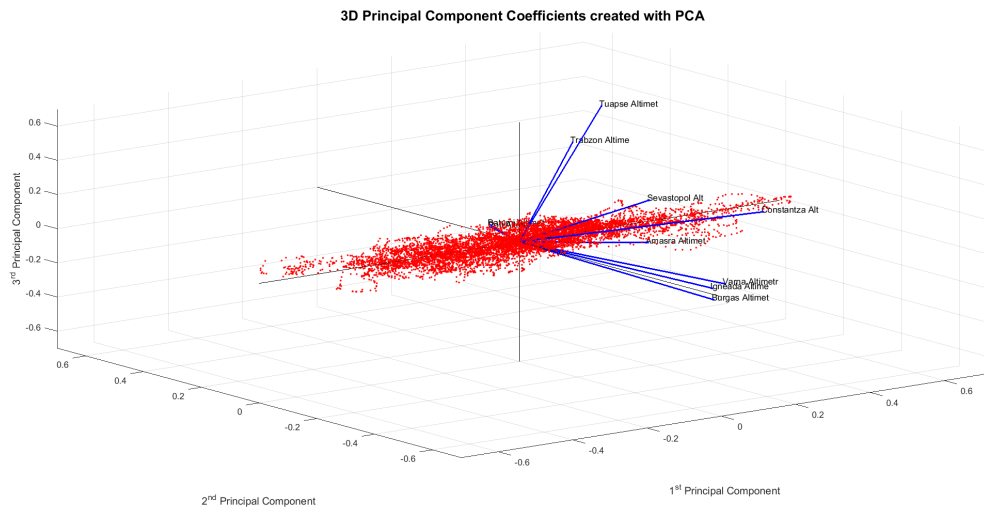


Figure E.3 : 2 view of three dimension of first, second and third principle components with data sets' direction

APPENDIX G

- *SEVASTOPOL & BATUMI*

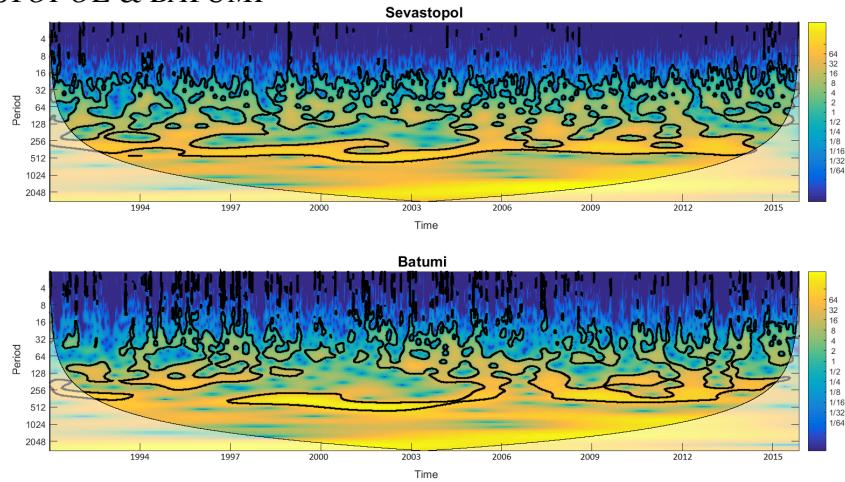


Figure G.1 : Continuous Wavelet Transform comparison between Sevastopol and Batumi extracted from grid altimetry data

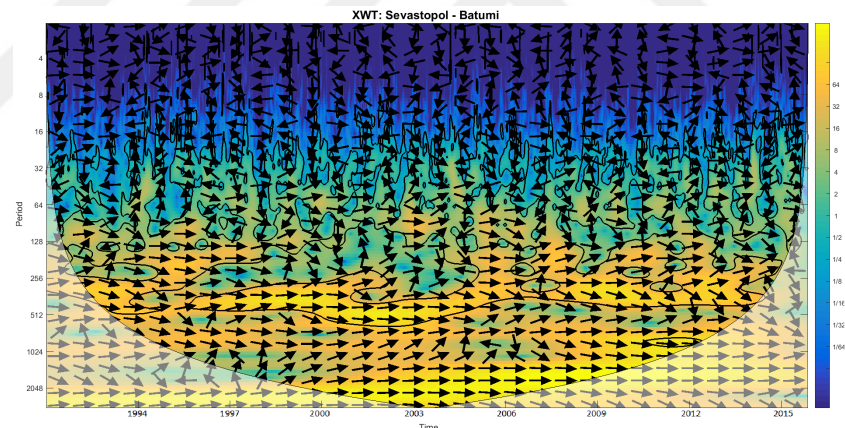


Figure G.2 : Cross Wavelet Transform of Sevastopol and Batumi extracted from grid altimetry data

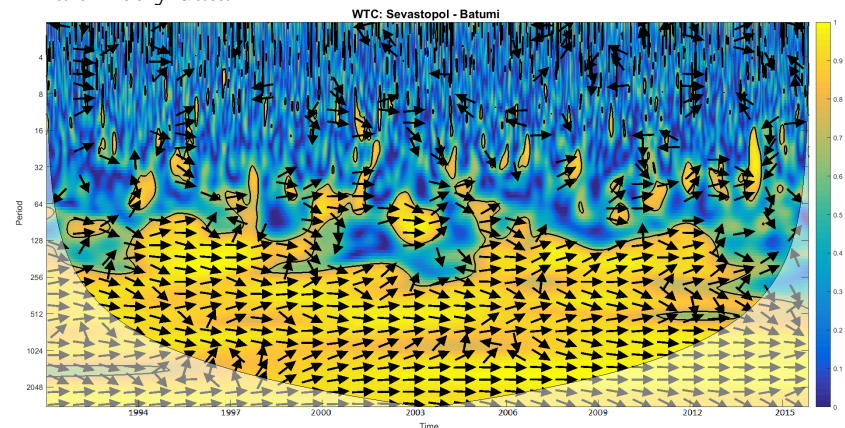


Figure G.3 : Wavelet Coherence Transform of Sevastopol and Batumi extracted from grid altimetry data

- SEVASTOPOL & TUAPSE

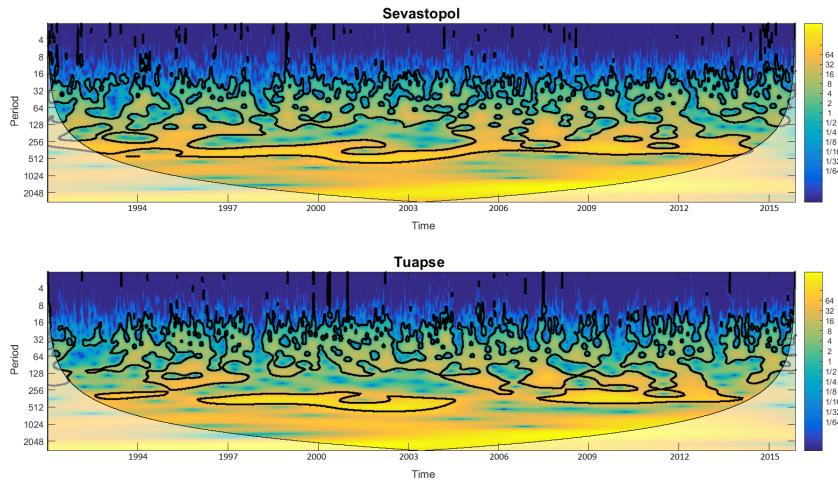


Figure G.4 : Continuous Wavelet Transform comparison between Sevastopol and Tuapse extracted from grid altimetry data

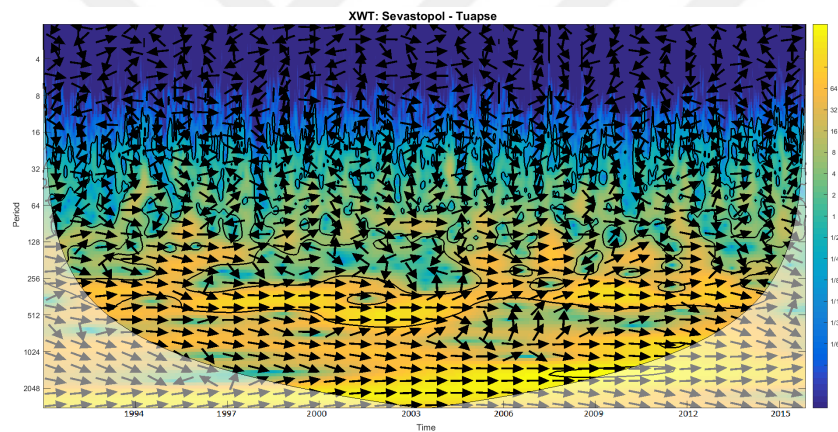


Figure G.5 : Cross Wavelet Transform of Sevastopol and Tuapse extracted from grid altimetry data

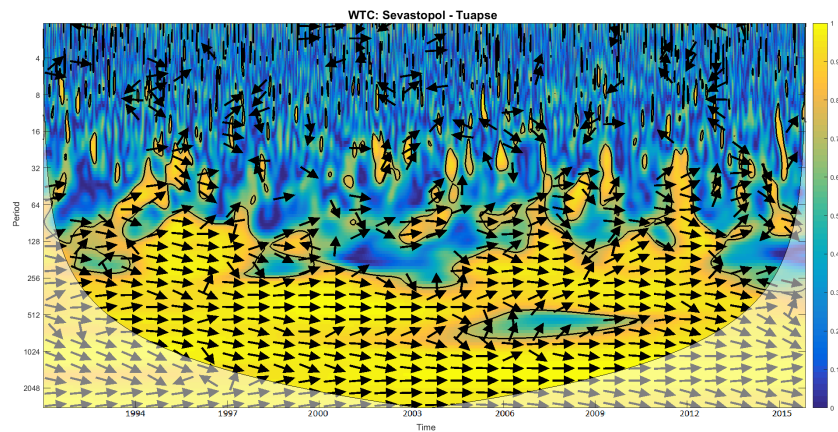


Figure G.6 : Wavelet Coherence Transform of Sevastopol and Tuapse extracted from grid altimetry data

- SEVASTOPOL & VARNA

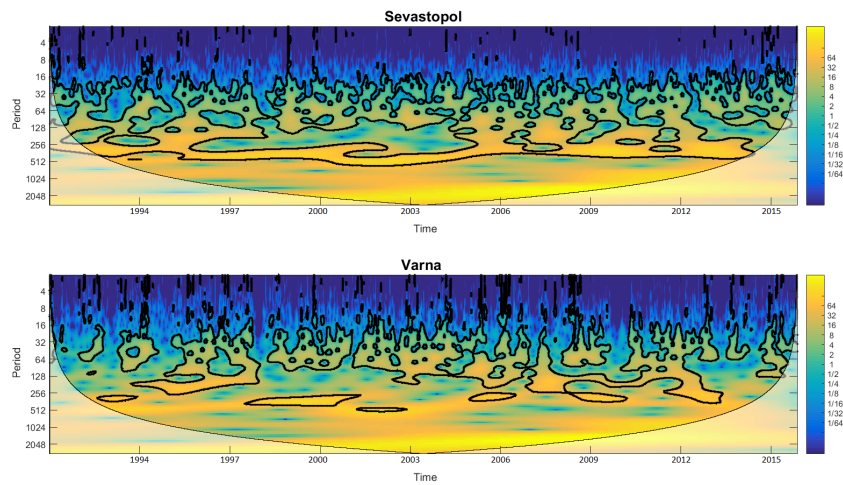


Figure G.7 : Continuous Wavelet Transform comparison between Sevastopol and Varna extracted from grid altimetry data

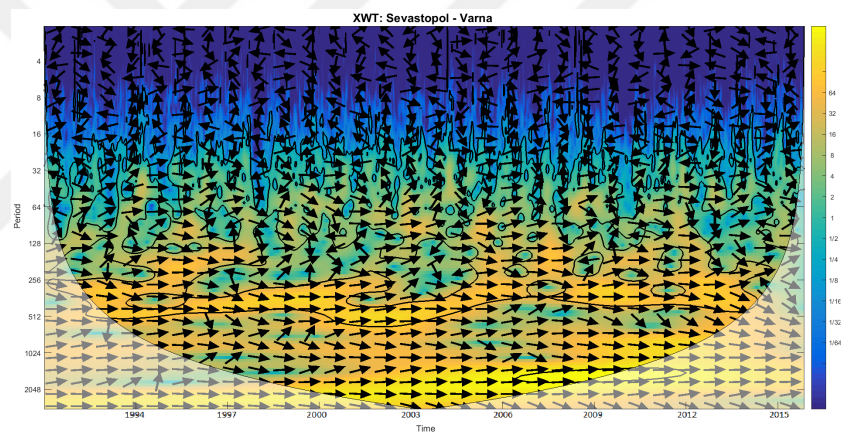


Figure G.8 : Cross Wavelet Transform of Sevastopol and Varna extracted from grid altimetry data

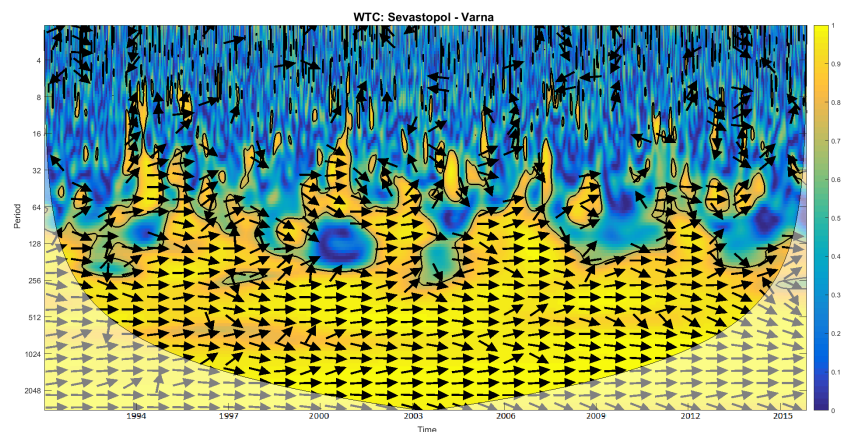


Figure G.9 : Wavelet Coherence Transform of Sevastopol and Varna extracted from grid altimetry data

• *TUAPSE & BATUMI*

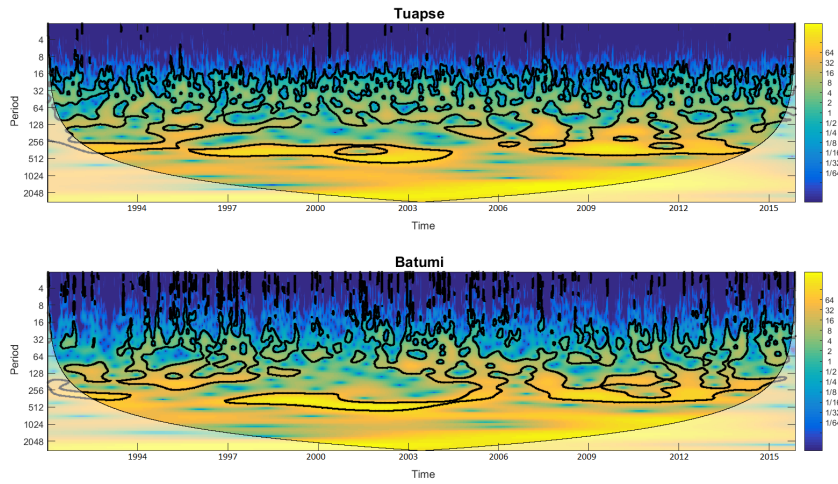


Figure G.10 : Continuous Wavelet Transform comparison between Tuapse and Batumi extracted from grid altimetry data

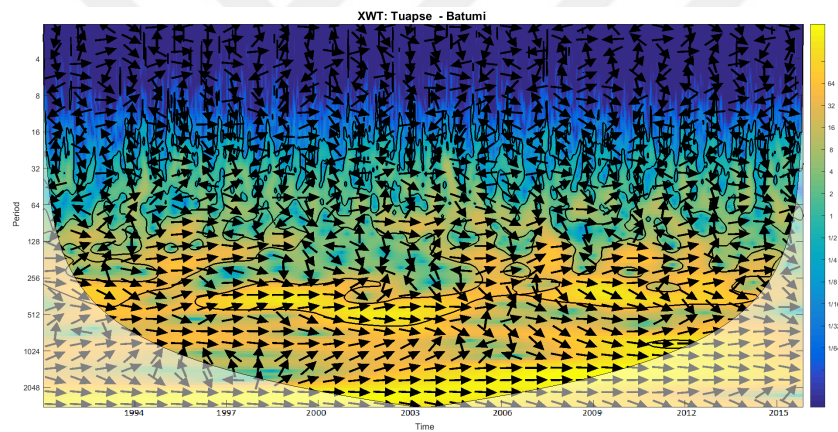


Figure G.11 : Cross Wavelet Transform of Tuapse and Batumi extracted from grid altimetry data

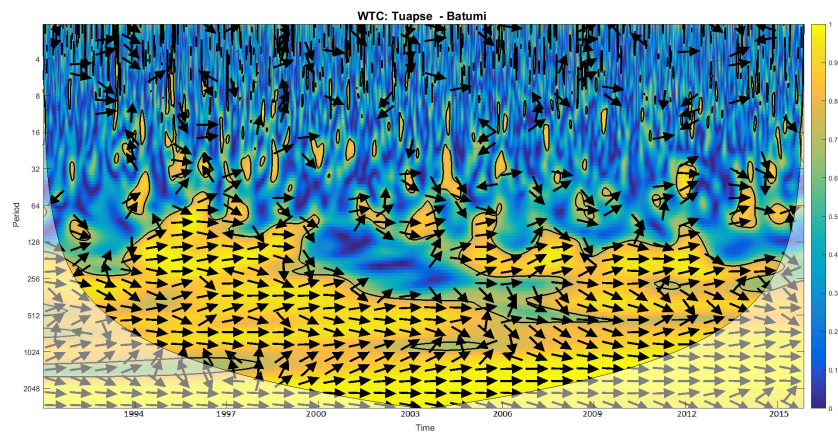


Figure G.12 : Wavelet Coherence Transform of Tuapse and Batumi extracted from grid altimetry data

• *TUAPSE & VARNA*

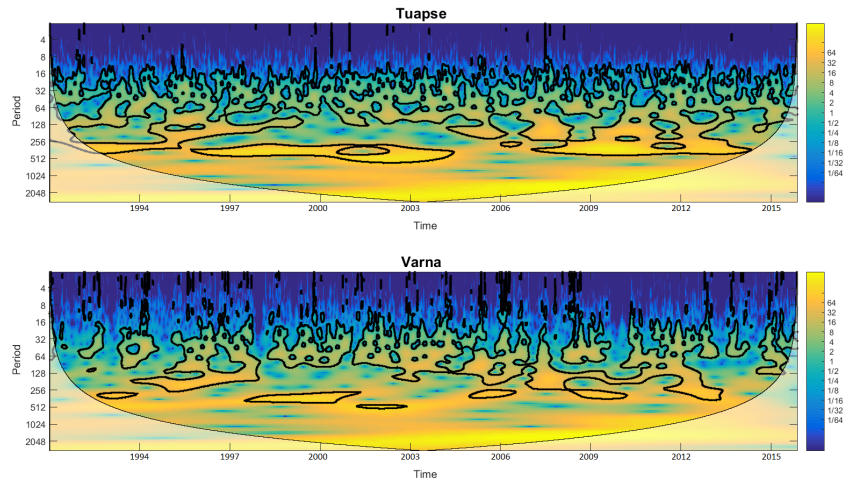


Figure G.13 : Continuous Wavelet Transform comparison between Tuapse and Varna extracted from grid altimetry data

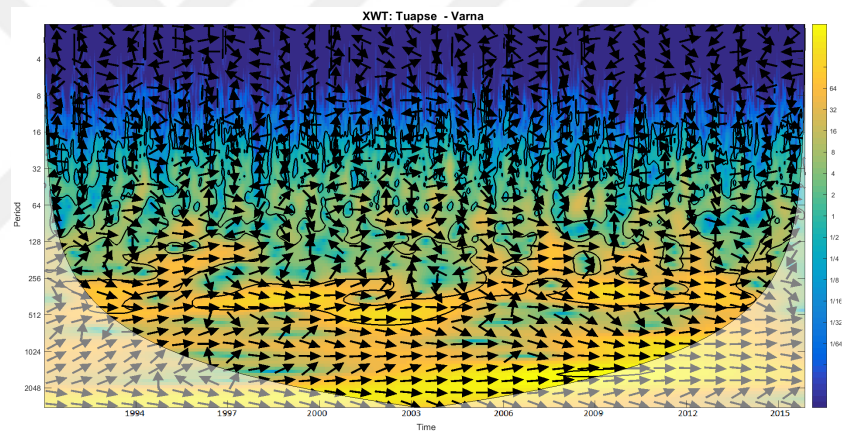


Figure G.14 : Cross Wavelet Transform of Tuapse and Varna extracted from grid altimetry data

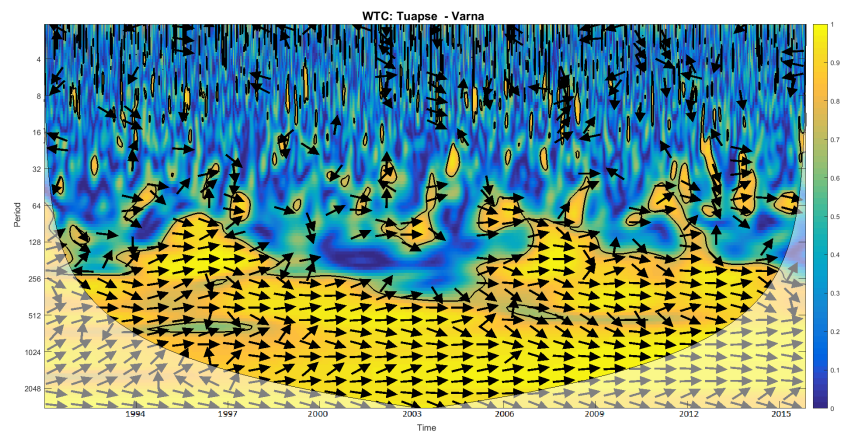


Figure G.15 : Wavelet Coherence Transform of Tuapse and Varna extracted from grid altimetry data

• *BATUMI & VARNA*

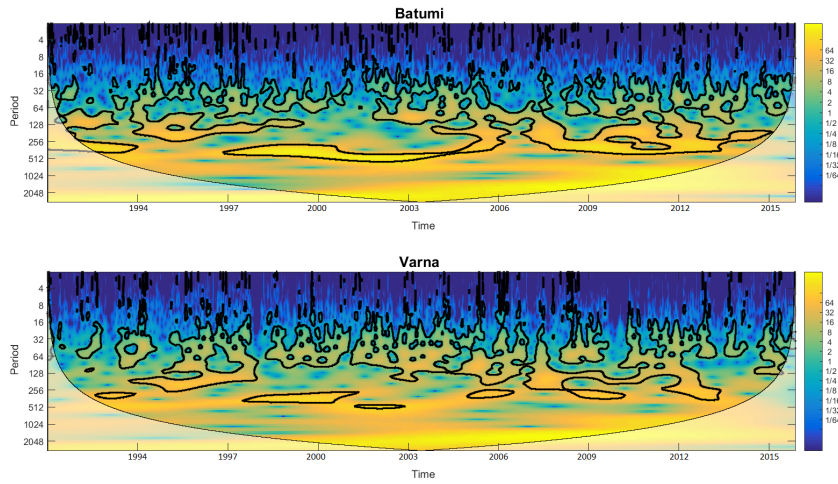


Figure G.16 : Continuous Wavelet Transform comparison between Batumi and Varna extracted from grid altimetry data

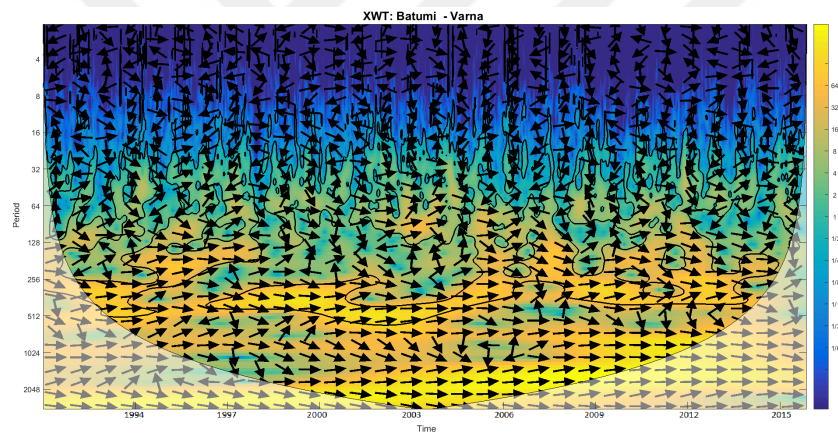


Figure G.17 : Cross Wavelet Transform of Batumi and Varna extracted from grid altimetry data

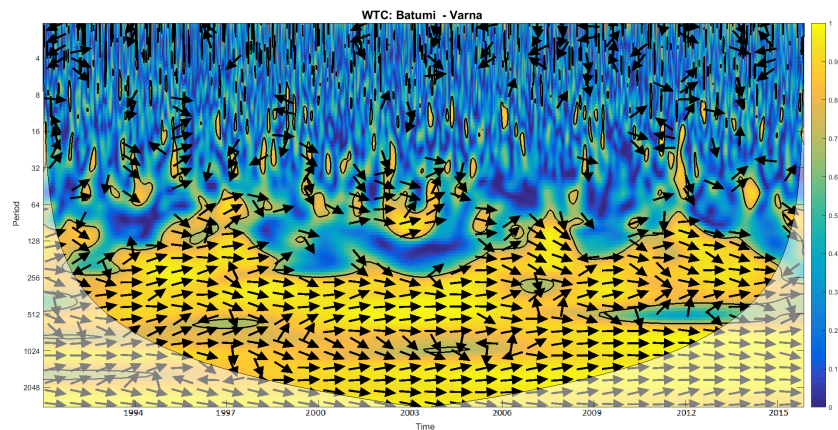


Figure G.18 : Wavelet Coherence Transform of Batumi and Varna extracted from grid altimetry data

- *IGNEADA*

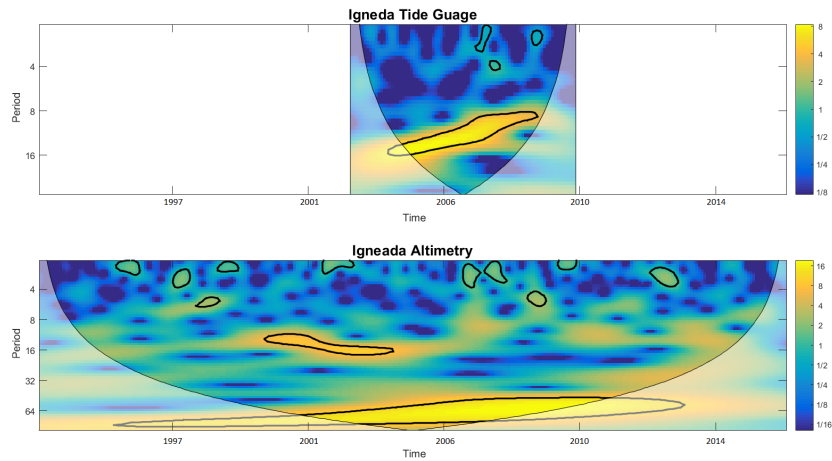


Figure G.19 : Continuous Wavelet Transform comparison between tide gauge and grid altimetry data for Igneada

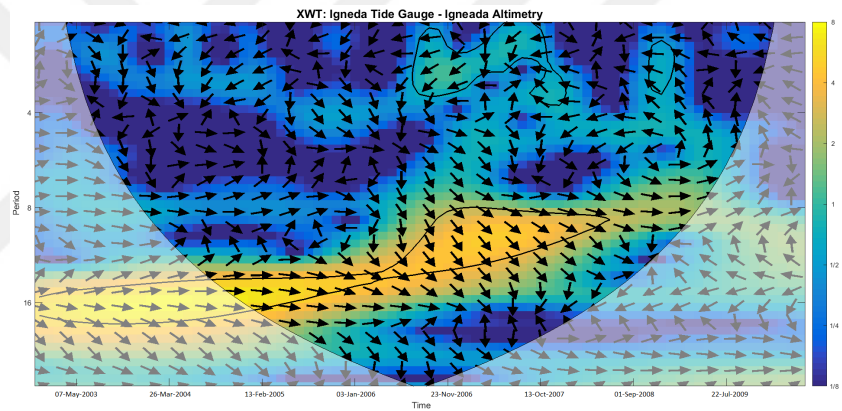


Figure G.20 : Cross Wavelet Transform of tide gauge and grid altimetry data for Igneada

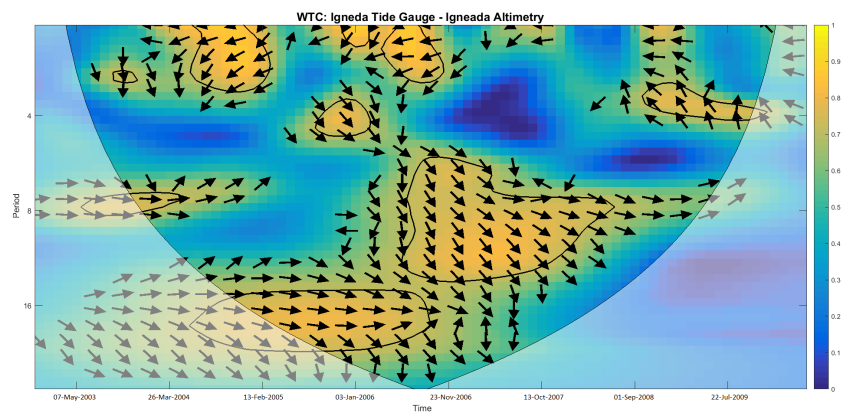


Figure G.21 : Wavelet Coherence Transform of tide gauge and grid altimetry data for Igneada

- AMASRA

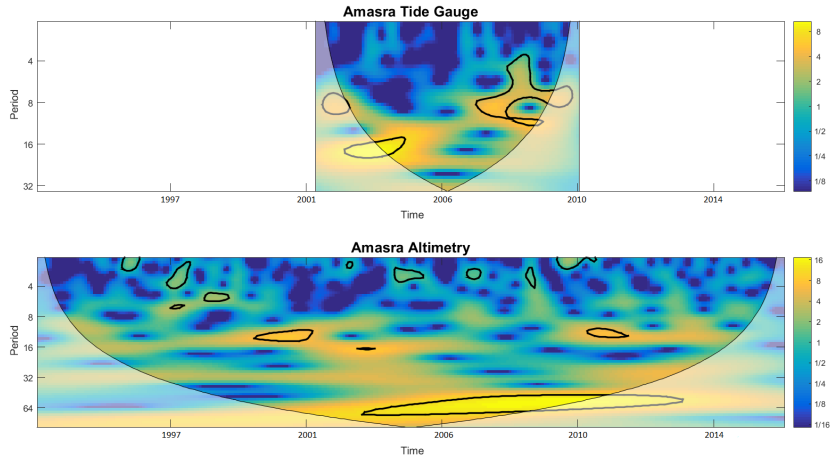


Figure G.22 : Continuous Wavelet Transform comparison between tide gauge and grid altimetry data for Amasra

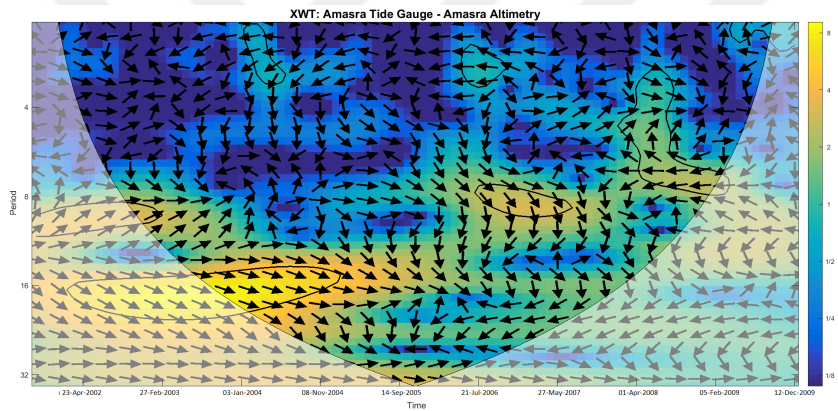


Figure G.23 : Cross Wavelet Transform of tide gauge and grid altimetry data for Amasra

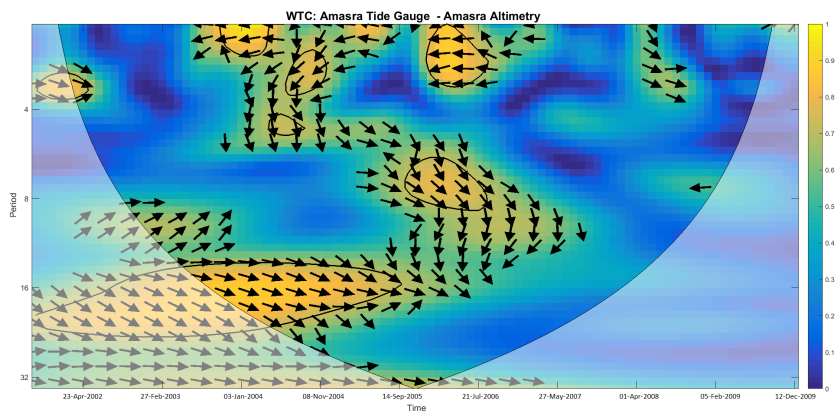


Figure G.24 : Wavelet Coherence Transform of tide gauge and grid altimetry data for Amasra

• *TRABZON*

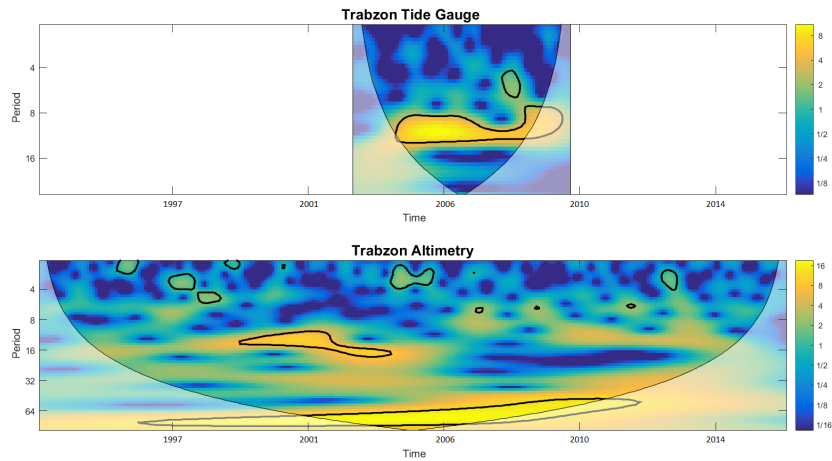


Figure G.25 : Continuous Wavelet Transform comparison between tide gauge and grid altimetry data for Trabzon

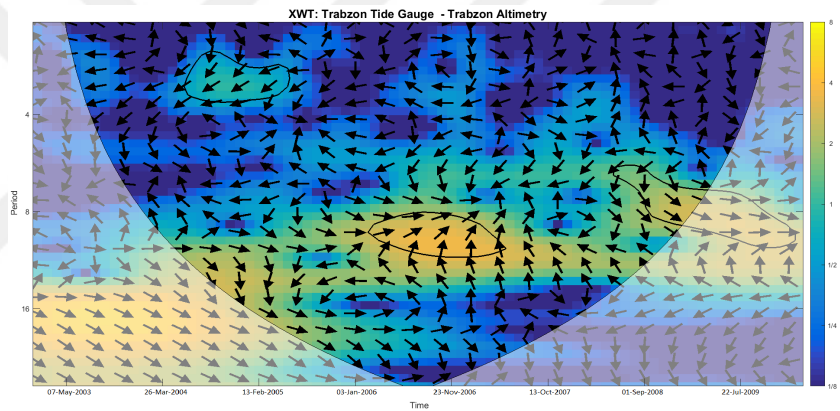


Figure G.26 : Cross Wavelet Transform of tide gauge and grid altimetry data for Trabzon

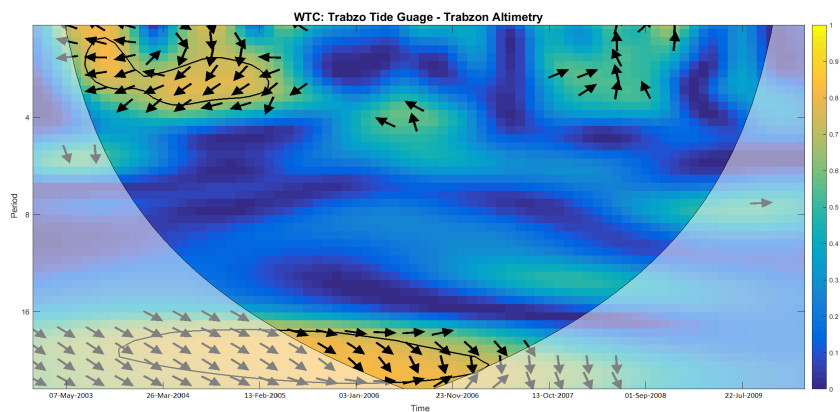


Figure G.27 : Wavelet Coherence Transform of tide gauge and grid altimetry data for Trabzon

• *BATUMI*

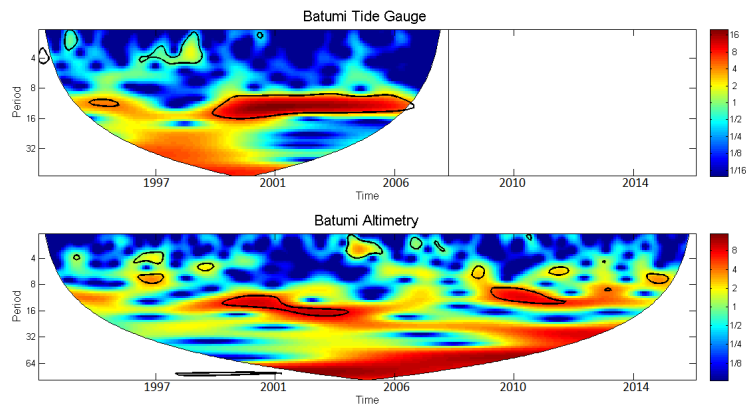


Figure G.28 : Continuous Wavelet Transform comparison between tide gauge and grid altimetry data for Batumi

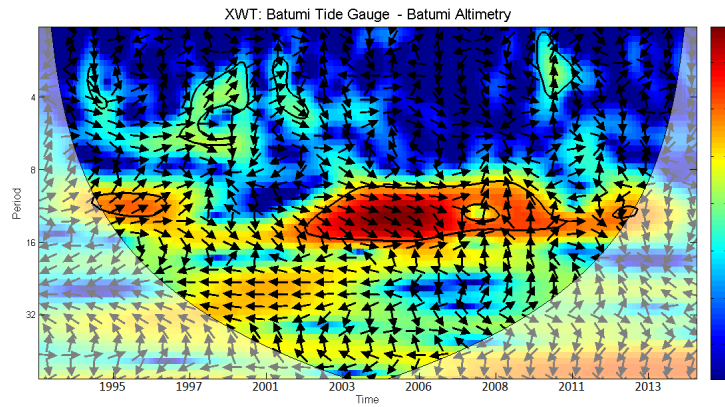


Figure G.29 : Cross Wavelet Transform of tide gauge and grid altimetry data for Batumi

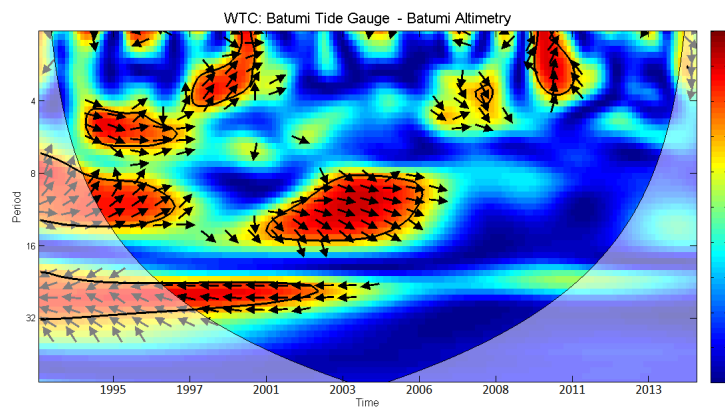


Figure G.30 : Wavelet Coherence Transform of tide gauge and grid altimetry data for Batumi

- *POTI*

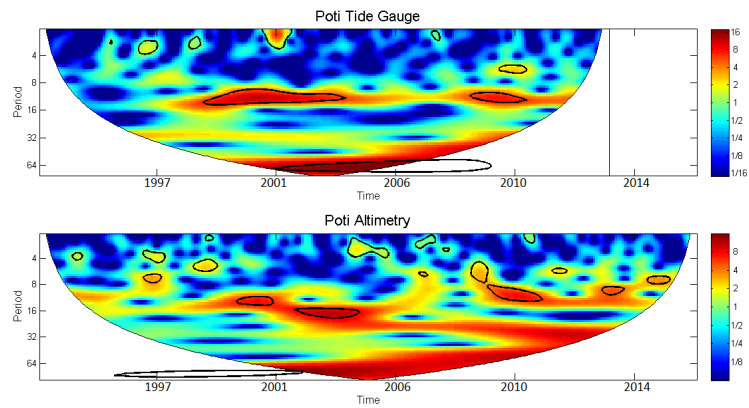


Figure G.31 : Continuous Wavelet Transform comparison between tide gauge and grid altimetry data for Poti

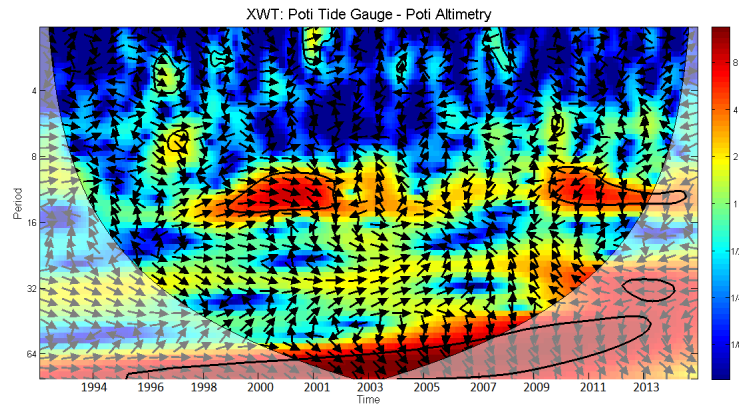


Figure G.32 : Cross Wavelet Transform of tide gauge and grid altimetry data for Poti

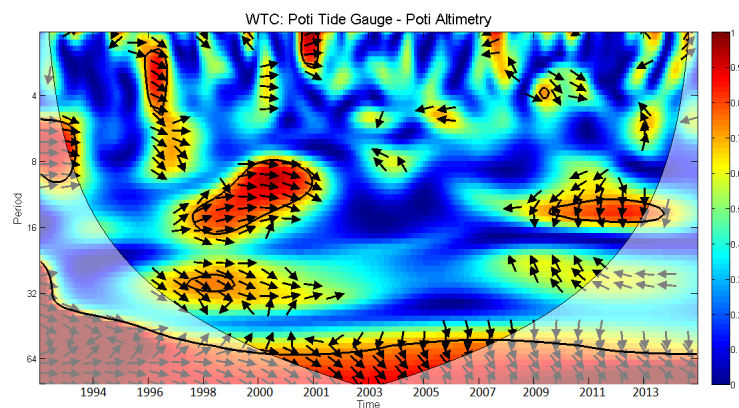


Figure G.33 : Wavelet Coherence Transform of tide gauge and grid altimetry data for Poti

• TUAPSE

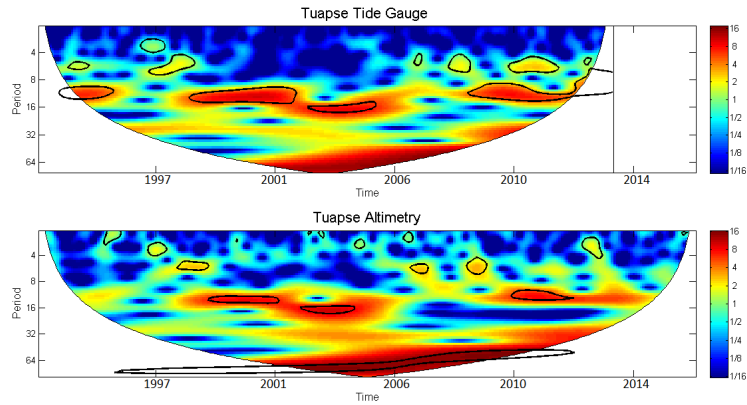


Figure G.34 : Continuous Wavelet Transform comparison between tide gauge and grid altimetry data for Tuapse

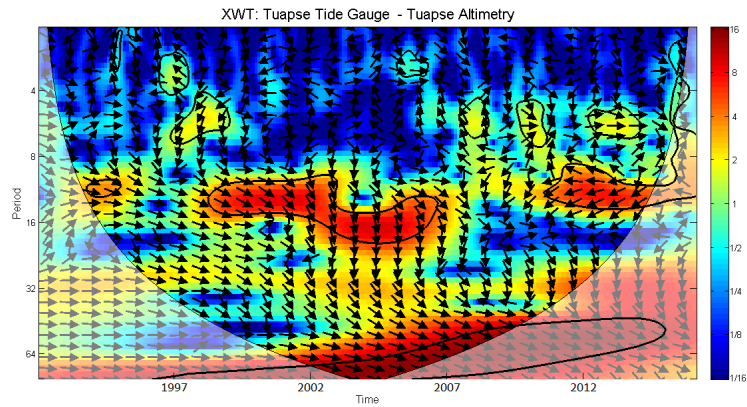


Figure G.35 : Cross Wavelet Transform of tide gauge and grid altimetry data for Tuapse

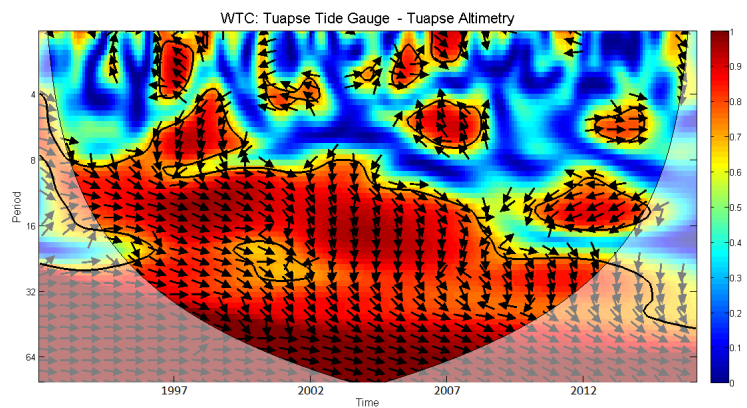


Figure G.36 : Wavelet Coherence Transform of tide gauge and grid altimetry data for Tuapse

APPENDIX H

- *IGNEADA*

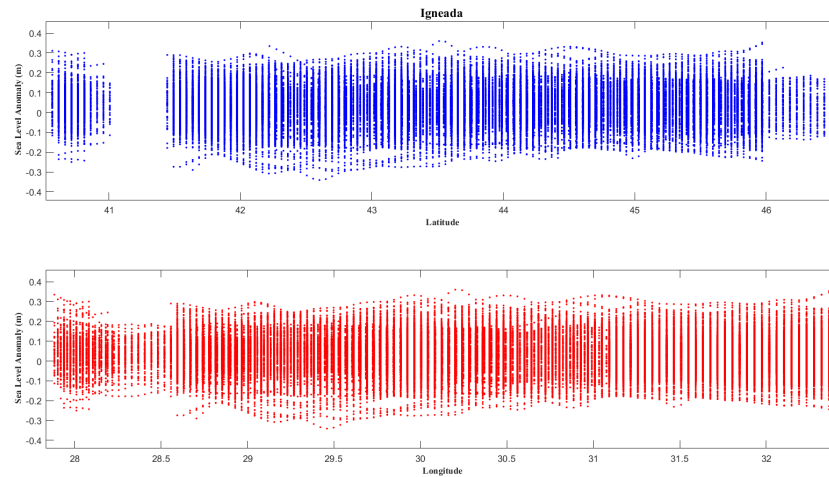


Figure H.1 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1-J2 No.109 and GFO No.388 along-tracks, passed near to Igneada

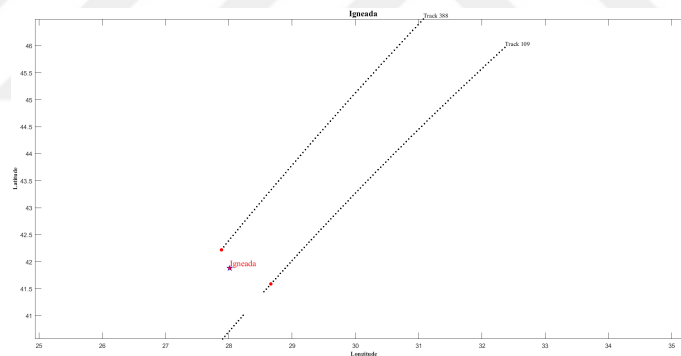


Figure H.2 : Nearest track points (red points) of T/P-J1-J2 No.109 and GFO No.388 from Igneada station

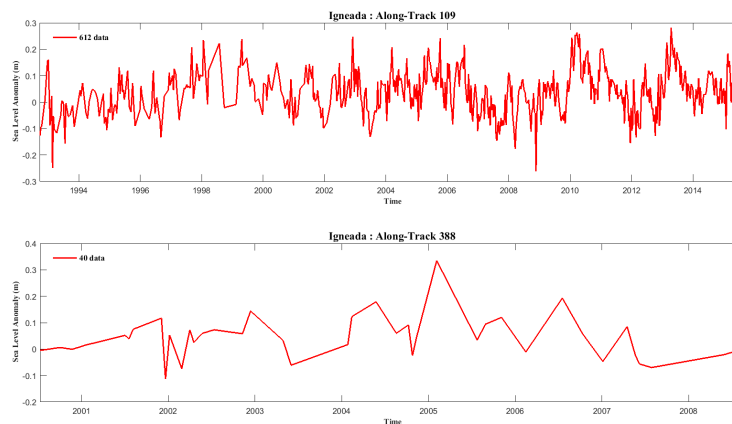


Figure H.3 : Nearest track points time series of T/P-J1-J2 No.109 (top) and GFO No.388 (bottom) near to Igneada

- AMASRA

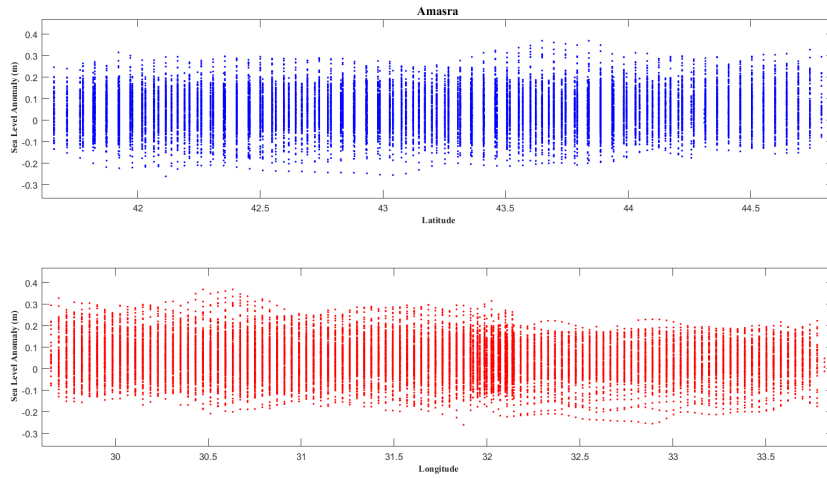


Figure H.4 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1 interlaced No.144 and GFO No.158 along-tracks, passed near to Amasra

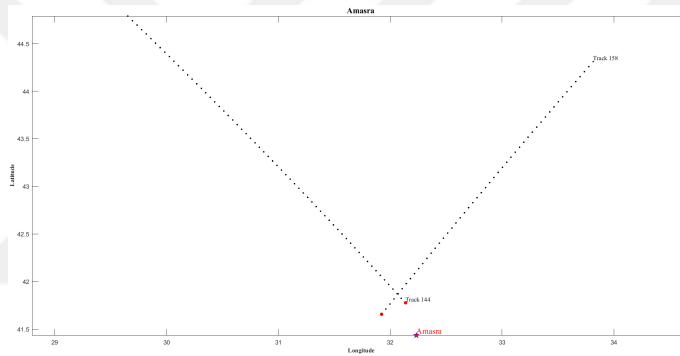


Figure H.5 : Nearest track points (red points) of T/P-J1 interlaced No.144 and GFO No.158 from Amasra station

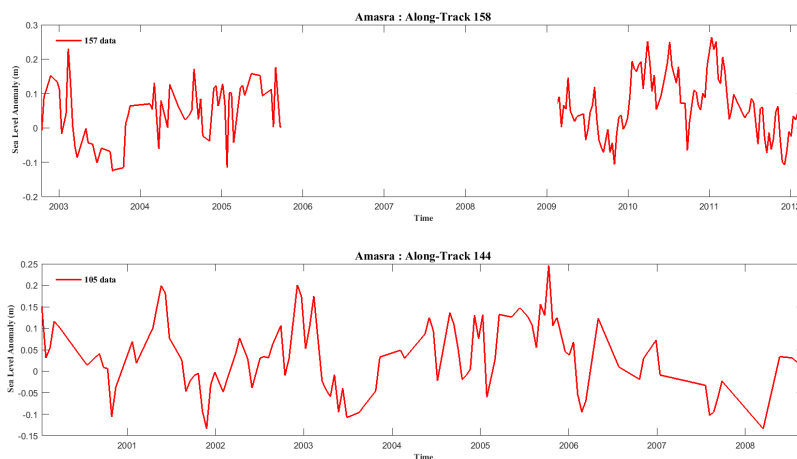


Figure H.6 : Nearest track points time series of GFO No.158 (top) and T/P-J1 interlaced No.144 (bottom) near to Amasra

• *TRABZON*

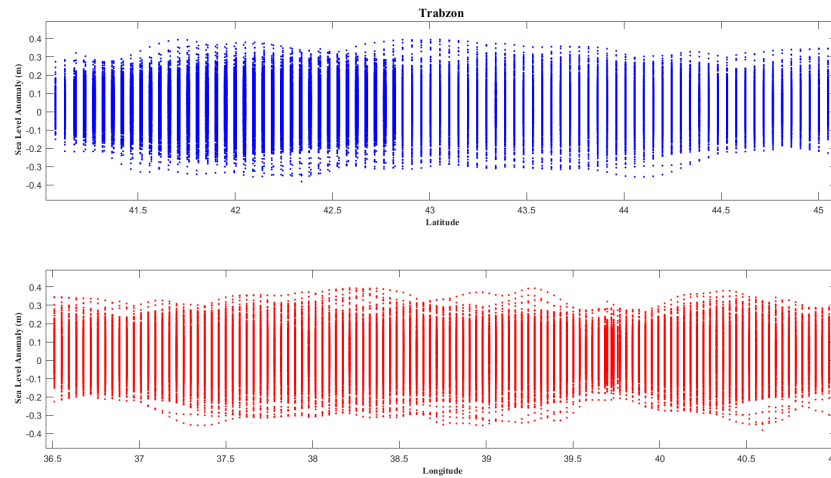


Figure H.7 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1-J2 No.42,159 along-tracks, passed near to Trabzon

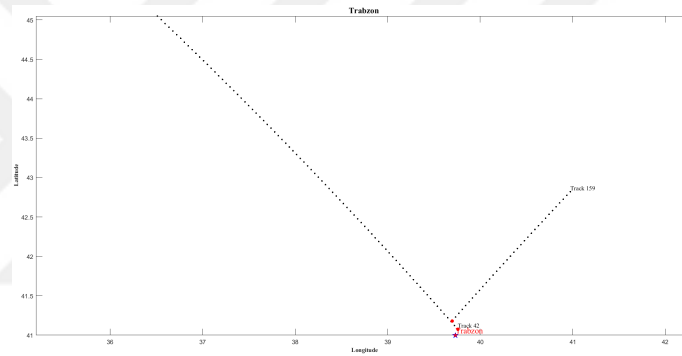


Figure H.8 : Nearest track points (red points) of T/P-J1-J2 No.42,159 from Trabzon station

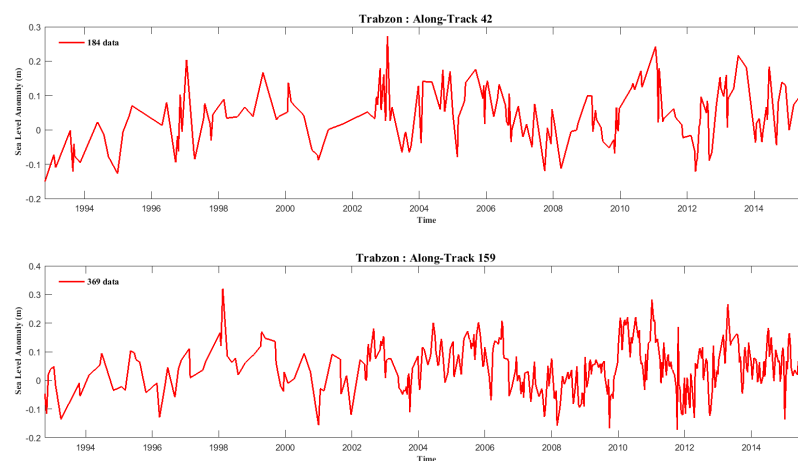


Figure H.9 : Nearest track points time series of T/P-J1-J2 No.42 (top) and T/P-J1-J2 No.159 (bottom) near to Trabzon

• *BATUMI*

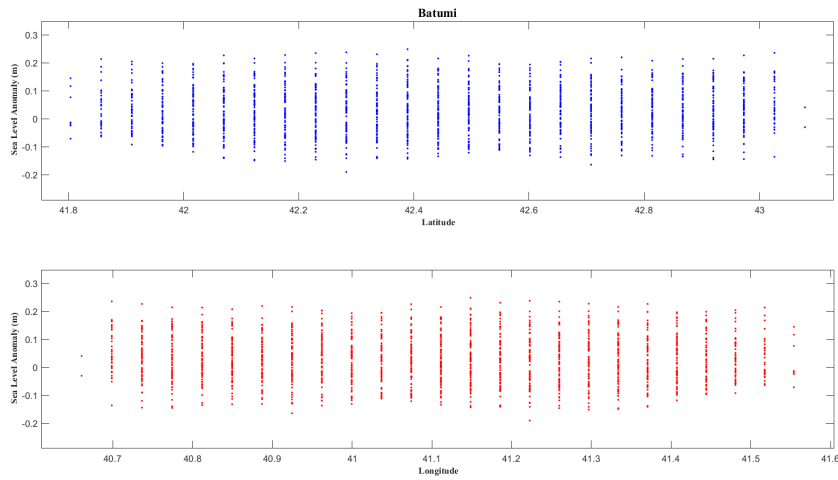


Figure H.10 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of GFO No.111 along-tracks, passed near to Batumi

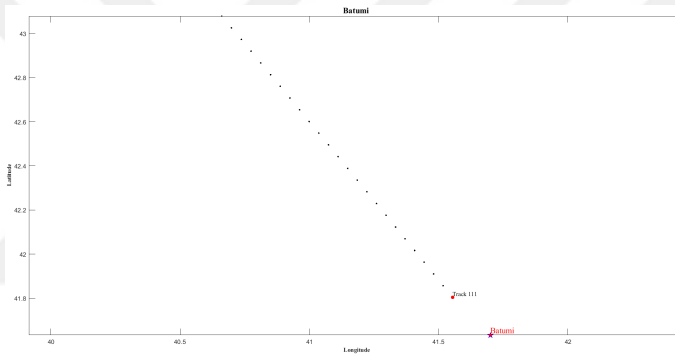


Figure H.11 : Nearest track points (red points) of GFO No.111 from Batumi station

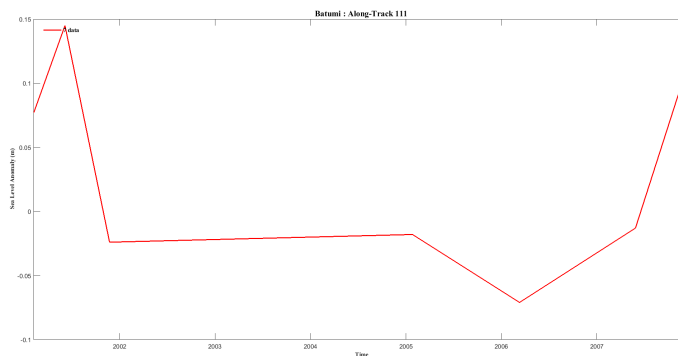


Figure H.12 : Nearest track points time series of GFO No.111 near to Batumi

- *POTI*

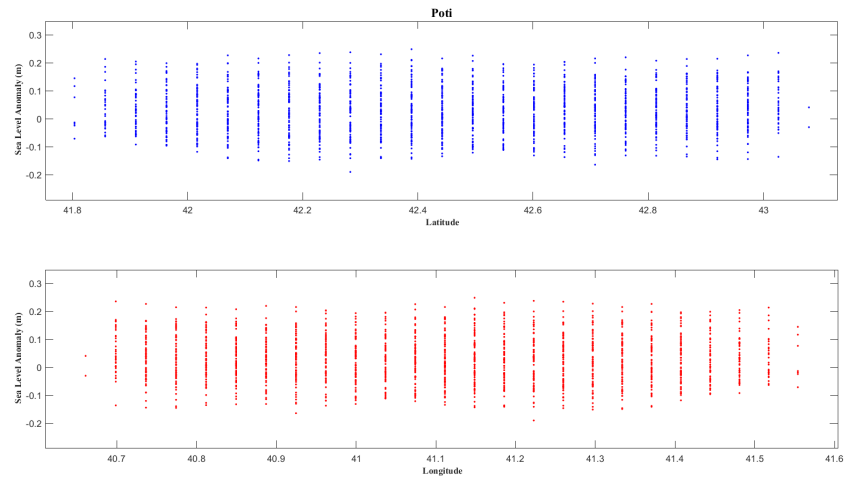


Figure H.13 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of GFO No.111 along-tracks, passed near to Poti

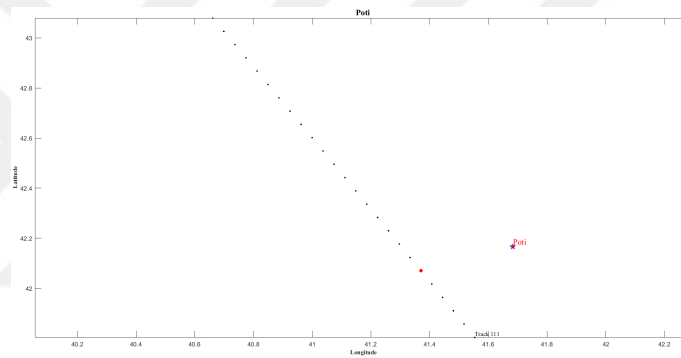


Figure H.14 : Nearest track points (red points) of GFO No.111 from Poti station

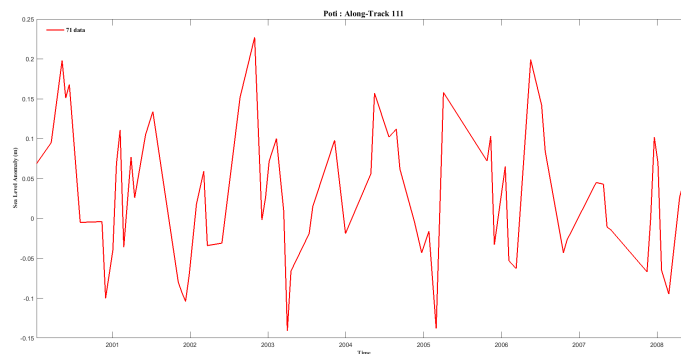


Figure H.15 : Nearest track points time series of GFO No.111 near to Poti

• *TUAPSE*

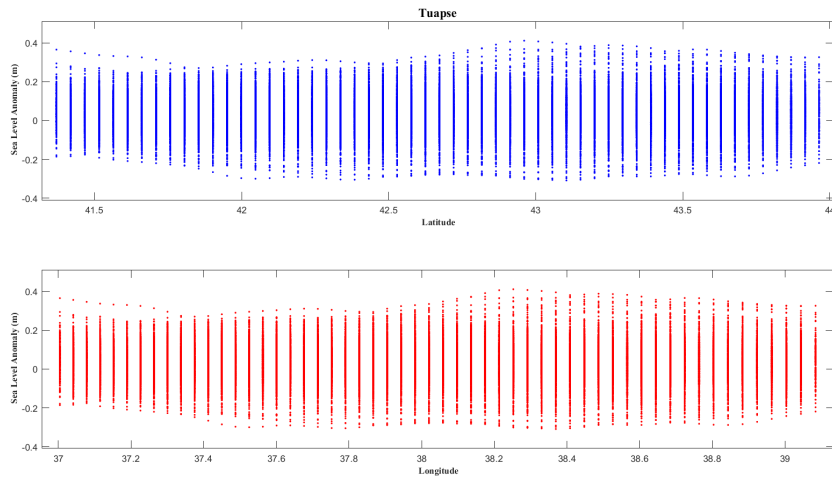


Figure H.16 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1-J2 No.83 along-tracks, passed near to Tuapse

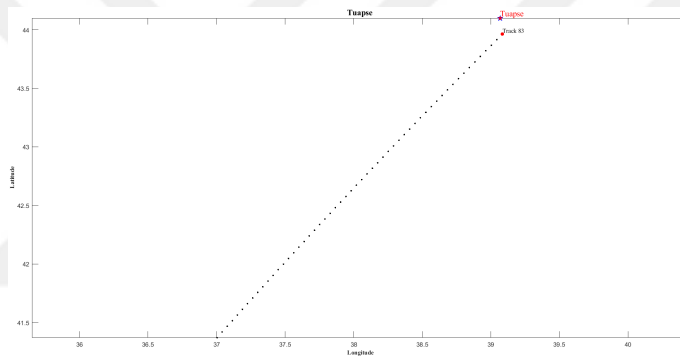


Figure H.17 : Nearest track points (red points) of T/P-J1-J2 No.83 from Tuapse station

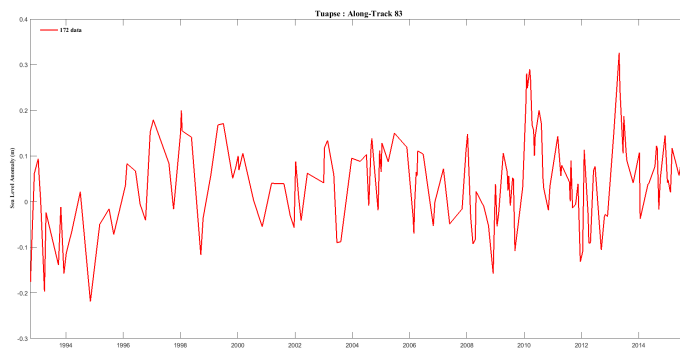


Figure H.18 : Nearest track points time series of T/P-J1-J2 No.83 (bottom) near to Tuapse

- SEVASTOPOL

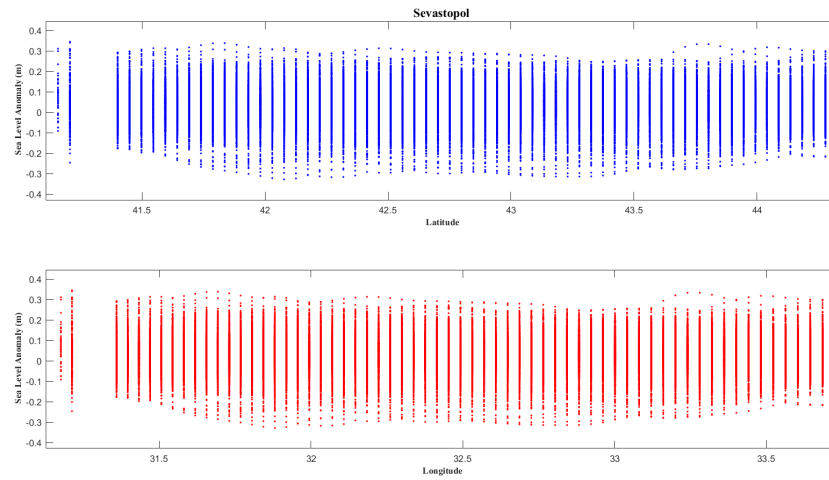


Figure H.19 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1-J2 No.185 along-tracks, passed near to Sevastopol

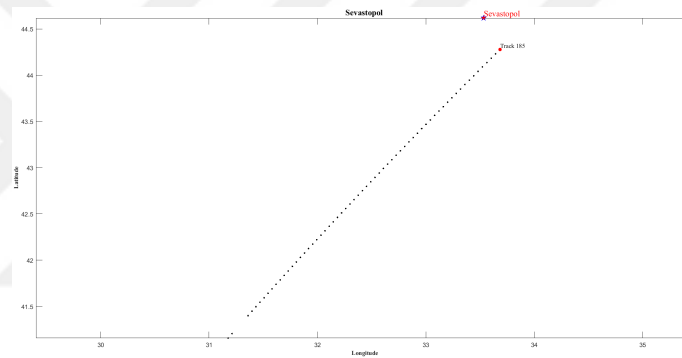


Figure H.20 : Nearest track points (red points) of T/P-J1-J2 No.185 from Sevastopol station

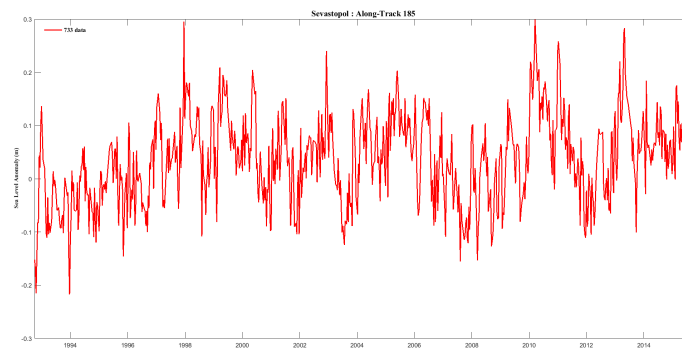


Figure H.21 : Nearest track points time series of T/P-J1-J2 No.185 (bottom) near to Sevastopol

• *CONSTANTZA*

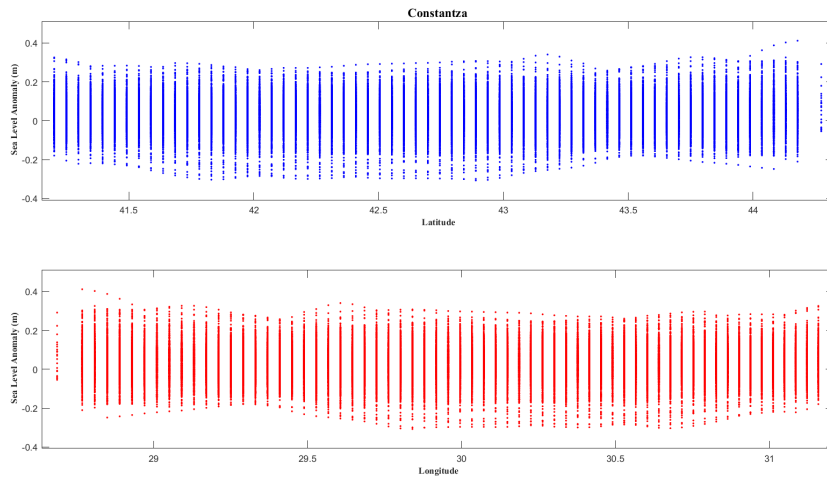


Figure H.22 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1-J2 No.68 along-tracks, passed near to Constantza

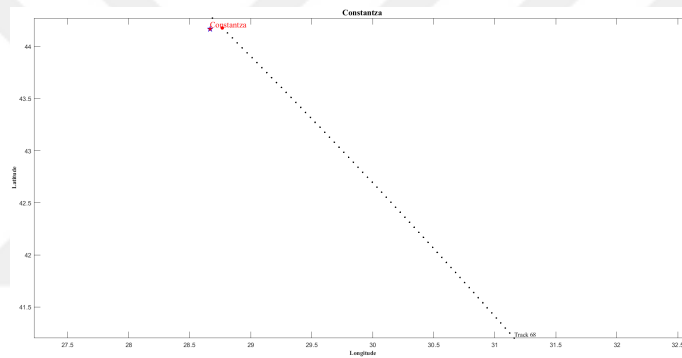


Figure H.23 : Nearest track points (red points) of T/P-J1-J2 No.68 from Constantza station

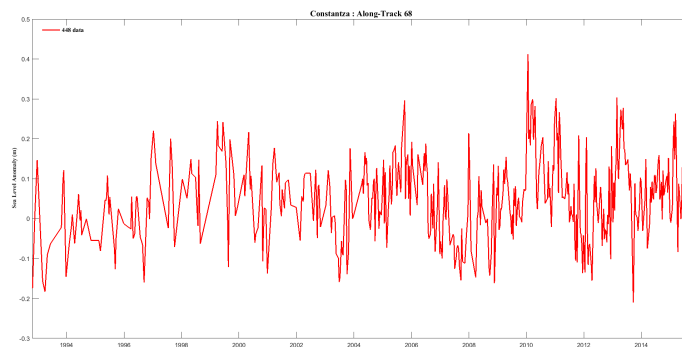


Figure H.24 : Nearest track points time series of T/P-J1-J2 No.68 (bottom) near to Constantza

- VARNA

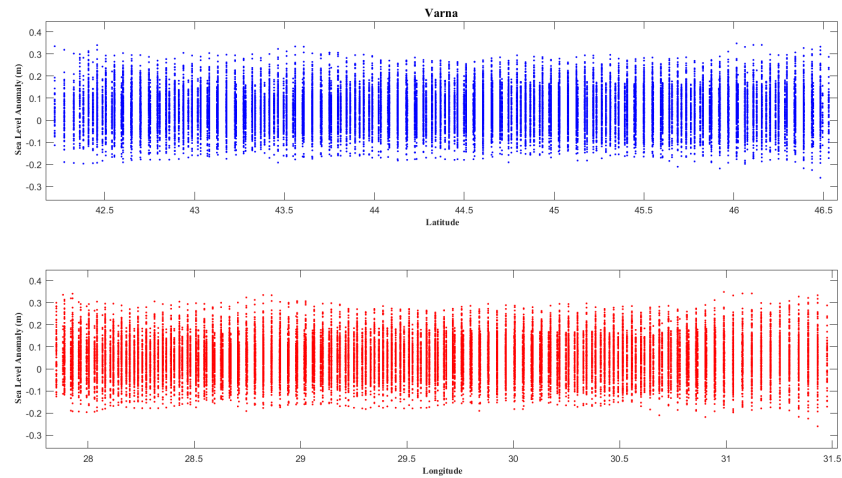


Figure H.25 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1 interlaced No.109 and GFO No.388 along-tracks, passed near to Varna

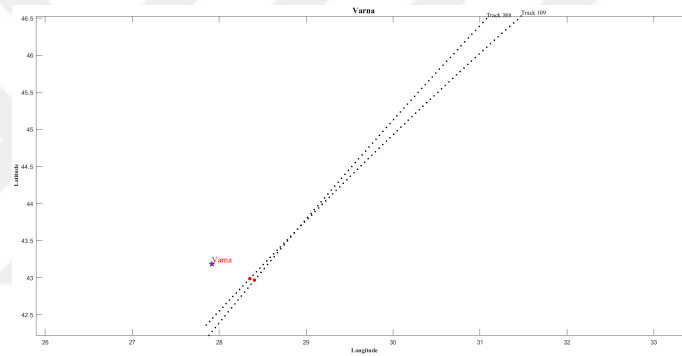


Figure H.26 : Nearest track points (red points) of T/P-J1 interlaced No.109 and GFO No.388 from Varna station

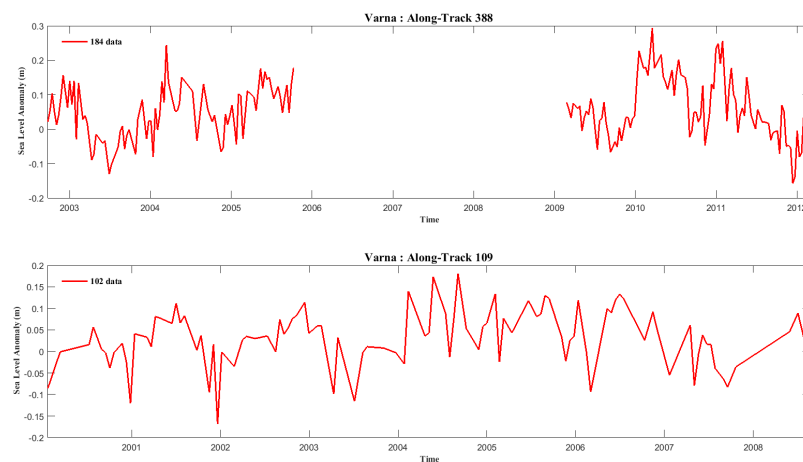


Figure H.27 : Nearest track points time series of GFO No.388 (top) and T/P-J1 interlaced No.109 (bottom) near to Varna

• *BOURGAS*

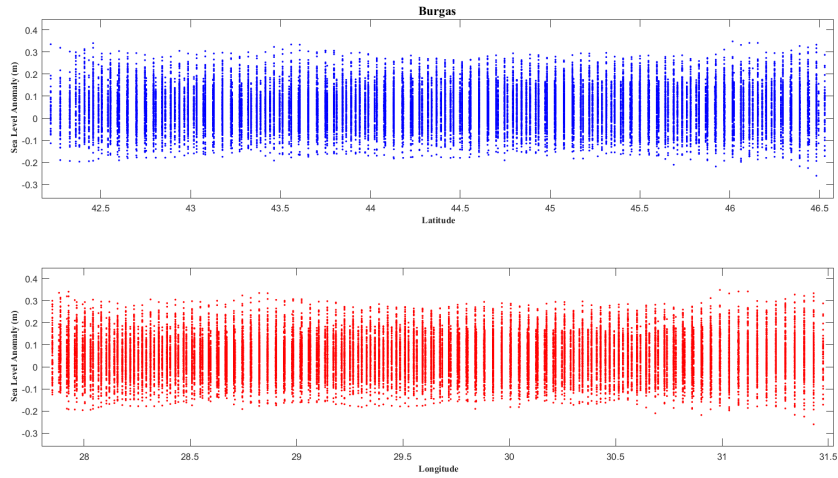


Figure H.28 : Latitude-SLA (top) and Longitude-SLA (bottom) graphs of T/P-J1 interlaced No.109 and GFO No.388 along-tracks, passed near to Bourgas

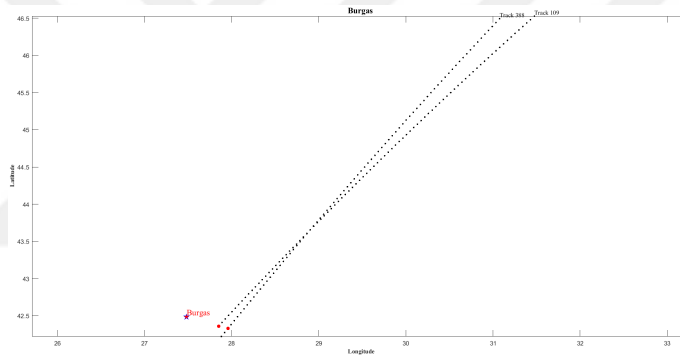


Figure H.29 : Nearest track points (red points) of T/P-J1 interlaced No.109 and GFO No.388 from Bourgas station

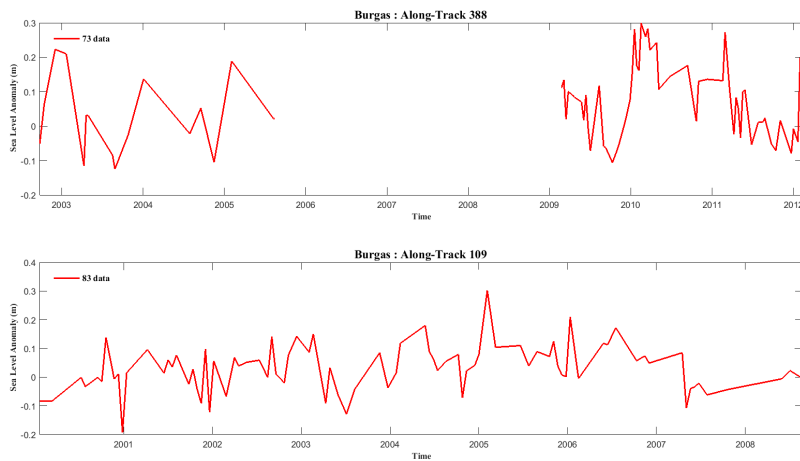


Figure H.30 : Nearest track points time series of GFO No.388 (top) and T/P-J1 interlaced No.109 (bottom) near to Bourgas

APPENDIX I

- *IGNEADA*

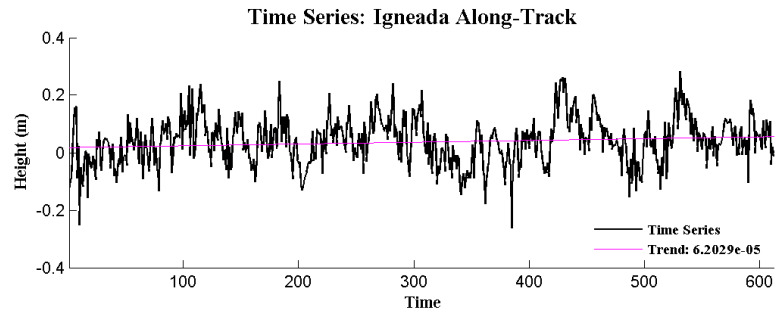


Figure I.1 : Extracted time series from along-track for Igneada

Table I.1 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Igneada

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	6.203E-05	1.868E-05		
$\sphericalangle S_{sa}$	0.00714	0.00466	222.111	0.267
$\sphericalangle S_a$	0.00963	0.00467	289.472	0.266

- *AMASRA*

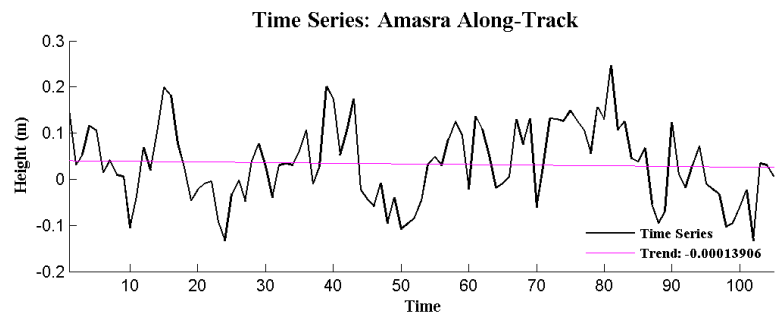


Figure I.2 : Extracted time series from along-track for Amasra

Table I.2 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Amasra

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	-0.000139	0.0002665		
$\sphericalangle S_{sa}$	0.02939	0.01030	53.370	0.600
$\sphericalangle S_a$	0.04614	0.01053	30.621	0.604

• *TRABZON*

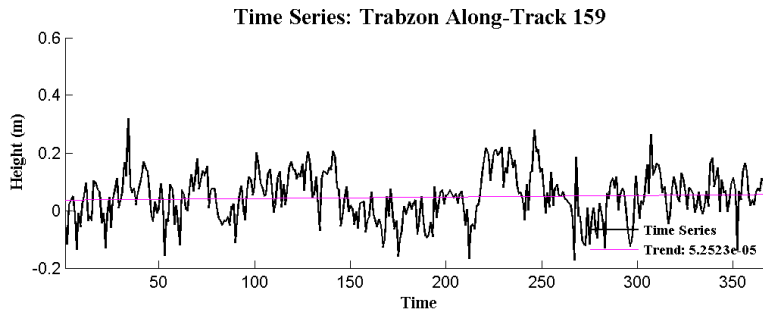


Figure I.3 : Extracted time series from along-track for Trabzon

Table I.3 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Trabzon

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	5.25E-05	4.08E-05		
$\simeq S_{sa}$	0.01580	0.00609	331.689	0.349
$\simeq S_a$	0.01239	0.00609	347.492	0.350

• *POTI*

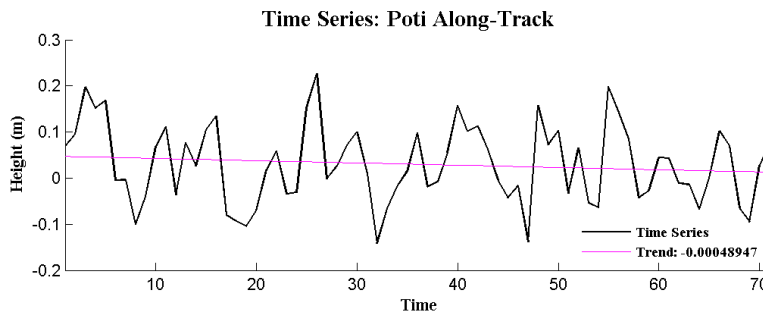


Figure I.4 : Extracted time series from along-track for Poti

Table I.4 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Poti

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	-0.00049	0.000494		
$\simeq S_{sa}$	0.02590	0.01457	132.467	0.819
$\simeq S_a$	0.00837	0.01418	69.830	0.851

- *TUAPSE*

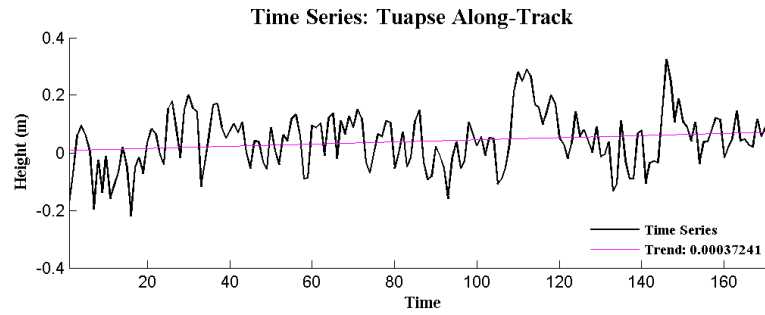


Figure I.5 : Extracted time series from along-track for Tuapse

Table I.5 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Tuapse

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	0.000372	0.000147		
$\simeq S_{sa}$	0.02241	0.00987	87.323	0.562
$\simeq S_a$	0.04025	0.00984	6.214	0.569

- *SEVASTOPOL*

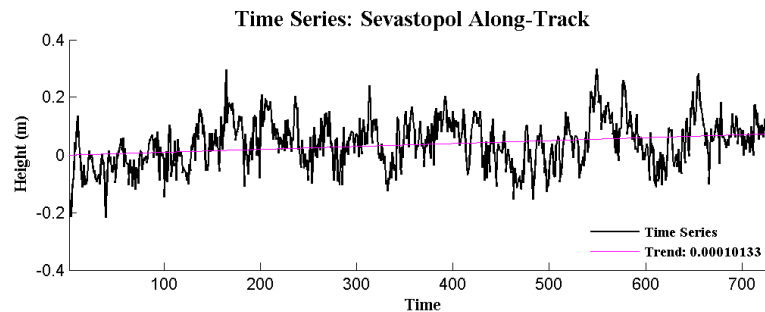


Figure I.6 : Extracted time series from along-track for Sevastopol

Table I.6 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Sevastopol

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	0.000101	1.41E-05		
$\simeq S_{sa}$	0.00939	0.00420	161.205	0.240
$\simeq S_a$	0.00929	0.00419	212.018	0.241

• *CONSTANTZA*

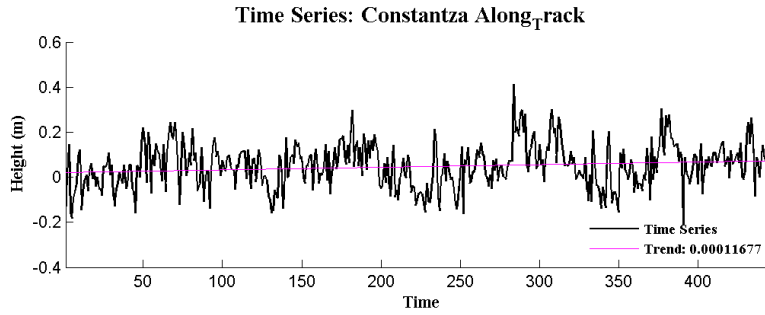


Figure I.7 : Extracted time series from along-track for Constantza

Table I.7 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Constantza

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	0.000117	3.55E-05		
$\simeq S_{sa}$	0.01095	0.00651	354.889	0.372
$\simeq S_a$	0.00267	0.00654	301.432	0.371

• *VARNA*

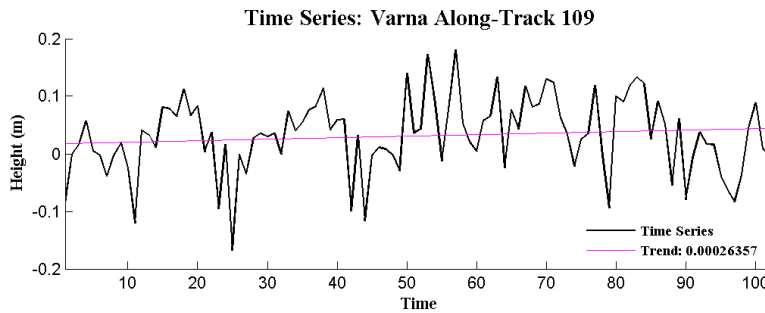


Figure I.8 : Extracted time series from along-track for Varna

Table I.8 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Varna

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	0.000264	0.000219		
$\simeq S_{sa}$	0.03480	0.00877	319.923	0.489
$\simeq S_a$	0.00727	0.00886	357.939	0.499

- *BOURGAS*

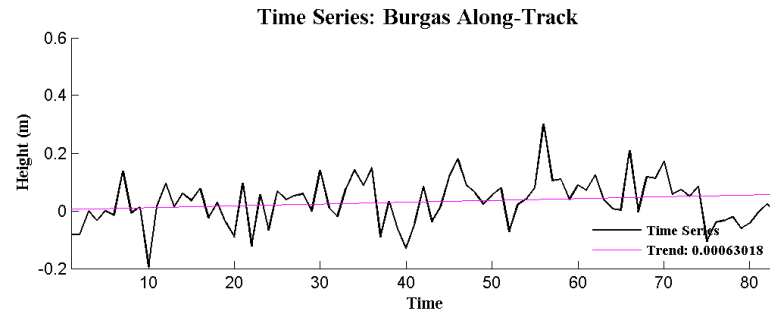


Figure I.9 : Extracted time series from along-track for Bourgas

Table I.9 : Calculated semiannual and annual tidal constituents using LSSA for along-track altimetry data of Bourgas

	Amp.(m)	sigma(m)	Phase(deg)	sigma(deg)
Trend (m)	0.00063	0.000371		
$\simeq S_{sa}$	0.02766	0.01223	274.786	0.690
$\simeq S_a$	0.02801	0.01184	241.878	0.732



APPENDIX J

- *IGNEADA*

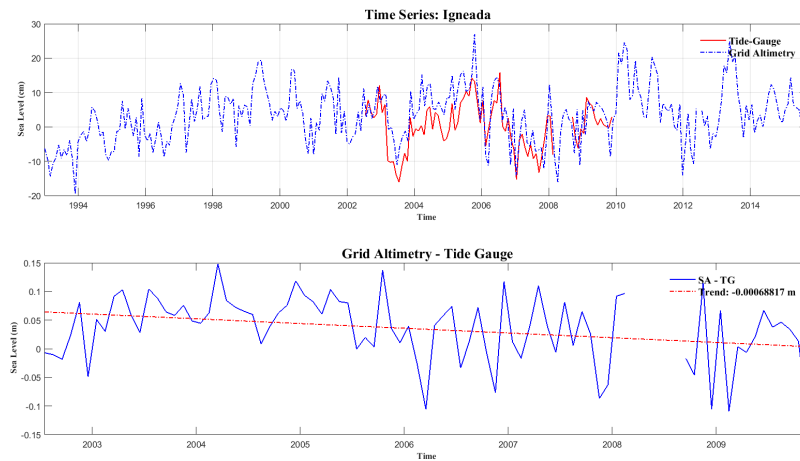


Figure J.1 : Difference between grid altimetry-tide gauge data (top) and its trend for Igneada

- *AMASRA*

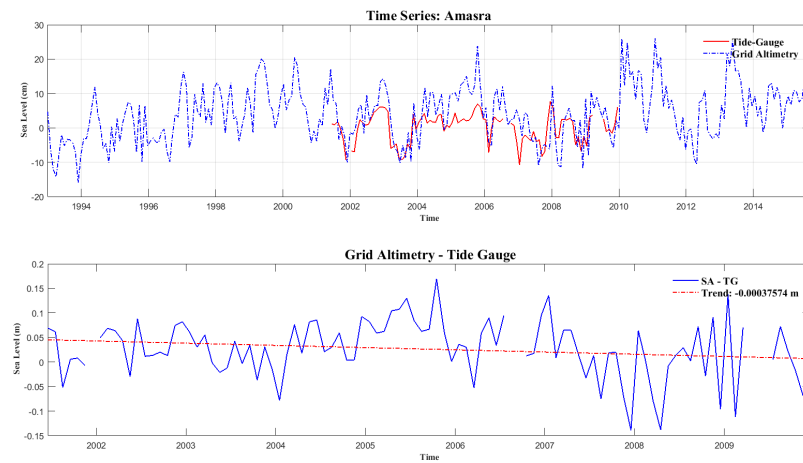


Figure J.2 : Difference between grid altimetry-tide gauge data (top) and its trend for Amasra

- *TRABZON*

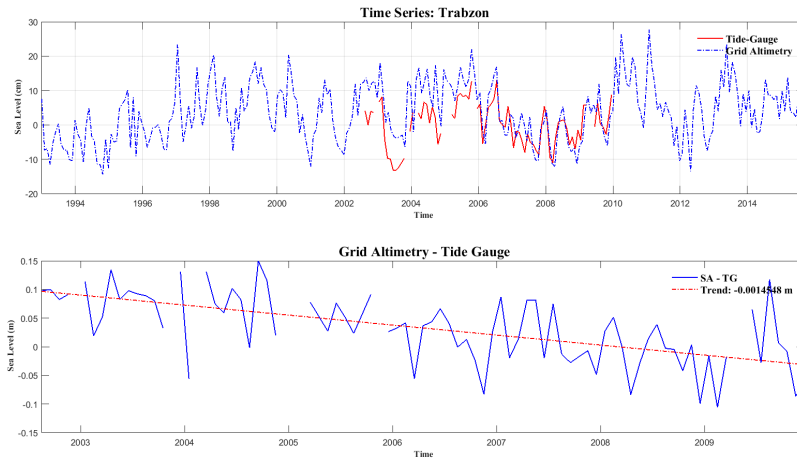


Figure J.3 : Difference between grid altimetry-tide gauge data (top) and its trend for Trabzon

- *BATUMI*

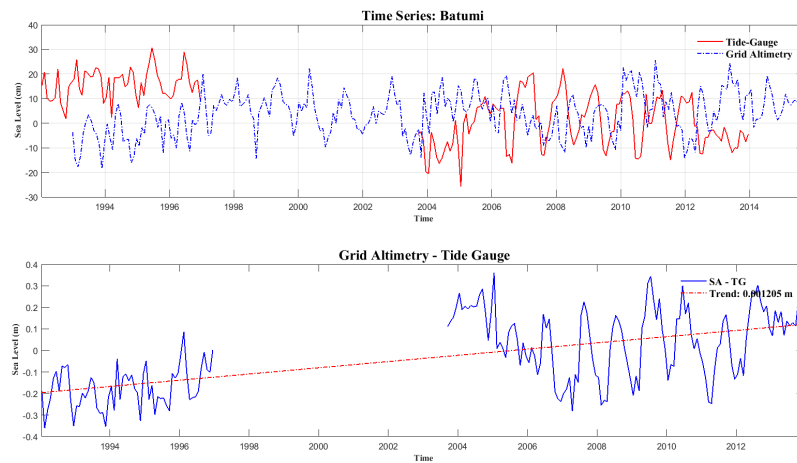


Figure J.4 : Difference between grid altimetry-tide gauge data (top) and its trend for Batumi

- *POTI*

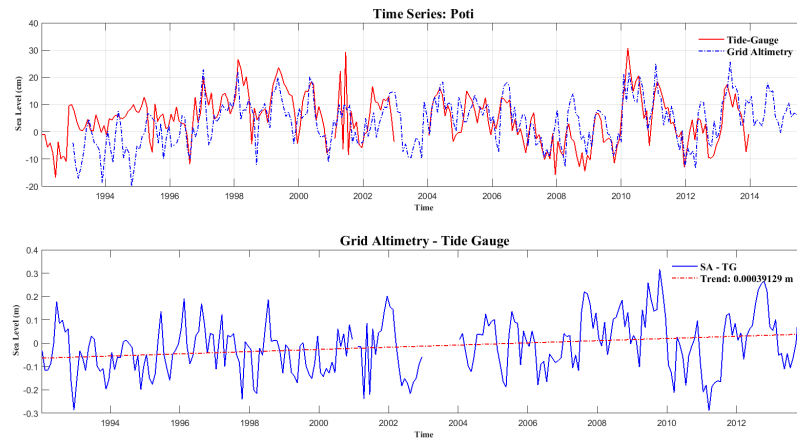


Figure J.5 : Difference between grid altimetry-tide gauge data (top) and its trend for Poti

- *TUAPSE*

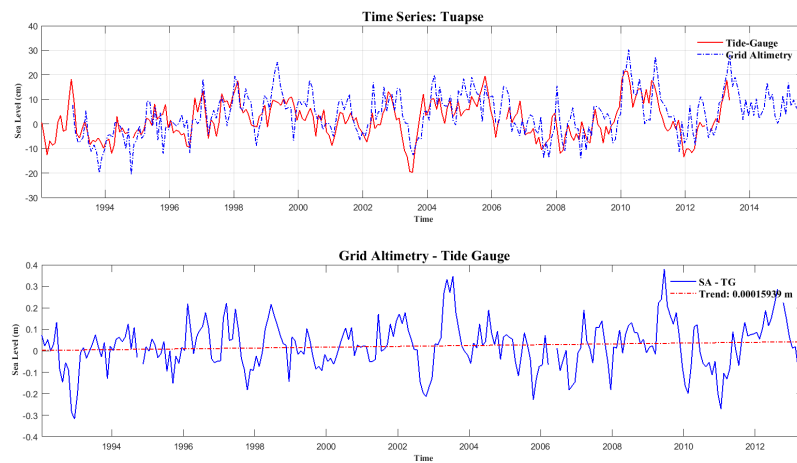


Figure J.6 : Difference between grid altimetry-tide gauge data (top) and its trend for Tuapse



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- Feizabadi M., Ince E.S., Erol B. 2015. Investigation on spectral methods for tide-gauge data analyses. IAG Symposia, G08 Sea Level Observation and Modelling, 26th IUGG General Assembly Prague, 22 Jun – 2 Jul 2015.
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