VENDOR LOCATION PROBLEM

A THESIS SUBMITTED TO THE DEPARTMENT OF INDUSTRIAL ENGINEERING AND THE INSTITUTE OF ENGINEERING AND SCIENCE OF BILKENT UNIVERSITY IN PARTIAL FULFILLMENT OF THE REQUIREMENTS FOR THE DEGREE OF MASTER OF SCIENCE

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ABSTRACT VENDOR LOCATION PROBLEM

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In this study, we aim to design a distribution system with the following components: the location of vendors, the number of vendors, the service region of the vendors, the number of vehicles and workers, and the assignment of demand points to these vendors and vehicles. We define our problem as a two-level capacitated discrete facility location problem with minimum profit constraints and call it *Vendor Location Problem*. In order to formulate the problem, two different objective functions are used: vendors's profit maximization and maximization of the demand covered. Integer linear programs for these two versions of the problem are formulated. Valid inequalities are used to strengthen the upper bounds. Finally, the performance of these models with different parameters are compared in terms of linear programming relaxation gap, optimality gap, CPU time, and the number of opened nodes for four different types of instances: instances with demand and profit which are independent of distance; profit function of distance; demand function of distance; demand and profit function of distance.

Keywords: Vendor location, two-level capacitated facility location problem, distribution system, minimum profit constraint, valid inequalities.

ÖZET BAYİ YER SEÇİMİ PROBLEMİ

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Bu tez çalışması; bir firmanın bayileri için yer seçimi, bayi sayısı, bayi çalışan ve araç sayıları ile müşterilerin bayilere ve araçlara atanması kararlarını içeren bir dağıtım sistemi tasarımını amaçlamıştır. Problem literatürdeki iki aşamalı ve kapasiteli kesikli tesis yerleşim problemi olarak tanımlanmış ve *Bayi Yer Seçimi Problemi* olarak adlandırılmıştır. Bayi karını ve servis edilen talebi enbüyültmek olmak üzere iki farklı amaç fonksiyonu tanımlanmış ve bu iki problem için doğrusal tamsayı programları sunulmuştur. Geçerli eşitsizlikler eklenerek problemlerin üst limitleri düşürülmüş ve problemler çözümlenmiştir. Ayrıca, sayısal deneyler için dört farklı örnek grubu oluşturulmuştur: uzaklıktan bağımsız kar ve talep fonksiyonlarını; uzaklığa bağlı kar fonksiyonunu; uzaklığa bağlı talep fonksiyonunu; uzaklığa bağlı kar ve talep fonksiyonlarını içeren örnekler. Modeller oluşturulan örnek gruplarında parametreleri değiştirilerek doğrusal gevşetme farkı, eniyilik farkı, CPU süresi ve açılan düğüm sayısı bakımından karsılaştırılmıştır.

Anahtar sözcükler: Bayi yer seçimi, iki aşamalı kapasiteli tesis yerleşim problemi, dağıtım sistemi, minimum kar kısıtı, geçerli eşitsizlikler.

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Contents

1	INT	TRODUCTION	1
	1.1	Motivation	2
	1.2	Problem Definition	3
	1.3	Contribution	4
	1.4	Contents	5
2	VE	NDOR SYSTEM IN TURKEY	6
	2.1	LPG Company	6
	2.2	Demijohn Water Company	8
3	LIT	ERATURE SURVEY	11
4	MC	DEL DEVELOPMENT AND COMPLEXITY	19
	4.1	Notation and Parameters	19
	4.2	Decision Variables	20
	4.3	Objective Functions	20

CONTENTS

	4.4	Constraints	21
	4.5	Complexity	23
5	VA	LID INEQUALITIES	24
	5.1	Lower bounds on the number of vehicles $\ldots \ldots \ldots \ldots \ldots$	24
	5.2	Cover inequalities for vehicle capacity constraints $\ldots \ldots \ldots$	26
	5.3	Cover inequalities for the minimum profit constraints $\ldots \ldots \ldots$	27
6	CO	MPUTATIONAL RESULTS	29
	6.1	Models	29
	6.2	Input Data and Parameter Selection	32
	6.3	Comparison of Models	34
	6.4	Solution Analysis of an Instance	38
7	CO	NCLUSION	43
\mathbf{A}	Tab	les of Computational Results	47

List of Figures

1.1	The Distribution System	3
6.1	q_{ij} function in terms of distance	33
6.2	Comparison of average cpu times for <i>ProfitVLP</i>	37
6.3	Comparison of average cpu times for $CoverageLP$	38
6.4	The solution of $PM2$ for $ProfitVLP$ type A problem	39
6.5	The solution of $PM3$ for $ProfitVLP$ type D problem	40
6.6	The solution of $CM4$ for $CoverageVLP$ type A problem	41
6.7	The solution of $CM2$ for $CoverageVLP$ type D problem	42

List of Tables

6.1	Constraints for model <i>ProfitVLP</i>	31
6.2	Constraints for model <i>CoverageVLP</i>	31
A.1	LP gap, CPU time/ optimality gap and number of nodes of $ProfitVLP$ in A type instances $\ldots \ldots	48
A.2	LP gap, CPU time/ optimality gap and number of nodes of <i>Prof-</i> itVLP in B type instances	49
A.3	LP gap, CPU time/ optimality gap and number of nodes of <i>Prof-</i> itVLP in C type instances	50
A.4	LP gap, CPU time/ optimality gap and number of nodes of <i>Prof-</i> itVLP in D type instances	51
A.5	LP gap, CPU time/ optimality gap and number of nodes of Cov - erage VLP in A type instances	52
A.6	LP gap, CPU time/ optimality gap and number of nodes of Cov - erage VLP in B type instances	53
A.7	LP gap, CPU time/ optimality gap and number of nodes of Cov - erage VLP in \mathbf{C} type instances	54

A.8	LP gap, CPU time/ optimality gap and number of nodes of Cov -	
	$erageVLP$ in D type instances \ldots \ldots \ldots \ldots \ldots	55

Chapter 1

INTRODUCTION

Recently, the importance of customer satisfaction has increased dramatically for the firms in the service sector. One of the key factor that has a big impact on customer satisfaction is the service time. Therefore, these firms pay more attention to production, logistics, and distribution management to create a competitive advantage over their competitors. Hence, vendor location decisions become an important component as a management concept that affect the service time excessively. Moreover, the design of distribution system is typically a costly and time-sensitive project. The main factors to be determined before locating facilities are the area of the location, the number of facilities, and capacity specifications.

In this thesis, we aim to design the distribution system for firms, which sell their products through vendors. This system design problem includes the decision on the location of their vendors, the service region of each vendor, the number of vehicles and workers for each vendor, and the assignments of customers to these vendors and vehicles. Customer/ demand point and facility/ vendor are used interchangeably hereafter.

1.1 Motivation

We consider a discrete facility location problem encountered by one of the major demijohn water sellers in Ankara. A few years ago, the company decided to introduce its own brand and wanted to locate a number of vendors and to determine disjoint sales regions for its vendors in a way that each vendor can achieve at least a minimum level of profit.

The sales of demijohn water works on a kind of membership of customers. Every brand has its own bottles. A customer who wants to buy the product of a given brand is charged for the first bottle. After the first purchase, the empty bottle is changed with a full bottle, and the customer is only charged as much as the price of the water. This discourages customers from switching frequently from a brand to another.

Before the company introduced its product, a detailed market analysis has been conducted to determine the criteria that the customers use in deciding which brand to buy and to forecast the demand for the new product. It has been observed that the customers valued the most, the quality of the water (taste, hygiene, chemical composition etc.) and the quality of the service. The quality of the service was strongly related to service times and the satisfaction was affected by the presence of competitors in the same region who could provide shorter service times.

It was concluded that the number of customers that the company could attract from a given region depended highly on the distance between the region and the vendor to which this region would be assigned to and the distances between the region and the vendors of competitor brands. Hence opening vendors at many locations could increase the market share of the company. However this could result in vendors with insufficient sales to achieve at least a minimum level of profit.

The distribution system of the company is depicted in Figure 1.1.

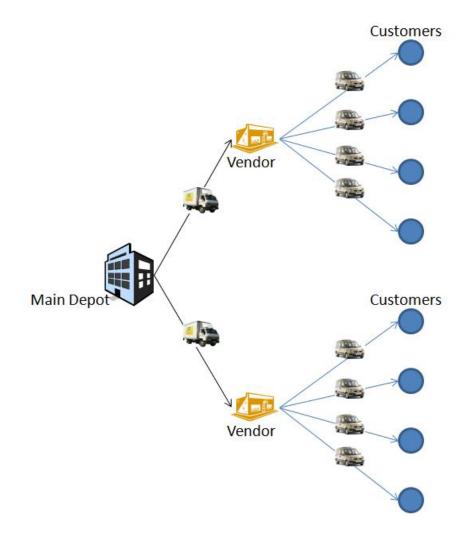


Figure 1.1: The Distribution System

1.2 Problem Definition

We aim to establish a distribution system for companies by deciding where to locate their vendors, the number of vehicles for each vendor as well as the assignment of customers to these vendors and vehicles.

We define the Vendor Location Problem (VLP) as follows. We are given a set of demand points which correspond to population zones and a set of possible locations for vendors. For each vendor, there is a maximum number of vehicles that this vendor can use. We are given the fixed cost of operating a vendor office (rent, insurance, salaries of employees at office etc.) at a given location and the

cost (including the salary of the driver) and capacity of a vehicle.

For a given demand point, there is a set of eligible vendors that can serve this demand point. Demands of demand points change according to the proximity to vendors and also the proximity of other brands' vendors in the region. Hence, the demand and the profit (sales revenue minus the transportation cost) a demand point generates depends on the vendor that serves it.

Now, the *VLP* is to locate a given number of vendors and to assign each demand point to at most one vehicle of an eligible vendor such that capacities of vehicles are not exceeded and each vendor achieves a minimum level of profit. We consider two objective functions. In *ProfitVLP*, the aim is to maximize the total profit and in *CoverageVLP*, the aim is to maximize the coverage, i.e., the total demand served.

1.3 Contribution

In this study, we introduce two new two-level facility location problems, namely ProfitVLP and CoverageVLP, that are motivated by a real life problem. Different from the classical facility location problems, here we have minimum profit constraints for open facilities and capacity constraints for their vehicles. We investigate the computational complexity of these problems and prove that they are strongly NP-hard. We propose integer programming formulations, valid inequalities and extra constraints to be able to use the cutting planes of off-the-shelf integer programming solvers. We report the outcomes of a computational study where we used four types of instances which differ in their demand and profit functions. We investigate the effect of valid inequalities on linear programming relaxation bounds and solution times for these different types of instances. Finally, we analyze the optimal solutions of ProfitVLP and CoverageVLP and report how the differences in demand and profit functions effect the locations of facilities and their service regions for an example problem.

1.4 Contents

The remainder of the thesis is organized as follows:

In Chapter 2, we give information on two companies that use vendors for sales.

In Chapter 3, we provide a review of the literature in facility location problems by comparing our problem with these problems.

In Chapter 4, we formally define our problem and then propose an integer linear program to solve the problem exactly.

In Chapter 5, we derive some valid inequalities to strengthen the models presented in Chapter 4.

In Chapter 6, we will present four types of instances. Experimental results related with valid inequalities are given and discussed by comparing the models with each other.

In Chapter 7, we conclude the thesis by giving an overall summary of our contribution to the existing literature and list some possible future research directions.

Chapter 2

VENDOR SYSTEM IN TURKEY

We have interviewed two different firms which sell their products through vendors. The first company is in LPG (Liquefied Petroleum Gas) cylinder market in Turkey. The other one is a beverage company, who produces 19 L HOD-Demijohn water. Since we are not allowed to use their brand names, we call them as Company X and Y, respectively. In the following two sections, we give some general information about these companies and their vendor systems.

2.1 LPG Company

LPG cylinder companies sell their products through vendors. Distribution network is the most important issue to attract customers and meet customer satisfaction for this kind of companies.

The distribution network is composed of filling facilities and vendors. Vendors prefer managing the logistics by their own, although Company X provides free logistics. The reason behind it is that vendors want to order the products in the specified amount and time based on their needs rather than the fixed amount and time the distribution centers determine. The vendors close to the filling facilities do not tend to keep inventory.

The distribution of the products to the customers depends on the type of customer. Customers of Company X can be categorized into three segments as individual subscribers, corporate customers, and the customers of secondary vendors. Individual and corporate customers make a phone call to make an order and the vendors bring their products via their own vehicles to replace the empty LPG cylinders with full ones. However, secondary vendors meet the demand of people in villages or suburbs without taking any order. Besides, in suburbs, the vehicles go around with the company's jingle to capture the consumer.

To locate the vendors, Company X does not take into account the distance between vendors. Therefore, customers sometimes complain about the imbalance of delivery time of each vendor. Since they have no region division for the vendors, customers are free to choose their own vendors. Sometimes, this leads to long delivery times and high transportation costs.

The most important factor affecting the delivery time is the number of vehicles. The number of vehicles each vendor has is not determined by company X and it changes from region to region. As vendors patronize more customers, the need for an extra vehicle occurs. Vendors assign one more vehicle as a result of increase in the complaints from customers about the delivery time. The aim of Company X is to minimize the number of vehicles without decreasing the service quality.

The customers mainly make their decisions for which brand to choose according to three criteria: reliability that comes from the name of the brand, price, and delivery time. The aim of the company is to keep the lead time of delivery of products below half an hour, but it changes between 20 and 60 minutes due to the reasons mentioned above.

If a vendor cannot compensate its costs and make enough profit due to decrease in demand, then it has to be merged with one of the neighboring vendors. It may happen that Company X locates its vendors in the same area and this may create serious risk in terms of vendor's profitability and customer satisfaction. This can cause a vendor to be out of business since it is not possible to cover the costs. In 2008, seven vendors closed their businesses, and three vendors were merged to compensate the costs.

2.2 Demijohn Water Company

One of the most proper example for selling products through vendors is demijohn water companies. In Turkey, there are more than 400 brands in the demijohn sector. To understand the vendor system, we interviewed one of these brands, which we call Company Y.

The distribution network of Company Y has distribution centers in cities who supply demijohns for vendors. There are two distribution centers in Ankara: the east region distribution center and the west region distribution center. Each of these centers provides supply to 17 vendors. The separation is based on the amount of demand and region.

These distribution centers order demijohn waters to the company once a day. The delivery time for demijohns for reaching the distribution centers from the factory is 24 hours. Vendors give their orders to the distribution centers at the end of the working day to have the products at the beginning of the next day. Generally, the distribution center is responsible for logistics of the demijohns to the vendors, unless the vendor is willing to receive from the stock warehouse thanks to the proximity. The west distribution center has 4 trucks with capacities 100, 300, 450, and 700 demijohns. Most of the time, one trip per truck per day is enough, if necessary they assign the trucks for a second trip through a day, starting with the smallest truck. Distribution centers have the safety stock which is enough for a daily demand. The sale of a distribution center is 2300- 2500 demijohns per day on the average. It can change in the range of 10% and 15%.

Vendors are responsible to deliver products to customers via their own vehicles. The process of receiving an order from a customer starts when the customer calls the responsible vendor to leave a message of his/her request to the vendor's computer. Then, the request is directed to the deliveryman who is responsible for that region. The deliveryman brings the full bottle to the customer's adress and takes the empty bottle to take it back to the vendor.

The service regions of the vendors are strictly separated from each other and the vendors are prohibited to serve in an other vendor's district. Company decides about the vendor locations with respect to the demands of the regions. First, they choose elite districts to serve and then they decide about the remaining regions.

Moreover, the region of the each vendor's vehicles is also determined and even if the delivery takes less time, customers of a deliveryman cannot be served by another deliveryman working for the same vendor. To shorten the delivery time and to minimize the transportation cost, vehicles assigned to each part of the vendor's region have specific points to wait in their service area. They are not allowed to return back to their vendors during the day before finishing all demijohns loaded on their vehicles.

Another important issue is to decide about the number of vehicles since it affects the delivery time. In the demijohn water sector, each vendor has a different number of vehicles. Regarding that shipping 50-60 demijohns in a day is ideal and more than 80-90 can be shipped by a vehicle, the vendor starts with a vehicle at first. As the vendor patronizes more customers, they augment the number of vehicles in order to have acceptable delivery time.

One of the distribution centers of Company Y has vendors with 1 to 6 vehicles that can be loaded 3 times and accomplish at most 3 tours in a day. The average number of vendor's vehicles is 3. If a vendor cannot afford to buy more vehicles and demand cannot be met within reasonable service times, the need for an extra vendor in that region occurs. This is called "vendor split". Each vendor has to compensate its cost and to continue his business. If a customer is far from the other customers of the vendor, advertisements or promotions are applied to capture more customers at that region to cover the costs. The vendor does not accept the demand if there is still not enough demand in that direction to compensate its own cost.

Although the number of vehicles and delivery times are crucial for vendors to attract the customers, Company Y does not control vendors in terms of delivery time, unless customers deliver a complaint to the company. However, the sales of vendors are inspected and necessary precautions are taken if any loss occurs. In addition to this, Company Y follows the shifts to other brands and tries to get information which other brands customers prefer to Company Y.

Apart from the delivery time, the reasons customers choose the specific brand of demijohn water are reliability of the brand, price, taste, and some emotional factors. For example, the deliveryman has an affect on the process of deciding the demijohn water to buy. They are strictly prohibited to enter customer's house and must be neat. Moreover, customers in Turkey are not tightly coupled with a brand. The regions with well-educated customers have steady sales. However, the demand of less-educated customers is more sensitive due to promotions, free-ofcharge exchange demijohns or campaigns. The importance given to price differs according to region.

Chapter 3

LITERATURE SURVEY

There is a wide variety of location problems in the literature. Generally, distribution, transportation and telecommunication are the most important areas for facility location problems. The need for locating facilities arises both in private and public sector. In private sector, industrial firms, retail facilities or banks have to locate their facilities and for the latter one, government agencies decide on the location of schools, hospitals, fire stations, and ambulances.

Location Problems were first introduced in 1909 by Alfred Weber [19] who studied the problem of locating a warehouse in the plane on which the customers are spatially distributed with the objective of minimizing the total walking distance of customers to the facility. More realistic models and algorithms were introduced in the mid-1960s.

Facility Location Problems can be classified regarding various criteria. Klose and Drexl [14] classified facility location problems using the following criteria:

1. The space of location designs

Location problems are divided into two groups according to the space of d-dimensional real space and network location space. Both two groups are subdivided into continuous and discrete location problems. In location problems with continuous space, facilities can be located anywhere in the space or on the network. However, facilities are sited at the points in a finite set in discrete location problems.

ReVelle and Eiselt [15] stated in their survey that distances in real spaces are often calculated using metric Minkowski distances. The most focused distance types are Rectilinear distances, Euclidean metric and Chebyshev metric.

In network location problems, shorthest path is the method for calculating the distance between nodes which presented by Dijkstra [9].

Our problem is a discrete location problem in 2-dimensional real space and we use Euclidean metric to compute the distances between facilities and customers.

2. Classes of location objectives

Eiselt and Laporte [10] examined different objective functions for location models. They categorized objective functions into three groups: pull, push and balance objectives. First, if the aim is to locate facilites close to the customers, it is a pull objective. Minisum, maximum capture, minimax and covering problems are the major classes of problems of pull objectives. When the aim is to maximize sales, revenue and customers captured, maximum capture objectives arise. If the issue is to minimize the maximum distance, minimax objectives are used. Max cover and min (cost) cover problems are the two version of covering objectives. In max cover problems, the idea is that facilities are located to maximize the demand captured with a fixed number of facilities. Min (cost) cover problems aim to cover the whole demand with a variable number of facilities by satisfying the distance constraint.

Push objectives aims to locate undesirable facilities. Finally, balance objectives try to balance distances between facilities and customers, i.e., minimize the variability of the distribution of distances.

Generally, public sector aims to increase the accessibility of facilities e.g., minimizing the maximum distance between facilities and customers. However, private sector chooses to maximize profits or minimize cost. We define two objective functions including both two groups for our problem: maximizing profit and maximizing coverage.

3. Product type

Problems can include single-product or multi-product. In single-product models, there is a homogeneous product which does not differ in terms of cost, quality, capacity or demand attributes. All products are homogeneous in our problem.

4. Demand type

In location problems, demand can be classified as elastic and inelastic demand. In inelastic demand, spatial decision does not influence demand. On the contrary, if demand is elastic, it may change according to proximity. Elastic demand is usually a component of competitive facility location problems.

In Competitive location, private sectors' organizations struggle to be close to the customers in order to attract them to their retailers. Characteristics of this problem are various and one of the important component is objective function which is generally based on the utility function. Aboolian et al. [2] suggested a spatial interaction model with multiple facilities, elastic concave demand and multiple design characteristics for competitive location problem. They solved the model for a real life example to locate a set of retail facilities in Toronto, Canada. They used Tangent- Line Approximation (TLA) by adopting the piecewise linear function to linearize the nonlinear concave model for medium-size instances. They also developed an ascent heuristic for larger problems.

Berman and Drezner [4] studied the multiple facility location problem on a network. They define stochastic demand function as distance dependent, that is to say, it decreases as distance increases. Their objective function is to maximize the demand. They developed heuristic algorithms that are ascent algorithm, tabu search and simulated annealing and concluded that the best approach is simulated annealing. We model both the demand and the profit as a function of distance. In contrast to these studies mentioned above, we model demand using a piecewise linear function.

5. Planning period and data type

In facility location problems, static and dynamic models are studied in the literature. Static models optimize the system for a time period. In dynamic models, multiple periods are considered, data varies over time and it is possible to relocate the system components in the given planning horizon. Our problem is a static location problem.

In terms of certainty, static models can be divided into deterministic and probabilistic models. Deterministic models ignore the uncertainty. However, probabilistic models' data is not known with certainty.

Brotcorne et al. [5] worked on ambulance location and relocation models. After they mentioned how the emergency services operate, they presented static and dynamic models for ambulance location problems. They concluded that fast heuristics and sufficient computing power make the dynamic models useful in real life. The Location Set Covering Model (LSCM) of Toregas et al. [18] aimed to minimize the number of ambulances so as to cover all demand points. The objective of Maximal covering location problem (MCLP) studied by Church and ReVelle [7] is to maximize coverage with limited resource available.

6. Routing

ReVelle and Laporte [16] presented Location Routing Problems considered as plant location problems with spatial interaction. These models simultaneously locate facilities and construct routes of delivery and/or collection. There are the Median Tour (MTP) and Covering Tour Problems (CTP), the Newspaper Delivery Problem (NDP) and Multiple Tour Plant Location Problems (MTLP) in this category. The Median Tour Problem introduced by Current and Schilling [8] is the extension of the Generalized Traveling Salesman Problem. Its objective is to minimize both the length of the Hamiltonian tour among facilities and the sum of radial distances between remaining sites and the closest facility. Current and Schilling [8] works on Covering Tour Problem which is a version of MTP. Mailbox location is the application of MTP and CTP.

In the Newspaper Delivery Problem, Jacobsen and Madsen [13] aimed to minimize the total length of all tours. Primary tours through a subset of sites and secondary tours associating sites to the primary tours are computed.

Finally, Multiple Tour Plant Location Problem corresponds the NDP, but there are no tours between facilities and there is a fixed charge for opening facilities.

Although our problem includes delivery/collection process, we cannot construct a route for vehicles as in the case of MTP, CTP, NDP and MTLP, since customer's order triggers the delivery/collection process.

7. Capacity constraints

If the model has no capacity constraints, it is called uncapacitated facility location problem (UFLP). If facilities have capacity constraints, then the problem is called capacitated facility location problem (CFLP).

Models with capacity constraints are separated into two groups: singlesource and multiple-source. In capacitated facility location problems with single-source, each customer has to be served by only one facility.

In the literature, one of the common way of solving CFLP is to use Lagrangian Heuristics. Holmberg et al. [12] suggested a Lagrangian Heuristic including a strong primal heuristic and a branch-and-bound for CFLP with single sourcing (SSCFLP). They use subgradient optimization in Lagrangian Heuristic and repeated matching in primal heuristic. To relax the set of constraints, they chose assignment constraints, so they worked on knapsack problems. They concluded that Primal heuristic with Lagrangian relaxation is a very efficient method since Lagrangian relaxation provides strong lower bounds and primal heuristic finds optimal or near optimal solutions quickly. In our problem, vehicles of vendors have capacity limits, so our problem is capacitated.

Albareda et al. [3] introduced a new problem called Capacity and Distance Constrained Plant Location Problem (CDCPLP) which is an extension of discrete capacitated plant location problem. They propose mathematical formulations and a solution technique for this problem. Their problem has the following properties:

- After customers are assigned to facilities, each customer is also assigned to a vehicle.
- There are plant capacities and upper bounds on the total distance traveled by each vehicle.
- Demands are not divisible.

They proposed alternative mathematical models that minimize the total cost: the fixed cost for opening plants, the vehicle utilization cost and the assignment cost. They add some inequalities to their first alternative to avoid symmetries that arise since vehicles are identical.

In the first model, they suggested a bilevel model that minimizes required the vehicles to satisfy the assigned customer demands by separating the problem to Bin Packing Problems.

Second, they proposed a relaxed model for CDCPLP to generate good lower bounds by changing the capacity constraints with surrogate aggregated capacity constraints and adding valid inequalities. They improve tabu search based heuristic with three levels of search: plant-level, assignment level and packing-level. The results show that tabu search heuristic provides optimal or near optimal solutions within reasonable computational times.

Our problem is related with CDCPLP in many points. VLP has similar properties mentioned above except the second item. In our problem, not facilities but vehicles have capacity limits and we do not set upper bounds on total distances traveled. Besides, we have an additional constraint which provides the minimum profit of each vendor. Although we have no constraint on total distance traveled, demands are decreasing as distance between vendors and demand points is increasing in VLP. Furthermore, we set a distance restriction for each vendor that is allowed to serve a customer.

8. Hierarchical stages

Hierarchical location problems occur in many areas such as health care, industrial and telecommunication network contexts. In industrial context, goods start to move from manufacturing plants to warehouses and from warehouses to demand points. Although supply chain concept comes up at this point, the difference between supply chain and location problems is that primary consideration is to focus on the design and secondary issue is operation in location problems like as in hierarchical location problems.

In hierarchical facility location problems, there are k levels representing the different type of facilites having interaction. Sahin and Süral [17] reviewed the hierarchical facility location problems. First, they focused on four attributes of this type of problems: flow-pattern, service varieties, spatial configuration and objective. According to these attributes, they mention the real life applications of hierarchical facility location problems such as healthcare system, solid waste management system, production-distribution system, education networks. They give mathematical formulations of these problems based on above attributes and solution methods.

Our problem can be seen as a hierarchial facility location problem where customers are level 0, vehicles are level 1 and vendors are level 2. According to the attributes they defined, our problem is single-flow, since a customer to be served by the highest-level facility goes to a level 1 first and then passes through level 2 which is a vendor. Moreover, our problem is nonnested in terms of service varieties, since facilities at each level offer different services. According to spatial configuration, our system is coherent, because each vehicle belongs to a vendor.

Another study about hierarchical facility location problem was conducted by Aardal et al. [1]. They studied the two-level uncapacitated facility location (TUFL) problem. After they improved for multi-commodity flow formulations of TUFL, they compared them with one-level uncapacitated facility location problem. They presented new families of facets and valid inequalities for TUFL. They discussed useful inequalities for computational purposes for alternative models they developed.

Moreover, Chardaire et al. [6] also studied hierarchical facility location problem. They presented upper and lower bounds for the two-level simple plant location problem. They characterized their problem for two-level concentrator access network in telecommunications industry. First, they introduce a simplified version of the two-level simple plant location problem. They assumed that there is no capacity constraint and all concentrators are of the same type. They developed an effective simulated annealing algorithm for this model to improve some of the upper bounds of Lagrangian relaxation algorithm. Then, they presented improved model formulation for the two-level simple plant location problem. Although both formulations' linear programming relaxation have the same optimal value, improved formulation was tightened using a family of polyhedral cuts that define facets of the convex hull of integer solutions.

Our formulations are an extension of the formulations presented in the two papers mentioned above. We have additional constraints which are capacity and minimum profit.

Chapter 4

MODEL DEVELOPMENT AND COMPLEXITY

In this chapter, we introduce the notation and then present formulations for our problem. Then we prove that both problems are strongly NP-hard.

4.1 Notation and Parameters

Let I be the set of demand points and J be the set of possible locations for vendors. For a demand point $i \in I$, J_i is the set of vendors that can serve i. In our problem, we define J_i to be the set of vendors whose travel time i does not exceed a given bound. We also define $I_j = \{i \in I : j \in J_i\}$ for $j \in J$.

We denote with f_j the fixed cost of the vendor office and with v_j the fixed cost of a vehicle for a vendor located at $j \in J$. We define ρ_{min} to be the minimum profit a vendor should achieve.

We denote with p the number of vendors to be located. The vendor at location $j \in J$ may have up to k_j^{max} vehicles. Let $K_j = \{1, \ldots, k_j^{max}\}$ for $j \in J$. The capacity of a vehicle is equal to γ .

Demand point $i \in I$ has demand q_{ij} and generates profit ρ_{ij} if it is served by the vendor at location $j \in J_i$.

4.2 Decision Variables

After defining the parameters, we introduce the decision variables used to formulate the problem. We define y variables to open facilities, z variables to indicate a purchase of a vehicle for facilities, and finally x variables to assign customers to facilities and vehicles.

 $\begin{aligned} x_{ijk} &:= \begin{cases} 1, & \text{if demand point } i \text{ is assigned to vehicle } k \text{ of vendor } j \\ 0, & o.w \end{aligned}$ $\forall i \in I, j \in J_i, k \in K_j$ $z_{jk} &:= \begin{cases} 1, & \text{if vendor } j \text{ uses vehicle } k \\ 0, & o.w \end{aligned}$ $\forall j \in J, k \in K_j$ $y_j &:= \begin{cases} 1, & \text{if a vendor is located at location } j \\ 0, & o.w \end{aligned}$ $\forall j \in J. \end{aligned}$

4.3 Objective Functions

We have two different objective functions. First one is:

$$\max \sum_{i \in I} \sum_{j \in J_i} \sum_{k \in K_j} \rho_{ij} x_{ijk} - \sum_{j \in J} \sum_{k \in K_j} v_j z_{jk} - \sum_{j \in J} f_j y_j$$

First objective function aims to maximize profit, which consists of three terms: the revenue of facilites after deducting the transportation cost between demand points and facilites, the fixed vehicle cost, and the fixed facility cost. Our second objective function which is to maximize the coverage of demand is the following:

$$\max \sum_{i \in I} \sum_{j \in J_i} \sum_{k \in K_j} q_{ij} x_{ijk}.$$

4.4 Constraints

Constraints of our model are as follows.

$$\sum_{j \in J_i} \sum_{k \in K_j} x_{ijk} \le 1 \qquad \forall i \in I$$
(4.1)

$$\sum_{j \in J} y_j = p \tag{4.2}$$

$$\sum_{k \in K_i} x_{ijk} \le y_j \qquad \forall i \in I, j \in J_i \tag{4.3}$$

$$\sum_{i \in I_j} q_{ij} x_{ijk} \le \gamma z_{jk} \qquad \forall j \in J, k \in K_j$$
(4.4)

$$\sum_{i \in I_j} \rho_{ij} \sum_{k \in K_j} x_{ijk} \ge \sum_{k \in K_j} v_j z_{jk} + (\rho_{min} + f_j) y_j \qquad \forall j \in J$$

$$(4.5)$$

$$x_{ijk} \in \{0,1\} \qquad \forall i \in I, j \in J_i, k \in K_j$$

$$(4.6)$$

$$z_{jk} \in \{0,1\} \qquad \forall j \in J, k \in K_j \tag{4.7}$$

$$y_j \in \{0,1\} \qquad \forall j \in J. \tag{4.8}$$

Constraints (4.1) ensure that a demand point is assigned to at most one vehicle of one eligible vendor. Constraint (4.2) states that the number of vendors to be located is p. If a vendor is not located at a given location, then a demand point cannot be served by any of its vehicles due to constraints (4.3). Constraints (4.4) are capacity constraints for vehicles. At the same time, they ensure that demand points are not assigned to vehicles which are not in use. Constraints (4.5) ensure that each vendor makes a profit of at least ρ_{min} units. Constraint (4.6), Constraint (4.7) and Constraint (4.8) are binary constraints for the variables x, y, z.

Moreover, there is the additional restriction that if a vendor is located at a given demand point, then the demand of this point should be served by itself. To handle this, we added the constraint

$$\sum_{k \in K_j} x_{jjk} = y_j \qquad \forall j \in J.$$
(4.9)

Since the vehicles are identical, there is symmetry in the set of feasible solutions and multiple representations for the same solution. To reduce this symmetry, following constraints can be added:

$$z_j = x_{jj1} \qquad \forall j \in J_i \tag{4.10}$$

$$x_{jj1} = y_{j1} \qquad \forall j \in J_i. \tag{4.11}$$

As a result, we have the following integer linear programming formulations:

Profit VLP

$$\max \sum_{i \in I} \sum_{j \in J_i} \sum_{k \in K_j} \rho_{ij} x_{ijk} - \sum_{j \in J} \sum_{k \in K_j} v_j z_{jk} - \sum_{j \in J} f_j y_j$$

s.t.

s.t.
$$(4.1)$$
- (4.11) .

Coverage VLP

$$\max \sum_{i \in I} \sum_{j \in J_i} \sum_{k \in K_j} q_{ij} x_{ijk}$$

s.t.

s.t. (4.1)-(4.11).

4.5 Complexity

Now, we investigate the complexity of the problems.

Theorem 1. ProfitVLP and CoverageVLP are strongly NP-hard.

Proof. We prove that decision versions of *ProfitVLP* and *CoverageVLP* are NP-complete in the strong sense by a reduction from the decision version of the bin packing problem.

Given a finite set of items U, a size $s_i \in \mathbb{Z}_+$ for each $i \in U$, a positive integer bin capacity B and a positive integer κ , the decision version of the bin packing problem is defined as follows. Is there a partition of set U into U_1, \ldots, U_{κ} such that $\sum_{i \in U_u} s_i \leq B$ for all $u = 1, \ldots, \kappa$? This problem is NP-complete in the strong sense (see problem [SR1] in Garey and Johnson [11]).

First remark that when $v_j = f_j = 0$ for all $j \in J$ and $\rho_{ij} = q_{ij}$ for all $i \in I$ and $j \in J_i$, problems *ProfitVLP* and *CoverageVLP* become the same problem. Hence in the remaining part of the proof, we only consider *CoverageVLP*.

We define the decision version of *CoverageVLP* as follows. Given the parameters of the problem and a positive constant Φ , does there exist a feasible solution with coverage at least Φ ? This problem is in NP.

Given an instance of the bin packing problem, let J be a singleton, $I = I_1 = U$, $p = 1, v_1 = 0, f_1 = 0, \rho_{min} = 0, k_1^{max} = \kappa, \rho_{i1} = q_{i1} = s_i$ for $i \in I, \gamma = B$, $\Phi = \sum_{i \in I} q_{i1}$. Now there exists a solution to the decision version of the bin packing problem if and only if there exists a solution to the decision version of *CoverageVLP*. Hence, the decision version of *CoverageVLP* is NP-complete in the strong sense. \Box

Chapter 5

VALID INEQUALITIES

In this chapter, we propose some valid inequalities for both versions of the VLP. Let F be the set of solutions that satisfy constraints (4.1)-(4.11). We use some substructures in the formulation to derive our valid inequalities.

5.1 Lower bounds on the number of vehicles

Albareda-Sambola et al.[3] propose the optimality cuts $\sum_{k \in K_j} z_{jk} \ge y_j$ for $j \in J$. These inequalities imply that if a vendor is located then it should use at least one vehicle. In our problem, since we have minimum profit constraints, in some cases we can obtain tighter bounds on the number of vehicles to be used by a vendor. Besides the resulting inequalities are valid inequalities. For $j \in J$ and a positive integer m, consider the following problem:

$$\delta_{j}(m) = \max \sum_{i \in I_{j}} \sum_{k=1}^{m} \rho_{ij} \alpha_{ik} - \sum_{k=1}^{m} v_{j} \beta_{k} - f_{j}$$

s.t.
$$\sum_{k=1}^{m} \alpha_{ik} \leq 1 \qquad \forall i \in I_{j}$$
$$\sum_{i \in I_{j}} q_{ij} \alpha_{ik} \leq \gamma \beta_{k} \qquad \forall k = 1, \dots, m$$
$$\alpha_{ik} \in \{0, 1\} \qquad \forall i \in I_{j}, k = 1, \dots, m$$
$$\beta_{k} \in \{0, 1\} \qquad \forall k = 1, \dots, m.$$

This problem maximizes the total profit for vendor j if vendor j can use at most m vehicles. Let m_j be the smallest integer with $\delta_j(m_j) \ge \rho_{min}$. Then for vendor j to achieve a minimum level of profit of ρ_{min} units, it should have at least m_j vehicles. If m_j is a positive integer which is less than or equal to k_j^{max} , then the inequality $\sum_{k \in K_j} z_{jk} \ge m_j y_j$ is a valid inequality. If m_j does not exist or if $m_j > k_j^{max}$, then vendor j cannot be profitable. Hence we can set $y_j = 0$.

The above problem is a single sourcing capacitated facility location problem which is an NP-hard problem. As a result, computing the $\delta_j(m)$ values may be quite time consuming. Hence we propose a way of computing lower bounds on m_j values.

Proposition 1. Let $j \in J$ and $\sigma_j = \max_{i \in I_j} \frac{\rho_{ij}}{q_{ij}}$. The inequality

$$\sum_{k \in K_j} z_{jk} \ge \left\lceil \frac{\rho_{min} + f_j}{\sigma_j \gamma - v_j} \right\rceil y_j \tag{5.1}$$

is valid.

Proof. For $j \in J$, $\sigma_j q_{ij} \ge \rho_{ij}$ for all $i \in I_j$. Multiplying constraints (4.4) with σ_j and summing over $k \in K_j$ yields $\sum_{i \in I_j} \sigma_j q_{ij} \sum_{k \in K_j} x_{ijk} \le \sigma_j \gamma \sum_{k \in K_j} z_{jk}$. Since $\sigma_j q_{ij} \ge \rho_{ij}$ for all $i \in I_j$, this implies $\sum_{i \in I_j} \rho_{ij} \sum_{k \in K_j} x_{ijk} \le \sigma_j \gamma \sum_{k \in K_j} z_{jk}$. Now combining this with constraint (4.5), we obtain

$$\sigma_j \gamma \sum_{k \in K_j} z_{jk} \ge \sum_{i \in I_j} \rho_{ij} \sum_{k \in K_j} x_{ijk} \ge \sum_{k \in K_j} v_j z_{jk} + (\rho_{min} + f_j) y_j$$

which gives

$$(\sigma_j \gamma - v_j) \sum_{k \in K_j} z_{jk} \ge (\rho_{min} + f_j) y_j$$

This implies that if $y_j = 1$, i.e., if a vendor is located at location j, then $\sum_{k \in K_j} z_{jk} \geq \frac{\rho_{\min} + f_j}{\sigma_j \gamma - v_j}$. Since the left hand side is integer in a feasible solution, we can round up the right hand side. \Box

For $j \in J$, σ_j can be computed in $O(|I_j|)$ time.

5.2 Cover inequalities for vehicle capacity constraints

For $i \in I$, $j \in J_i$, and $k \in K_j$, inequality

$$x_{ijk} \le z_{jk} \tag{5.2}$$

is a valid inequality. These inequalities are often dominated by cover inequalities that may be generated using the knapsack structure of the capacity constraints (4.4) for the vehicles. Cover inequalities that are valid for each of these knapsack constraints are also valid for F. Let $j \in J$, $k \in K_j$, and $C \subseteq I_j$ be such that $\sum_{i \in C} q_{ij} > \gamma$. Then the cover inequality $\sum_{i \in C} x_{ijk} \leq (|C| - 1)z_{jk}$ is a valid inequality.

Most of the integer programming solvers recognize knapsack constraints and use cover inequalities as cutting planes. So here we limit our attention to some lifted cover inequalities that are not many in number so that they can be added to the formulation before giving it to the solver.

For a given location $j \in J$, we first consider all demand points with demand larger than half of the capacity of a vehicle. Then we know that at most one of these points may be assigned to a given vehicle of vendor j. This leads to the following set of inequalities. **Proposition 2.** For $j \in J$ and $k \in K_j$, the lifted cover inequality

$$\sum_{i \in I_j: q_{ij} > \frac{\gamma}{2}} x_{ijk} \le z_{jk} \tag{5.3}$$

is valid for F.

Proof. Easy. \Box

Next, we generate lifted cover inequalities for each demand point $i \in I_j$ with demand not more than half the capacity.

Proposition 3. Let $i \in I_j$ be such that $q_{ij} \leq \frac{\gamma}{2}$. Define $C_{ij} = \{l \in I_j : q_{ij} + q_{lj} > \gamma\}$. Then the lifted cover inequality

$$x_{ijk} + \sum_{l \in C_{ij}} x_{ljk} \le z_{jk} \tag{5.4}$$

is valid for F.

Proof. If $x_{ijk} = 1$, then as $q_{ij} + q_{lj} > \gamma$ for each $l \in C_{ij}$, none of these demand points can be served by the same vehicle. If $x_{ijk} = 0$, then as $q_{lj} + q_{mj} > \gamma$ for land m in C_{ij} , we know that $\sum_{l \in C_{ij}} x_{ljk} \leq z_{jk}$. \Box

Notice that if C_{ij} is empty, then inequality (5.4) reduces to (5.2).

5.3 Cover inequalities for the minimum profit constraints

Finally, we propose cover inequalities for the minimum profit constraints. This is done by complementing sums of assignment variables and rewriting the minimum profit constraints as 0-1 knapsack constraints. **Proposition 4.** Let $j \in J$, $S_1 \subseteq I_j$, and $S_2 \subseteq K_j$ with $|S_2|v_j + (\rho_{min} + f_j) > \sum_{i \in I_j \setminus S_1} \rho_{ij}$. The inequality

$$\sum_{k \in S_2} z_{jk} \le \sum_{i \in S_1} \sum_{k \in K_j} x_{ijk} + (|S_2| - 1)y_j$$
(5.5)

is valid.

Proof. Let $j \in J$. For $i \in I_j$, define the variable $\overline{x}_{ij} = 1 - \sum_{k \in K_j} x_{ijk}$. Notice that \overline{x}_{ij} is a 0-1 variable. Now the minimum profit constraint (4.5) can be rewritten as

$$\sum_{i \in I_j} \rho_{ij} \ge \sum_{i \in I_j} \rho_{ij} \overline{x}_{ij} + \sum_{k \in K_j} v_j z_{jk} + (\rho_{min} + f_j) y_j$$

which is a knapsack inequality. Suppose that $y_j = 1$. Let $S_1 \subseteq I_j$ and $S_2 \subseteq K_j$. If $\sum_{i \in S_1} \rho_{ij} + |S_2|v_j + (\rho_{min} + f_j) > \sum_{i \in I_j} \rho_{ij}$, then the cover inequality $\sum_{i \in S_1} \overline{x}_{ij} + \sum_{k \in S_2} z_{jk} \leq |S_1| + |S_2| - 1$ is valid.

We can rewrite this inequality as $\sum_{i \in S_1} (1 - \sum_{k \in K_j} x_{ijk}) + \sum_{k \in S_2} z_{jk} \leq |S_1| + |S_2| - 1$ which simplifies to $\sum_{k \in S_2} z_{jk} \leq \sum_{i \in S_1} \sum_{k \in K_j} x_{ijk} + |S_2| - 1$. If $y_j = 0$, then $x_{ijk} = 0$ for all $i \in I_j$ and $k \in K_j$ and $z_{jk} = 0$ for all $k \in K_j$. Hence inequality (5.5) is valid. \Box

Chapter 6

COMPUTATIONAL RESULTS

In this chapter, we describe the test data and report the outcomes of two experiments. In the first experiment, we investigate for which sizes we can solve the formulations to optimality in reasonable times and the effect of valid inequalities on the quality of LP relaxation upper bound and the solution times. In the second experiment, we compare the solutions for the two versions of the problem for different parameters.

6.1 Models

Let ProfitM0 and CoverageM0 be the models presented in Chapter 4 as ProfitVLP and CoverageVLP respectively.

Let ProfitM1 and CoverageM1 be the models ProfitM0 and CoverageM0 strengthened with valid inequalities (5.1).

The fact that if a vendor is located at a demand point, then the point should use its first vehicle can further be used to obtain stronger lifted cover inequalities for the first vehicles:

$$\sum_{i \in I_j \setminus \{j\}: q_{ij} + q_{jj} > \gamma} x_{ij1} = 0 \qquad \forall j \in J$$
(6.1)

$$\sum_{i \in I_j \setminus \{j\}: q_{ij} > \frac{\gamma - q_{jj}}{2}} x_{ij1} \le z_{j1} \qquad \forall j \in J$$
(6.2)

$$x_{ij1} + \sum_{l \in I_j \setminus \{j\}: q_{ij} + q_{lj} > \gamma - q_{jj}} x_{lj1} \le z_{j1} \qquad \forall j \in J, i \in I_j \setminus \{j\}: q_{ij} \le \frac{\gamma - q_{jj}}{2} \quad (6.3)$$

We add the above cover inequalities for the first vehicles and inequalities (5.3) and (5.4) for the remaining vehicles to models *ProfitM1* and *CoverageM1* and call the resulting models *ProfitM2* and *CoverageM2*, respectively.

Moreover, we remove constraints (4.5) from models *ProfitM2* and *CoverageM2* and add the following variables and constraints to obtain models *ProfitM3* and *CoverageM3*:

$$\overline{x}_{ij} = 1 - \sum_{k \in K_j} x_{ijk} \qquad \forall i \in I, j \in J$$
(6.4)

$$\sum_{i \in I_j} \rho_{ij} \overline{x}_{ij} + \sum_{k \in K_j} v_j z_{jk} + (\rho_{min} + f_j) y_j \le \sum_{i \in I_j} \rho_{ij} \qquad \forall j \in J$$
(6.5)

$$\overline{x}_{ij} \in \{0, 1\} \qquad \forall i \in I, j \in J \tag{6.6}$$

The aim is to enable the solver to see the knapsack structure in the minimum profit constraints so that it can generate cover inequalities as presented in Chapter 5.

Next, we obtain models ProfitM4 and CoverageM4 by adding inequalities (6.7) to models ProfitM3 and CoverageM3, respectively.

$$z_{jk} \le y_j \qquad \forall j \in J, k \in K_j \tag{6.7}$$

After we analyzed the results, we tested one more formulation for each problem type. We see that the CPU time usually increases in *ProfitVLP*, when we add

cover inequalities for vehicle capacity constraints (Constraints (5.3) - (5.4) and (6.1) - (6.3)). We generate model *ProfitM5* by removing these constraints from model *ProfitM4*.

Observing the best results for CoverageVLP in terms of CPU time, we see that the most beneficial one is Constraints (6.7). So, we add only this constraints to model CoverageM0 to derive model CoverageM5.

To sum up, the constraints of models ProfitVLP and CoverageVLP (CoverVLP) are listed in Tables 6.1 and 6.2 respectively.

ProfitM0	ProfitM1	ProfitM2	ProfitM3	ProfitM4	ProfitM5
(4.1)-(4.11)	(4.1)-(4.11) (5.1)	(4.1)-(4.11) $(5.1)-(5.3)$ $(6.1)-(6.3)$	$\begin{array}{c} (4.1)-(4.4)\\ (4.6)-(4.11)\\ (5.1)-(5.3)\\ (6.1)-(6.6) \end{array}$	$\begin{array}{c} (4.1)-(4.4)\\ (4.6)-(4.11)\\ (5.1)-(5.3)\\ (6.1)-(6.7) \end{array}$	(4.1)-(4.4) $(4.6)-(4.11)$ (5.1) $(6.4)-(6.7)$

Table 6.1: Constraints for model *ProfitVLP*

CoverM0	CoverM1	CoverM2	CoverM3	CoverM4	CoverM5
(4.1)-(4.11)	(4.1)-(4.11)	(4.1)-(4.11)	(4.1)-(4.4)	(4.1)-(4.4)	(4.1)-(4.11)
	(5.1)	(5.1)- (5.3)	$\begin{array}{c} (4.6)-(4.11)\\ (5.1)-(5.3) \end{array}$	$\begin{array}{c} (4.6)-(4.11)\\ (5.1)-(5.3) \end{array}$	
		(6.1)- (6.3)	(6.1)- (6.6)	(6.1)- (6.7)	(6.7)

Table 6.2: Constraints for model Coverage VLP

For each value of p, k^{max} , and ρ_{min} , we have four different types of instances with different demand and profit structures. In **A** type problems, we take $q_{ij} = q_i$ and $\rho_{ij} = \rho_i$ for all $j \in J_i$ and $i \in I$. So in **A** type instances, the demand and profit are independent of the distance between the demand point and its vendor.

In **B** type problems, we take $q_{ij} = q_i$ and $\rho_{ij} = c_{ij}q_i$ for all $j \in J_i$ and $i \in I$ where c_{ij} is the unit profit that vendor j gains if it serves demand point i and is a function of the distance between i and j. In **C** type problems, we take q_{ij} to be a function of the distance between *i* and j and $\rho_{ij} = cq_{ij}$ for all $j \in J_i$ and $i \in I$ where *c* is the unit profit and does not depend on distances. In this case, we let $q_{ij} = q_i$ for vendors *j* that are within a short traveling time of *i* and then let q_{ij} decrease with the distance between *i* and *j* for other eligible vendors.

Finally in \mathbf{D} type instances, we take both the demands and the profits as functions of the distances.

6.2 Input Data and Parameter Selection

We are required to design the distribution system for HOD-Demijohn Water brand that will enter the market. We use the data from this demijohn water company. The data includes 84 demand points, their estimated demands, the distances, and cost parameters. Demand points are the customers buying HOD-Demijohn water and facilities are the vendors of this new brand. The set of possible locations for the vendors is the same as the set of demand points.

We define that the distance between the vendor and the customer, d_{ij} , is allowed to be at most 10 km. Therefore, we construct the set J_i as following:

$$J_i := \{j : d_{ij} \le 10\} \quad \forall i \in I.$$

We are given the daily demand of points, q_i by the HOD-Demijohn water company. Since the waiting time is crucial for customers, we define the demand, q_{ij} demonstrated in Figure 6.1, as a function of the distance d_{ij} between demand points and vendors as follows:

$$q_{ij} := \begin{cases} q_i, & \text{if } d_{ij} \le 5\\ q_i(1.5 - 0.1d_{ij}), & \text{if } 5 < d_{ij} \le 10 \end{cases}$$

$$\forall i \in I, j \in J_i.$$

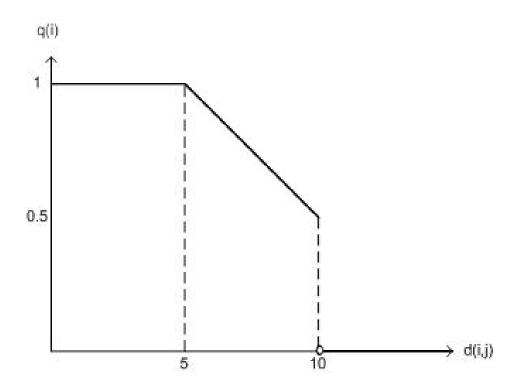


Figure 6.1: q_{ij} function in terms of distance

Company determines the fixed facility cost f_j ; the vehicle cost v_j including the 5 years forward purchase cost, depreciation, tax, maintenance and the personnel salary; and the profit of each product, m, which is independent of the distance between the demand point and its vendor.

The unit profit that vendor j gains if it serves demand point i is equal to c_{ij} and is defined as follows:

$$c_{ij} := (m - ud_{ij}) \quad \forall i \in I, j \in J_i.$$

Transportation cost for each product, u, is obtained by dividing the fuel cost of 1 km by the vehicle's capacity, γ .

Finally, we set the daily capacity of each vehicle γ to 60, since every vehicle has 20 bottles capacity and can be reloaded at most 3 times in a day.

Using the above parameters, we change the number of opened facilities p =

{4,6,8}, the maximum number of vehicles $k_j^{max} = \{6,8,10\}$, and the minimum profit value $\rho_{min} = \{50,100,150\}$ to see the effects of changes in parameters p, k_j^{max} , and ρ_{min} .

6.3 Comparison of Models

In this section, we will give the comparison among our models in terms of LP relaxation gaps, CPU times or final IP gaps for unsolvable instances, and the number of branch and cut nodes. Also, the effects of valid inequalities are analyzed. We try to analyze which formulation is better in which cases.

All models are solved using GAMS 22.5 and CPLEX 11.0.0 on an AMD Opteron 252 processor (2.6 GHz) with 2 GB of RAM operating under the system CentOS (Linux version 2.6.9-42.0.3.ELsmp). We have a time limit of one hour.

In Tables A.1-A.4 in the Appendix, we report the results for *ProfitVLP* and the four types of instances, \mathbf{A} , \mathbf{B} , \mathbf{C} , and \mathbf{D} , respectively. Tables A.5-A.8 in the Appendix are the results for *CoverageVLP* and the four types of instances, \mathbf{A} , \mathbf{B} , \mathbf{C} , and \mathbf{D} , respectively. For each instance and model, we report the percentage gap between the upper bound obtained by solving the linear programming relaxation of the corresponding model and the best lower bound for the integer problem in the column *LP Gap*. Then we report the cpu times in seconds. If the problem is not solved to optimality in one hour, then we report the remaining percentage gap in parenthesis. Finally, we report the number of nodes in the branch-and-cut tree for each model and instance. The best results are marked bold.

Each table has a summary, where we can see the averages of linear programming relaxation gaps, final optimality gaps, cpu times, number of nodes, the number of instances solved to optimality with each model, and the number of times each model was among the best for the considered criterion.

In the rest of the thesis, ProfitM0-ProfitM5 and CoverageM0-CoverageM5 are

abbreviated as PM0-PM5 and CM0-CM5, respectively.

Comparing models ProfitVLP and CoverageVLP in general, it is clear that for CoverageVLP we can reach optimality more quickly than for ProfitVLP. LP relaxation gap, which is measured as (100 * (LPoptimal - IPoptimal)/IPoptimal), is smaller for CoverageVLP than the one for ProfitVLP with valid inequalities.

Both problems ProfitVLP and CoverageVLP were infeasible for $\rho = 150$, p = 8 and all 4 demand and profit structures. These instances are removed from the results.

For the LP relaxation gap of model *ProfitVLP* for type **A** problems, *PM4* gives the best results in all the instances. On the average, *PM4* reduces the LP relaxation gap from 55.14% to 4.45%. The CPU times and the number of opened nodes are also less in *PM4* than in other models on average. However, *PM3* has the highest number of best solutions over 24 instances in terms of CPU times and the number of opened nodes. *PM3*, *PM4*, and *PM5* solve all problems whereas *PM0*, *PM1*, and *PM2* cannot. It is clear that *PM3* has better CPU times for $\rho_{min} = 150$. Results of the model *ProfitVLP* for type **A** problems are shown in Table A.1.

Table A.2 gives the LP relaxation gaps, CPU times, and the number of opened nodes of *ProfitVLP* for type **B** problems. *PM4* improves LP relaxation gaps for these instances as well. *PM3* has better average CPU times. *PM2* being the third on average in terms of CPU times has the largest number of results with the smallest CPU times, since problems with $\rho_{min} = 50$ are solved most quickly with this formulation. However, it cannot reach optimality in one instance with $\rho_{min} = 100$. Formulations which can reach optimality in all instances are only *PM3*, *PM4* and *PM5* like in *ProfitVLP* for type **A** problems. *PM4* has the best average performance in terms of the number of opened nodes.

When we generate the demand function in terms of distance between demand points and facilities as in models ProfitVLP for type **C** and **D** problems, it gets harder to reach optimality. For the LP relaxation gap of type **C**, PM4 has the best results except for three instances where it could not reach optimality. According to CPU times, PM0 has the smallest value with a slight diffence from PM5. The smallest final IP gap which is calculated by (100 * (Bestpossible - IPsolution)/Bestpossible) is given by PM5 that is 0.78% wheras it is 0.83% for PM0. However, the formulation reaching the optimality most frequently is PM0. PM0 can solve 7 instances to optimality, and others can solve 3,4,5,6, and 5 instances, respectively. On the other hand, PM5 gives the smallest CPU times in 11 out of 24 instances, which is the best result among all of the six model types. PM4 gives the smallest number of opened nodes on the average and the largest number of best solution in terms of opened nodes over 24 instances. Table A.3 includes the results of model ProfitVLP for type **C** problems.

The last type of instances are type **D** for *ProfitVLP* problems. From Table A.4, the smallest average LP relaxation gap is obtained using *PM4*, which has the best results in 18 out of 24 instances. Analyzing the CPU times and final IP gaps for unsolvable instances, we see that *PM5* has the smallest CPU time, 2794.21 sec. 9 instances can be solved by *PM5*, while others can solve fewer number of instances. *PM5* giving the best solutions in 8 instances also has the largest number of best solution. According to final IP gaps, it is in the second place with 0.93%. However, the difference between the first one, *PM1*, is 0.01%. *PM3* has the best results in 10 instances on average in terms of the number of opened nodes.

We can conclude that PM5 generally leads shorter CPU times not for all types of models, but for ProfitVLP type **C** and **D** problems.

For *CoverageVLP*, the LP relaxation gap is about 1% and the best model for it is CM4 in all instances and all model types. Although it seems that the decrease in LP gap relaxation is provided due to Constraint (6.7), the same results cannot be obtained when only Constraint (6.7) is added. So, we can conclude that although the most helpful one is Constraint (6.7), other constraints also help to decrease the LP relaxation gap.

When we compare the CPU times of model CoverageVLP for type A problems, CM4 decreases the CPU time from 521.64 sec. to 114.03 sec. This formulation

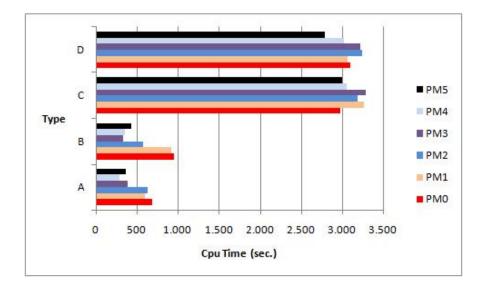


Figure 6.2: Comparison of average cpu times for *ProfitVLP*

can solve all instances, whereas others cannot. However, the best solutions are obtained in 7 instances with CM4, as CM5 can solve 8 instances within the smallest CPU time. CM4 also opens the least number of nodes with a huge difference from other formulations. The results of model *CoverageVLP* for type **A** problems are seen in Table A.5.

Results of problem *CoverageVLP* for type **B** instances indicate that CM4 has the smallest average CPU time with 190.60 sec. This formulation not only solves all of the 24 instances within 1 hr and gives the quickest results for 9 instances. CM5 gives the best results in terms of CPU times on 8 instances, but its average CPU time is 420.15 sec., which is about two times of CM4. In addition to its superiority in CPU times, CM4 also opens the least number of nodes on the average. This outcome does not change in 16 instances. The results of *CoverageVLP* for type **B** problems are presented in Table A.6.

Coverage VLP for type \mathbf{C} and \mathbf{D} problems can reach optimality within 1 hr in most of the models unlike *ProfitVLP*. On the average, *CoverageVLP* has the smallest CPU time in *CM5* with 68.41 sec. for type \mathbf{C} problems which are solved to optimality by all of the formulations. *CM4*, which gives the best results for *CoverageVLP* for type \mathbf{A} and \mathbf{B} problems, is in the second place with 96.23. 8 out of 24 instances get the smallest CPU time with *CM5*. However, *CM4* has the least number of nodes in 20 instances over 24 and provides opening fewer number of nodes on the average. The results are shown in Table A.7.

Finally, we analyze the results of *CoverageVLP* for type **D** problems in Table A.8. None of the models except *CM3* and *CM4* can reach optimality within 1 hr in 2 instances. *CM4* has the smallest average CPU time with 129.62 sec., but only 3 instances prove the optimality most quickly by *CM4*. *CM3* is the best one in this criterion with 6 instances. However, there is a slight difference between *CM3* and *CM4*'s CPU time in 6 instances, which get the best results with *CM3*. Like the CPU time, average number of opened nodes is the least in *CM4* and it has the best results in 15 instances.

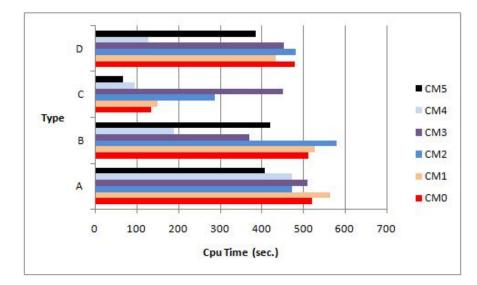


Figure 6.3: Comparison of average cpu times for CoverageLP

6.4 Solution Analysis of an Instance

We select an instance to analyze the solution for type **A** and type **D** problems. The instance has $\rho_{min}=100$, $k_j^{max}=8$ and p=6. The best results in terms of CPU time are obtained in *PM2*, *PM3*, *CM4* and *CM2* for the problems of *ProfitVLP* for type **A**, *ProfitVLP* for type **D**, *CoverageVLP* for **A** and *CoverageVLP* for **D** respectively. The solutions of *ProfitVLP* for type **A**, *ProfitVLP* for type **D**, Coverage VLP for type \mathbf{A} and Coverage VLP for type \mathbf{D} problems are shown on a map in Figure 6.4, 6.5, 6.6 and 6.7 respectively.

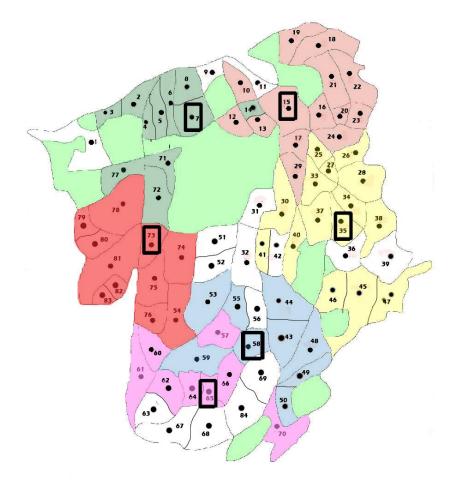


Figure 6.4: The solution of PM2 for ProfitVLP type **A** problem

Comparing the solutions of problems, we see that demand points assigned to the same vendor lie close to each other in both ProfitVLP and CoverageVLPtype **D** problems, wheras some demand points serviced from same vendor are seperated from the group in ProfitVLP and CoverageVLP for type **A** problems.

Moreover, uncovered demands which are white regions in the figures are less in type **D** problems than type **A**. The amounts of uncovered demand are 526, 113, 328, and 98 in *ProfitVLP* for type **A**, *ProfitVLP* for type **D**, *CoverageVLP* for type **A** and *CoverageVLP* for type **D** problems respectively.

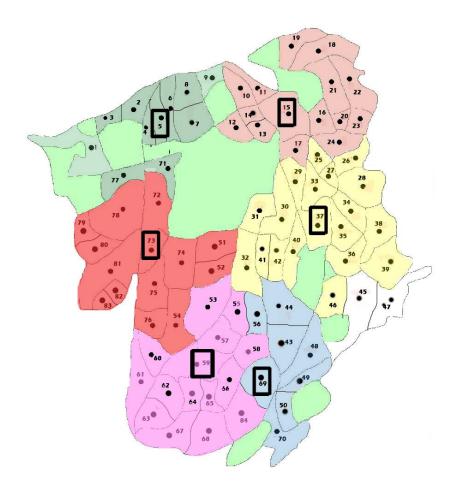


Figure 6.5: The solution of PM3 for ProfitVLP type **D** problem

Coverage VLP problem types provide service to more demand points according to corresponding *ProfitVLP*. Besides, 1152.70, 1214.32, 1032.20 and 992.36 are total profits of *ProfitVLP* for type **A**, *ProfitVLP* for type **D**, *CoverageVLP* for type **A** and *CoverageVLP* for type **D** problems.

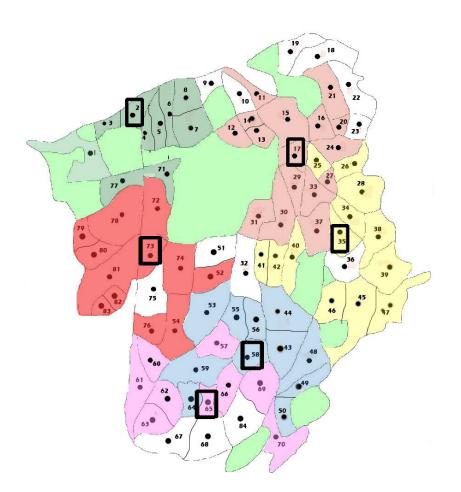


Figure 6.6: The solution of CM4 for CoverageVLP type ${\bf A}$ problem

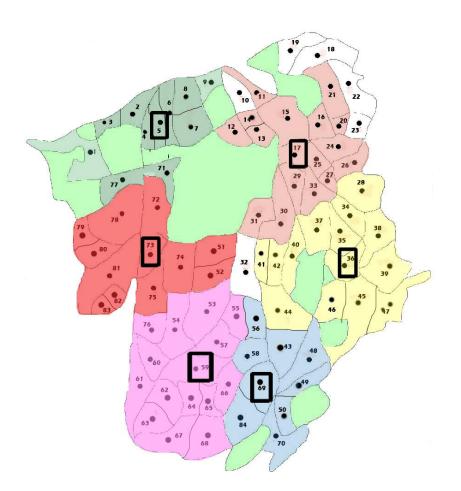


Figure 6.7: The solution of CM2 for CoverageVLP type ${\bf D}$ problem

Chapter 7

CONCLUSION

In this thesis, we considered the *Vendor Location Problem (VLP)*. The problem is to decide where to locate vendors, the number of vehicles each vendor should have, and the assignments of customers to these vendors and vehicles.

Firstly, we developed an linear integer program for VLP with profit (*ProfitVLP*) and coverage (*CoverageVLP*) maximization objectives. We construct four different types of problems. In **A** type problems, demand and profit are independent of distance between vendors and demand points. In **B** type problems, profit is a function in terms of distance. In **C** type problems, demand is a function of the distance. In this case, demand decreases as the distance between customers and facilities increases. In **D** type problems, both the demand and the profit are functions of the distance. All problems are extensions of two-level facility location problem with capacity and minimum profit constraints.

Since both problems are NP-Hard, we added valid inequalities to the models in order to get optimal solutions at faster times and reduce the linear programming relaxation gap. We have four groups of valid inequalities: lower bounds on the number of vehicles, cover inequalities for vehicle capacity constraints, cover inequalities for the minimum profit, and vehicle-vendor inequalities.

We added above inequalities to all our problems one by one to see the effects

of inequalities. The models with valid inequalities are tested by changing p, k_j^{max} and ρ_{min} parameters. All problems are solved within a time limit of 1 hour. Although valid inequalities reduce the linear programming relaxation gap, the effect of valid inequalities differ in each instance in terms of the CPU time. However, we can conclude that *CoverageVLP* is easier to solve than *ProfitVLP*. Moreover, *ProfitVLP* type **C** and type **D** problems, which include the demand as a function of the distance between demand points and vendors make the problem harder. As a result, optimality is attained for all instances except for some of *ProfitVLP* type **C** and type **D** problems within the given 1 hour time limit.

A future research direction may be to investigate different demand and profit functions.

Another future research may be to develop a heuristic for ProfitVLP type **C** and **D** problems, since we cannot reach optimality for some instances within 1 hour.

Finally, another future research may be an extension of Vendor Location Problem in competitive location context where other brands also have vendors. In our study, we construct profit and coverage profit maximization objectives. VLP in competitive location context can have multi-objective functions.

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Appendix A

Tables of Computational Results

$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	P_{a}	Parameters			LP Gap (%	ip (%)			CI	PU Time	CPU Time (sec.)/Optimality Gap(%	ptimality	γ Gap(%	()		Z	Number o	of Nodes		
6 4 76.77 76.77 29.21 6.48 6.48 6.43 37.61 203.00 284.25 454.59 61.57 177.23 29387 8 4 48.05 8.56 5.58 5.56 5.58 5.56 5.58 5.66 5.59 5.66 10.02 10.02 91.25 10.02 91.25 5.53 84.97 10.17 38.47 10 4 455.06 5.09 1.80 1.18 11.12.33 811.202 91.55 91.66 14.95 165 11.52 655.55 405.55 14.51 14.12 14.302 156.56 91.66 55.56	ρ_{min}	k^{max}	d		PM2	PM3	PM4	PM5	PM0	PM1	PM2	PM3	PM4	PM5	PM0	PM1	PM2	PM3	PM4	PM5
8 4 48.05 8.56 5.89 2.52 411.81 127.10 562.07 287.42 866.45 1002.20 277.54 10 4 42.51 3.92 3.92 3.92 2.31 24.55 110.71 13.83 150.20 10.70 3.847 6 50.91 50.91 4.80 4.15 50.91 1901 13.93 10.72 653.58 47.70 145.42 653.94 4987 157.59 9.46 43.57 673.57 777.12 41.91 145.42 756.94 1007.29 573.58 777.10 145.42 653.95 778.0 275.51 153.93 157.67 7767 777.10 145.42 756.95 1013.52 87.182 83.83 174.20 161.32 7767 7767 7767 7767 7767 7767 7767 7767 7767 7763 7763 7763 7743 774.72 876.44 7745 7743 7743 7743 77456 7763 <	50	9	4		29.21	29.21	6.48	6.48	397.61	203.00	284.25	454.59	261.57	177.23	29387	13208	14983	28200	13612	8503
	50	×	4		8.56	8.56	5.89	25.82	411.81	127.10		2874.28	866.48	1002.29	20792	7760	26693	103257	23868	43420
6 6 58.36 5.3.3 9.2.6 5.0.4 21.5.7 116.90 110.11 123.33 196.02 166.54 110.70 3847 8 6 50.91 50.91 4.80 4.15 50.91 180.06 56.8.44 60.53 112.02 91.72 55.3.85 49637 10 6 49.93 4.71 4.72 5.93 </td <td>50</td> <td>10</td> <td>4</td> <td></td> <td>3.92</td> <td>3.92</td> <td></td> <td>42.31</td> <td>244.58</td> <td>153.81</td> <td>32.81</td> <td>12.25</td> <td>9.46</td> <td>43.52</td> <td>27254</td> <td>17360</td> <td>3119</td> <td>248</td> <td>85</td> <td>780</td>	50	10	4		3.92	3.92		42.31	244.58	153.81	32.81	12.25	9.46	43.52	27254	17360	3119	248	85	780
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	50	×	9		4.80	4.80	4.15	50.91	1180.66	568.44	60.53	112.02	91.72	653.58	49637	20099	929	1621	1683	28500
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8 55.24 55.24 1.84 55.24 1.84 1.84 1.84 55.24 1.84 1.84 55.24 0.05) 741.72 897.38 742.00 54635 54635 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 34745 54635 54735 5574 5574 5574 5564 738 5564 738 10 4 45.51 3.92 3.92 249.33 619.59 9.84 35.56 738 10	100	9	×		1.84	1.84		55.24	270.22	159.86	330.99	310.32	408.94	285.72	4837	2495	4595	3669	4189	2963
	100	×	×		1.84	1.84		55.24	3259.19	1315.94		460.38	467.88	472.78	66262	30370	10986	3431	4171	4406
6 4 76.77 76.77 29.21 6.48 6.47 601.01 164.50 38.14 20508 10 4 42.51 3.92 3.92 3.92 3.92 2.93 2.64 36.53 5.64 738 6 6 6 11.02 11.02 6.85 3.77 256.54 141.90 97.67 136.63 132.64 738 8 6 55.77 7.06 7.06 6.76 55.77 366.69 249.83 619.59 52.91 108.36 10633 10 6 6.76 6.77 366.69 249.83 619.59 52.91 108.30 10633	100	10	8		1.84	1.84		55.24	(0.05)	(0.05)		741.72	897.38	742.00	54635	50175	47481	4803	5475	5494
	150	9	4		29.21	29.21	6.48	6.48	427.28	205.37			166.03	132.58	34745	10641	23289	6411	7191	5580
	150	x	4		8.56	8.56	5.89	25.82	282.47	883.12	976.47		164.50	398.14	20508	46832	54511	38617	5468	22293
	150	10	4		3.92	3.92		42.31	27.77	25.76	19.65	9.84	36.53	52.64	738	069	638	160	555	661
	150	9	9		11.02	11.02		23.77	242.70	256.54	141.90	97.67	125.62	120.08	11248	6592	4629	1580	1757	3557
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	150	x	9		7.06	7.06		55.77	366.69	249.83	619.59	52.91	139.67	108.36	10633	11690	23780	652	666	198
55.14 55.14 55.14 8.22 4.45 38.92 691.24 597.88 631.76 383.94 287.62 360.74 23051 (0.00) (0.00) (0.00) (0.00) (0.00) (0.00) (0.00) 23 23 23 23 24 24 24	150	10	9		6.35	6.35		54.73	979.08	2620.63		202.62	279.85	163.29	35910	64156	115684	877	928	981
$(0.00) (0.00) (0.00) (0.00) (0.00) (0.00) \\ 23 23 24 24$		Average			8.22	8.22		38.92	691.24	597.88	631.76		287.62	360.74		17027	19984	11604	5573	10411
23 23 24 24	Avg.	Opt. Gap((%)						(0.00)	(0.00)	(0.00)		(0.00)	(0.00)						
	# of St	olved Ins.((24)						23	23	22	24	24	24						
# of Best Solutions(/24) 10 10 24 3 2 4 3 10 4 1 2 4	# of Bes	t Solution	s(/24)		10	10	24	co	2	4	ę	10	4	1	2	4	2	6	4	က

Table A.1: LP gap, CPU time/ optimality gap and number of nodes of ProfitVLP in A type instances

APPENDIX A. TABLES OF COMPUTATIONAL RESULTS

48

Pa	Parameters			LP Gap (%	ф (%)			0	PU Time	CPU Time (sec.)/Optimality $Gap(\%)$	Optimali	sy Gap(9	()		Ň	Number of Nodes	f Nodes		
ρ_{min}	k^{max}	b	PM0 PM1	PM2	PM3	PM4	PM5	PM0	PM1	PM2	PM3	PM4	PM5	PM0	PM1	PM2	PM3	PM4	PM5
50	6	4	77.61 77.61	29.38	29.38	6.93	7.78	118.79	243.27	403.13	435.34	394.87	157.66	6510	14967	26960	26043	23355	6967
50	8	4	48.76 48.76	8.72	8.72	6.04	26.82	$1004.05\ 2726.00$	2726.00	858.60	664.81	140.27	483.59	73179	103608	66030	33633	3897	16495
50	10	4	43.51 43.51	4.32	4.32	4.32	43.31	80.74	185.76	10.28	19.22	20.70	54.16	4358	10526	278	396	368	069
50	9	9	59.28 59.28	9.42	9.42	5.33	22.89	378.75	173.11	108.48	302.37	206.38	204.76	17782	8094	4562	7770	5924	10605
50	×	9	52.04 52.04	5.12	5.12	4.55	52.02	368.67	119.70	149.56	71.49	147.88	165.26	14233	4161	5163	1678	2169	5203
50	10	9	51.17 51.17	4.53	4.53	4.53	51.17	1969.78	350.27	118.53	144.66	203.60	1920.13	82051	13989	2111	2356	4122	51737
50	6	×	57.31 57.31	2.38	2.38	2.21	57.23	277.26	308.33	101.84	172.87	178.26	213.94	7455	5374	1530	2400	1923	2837
50	×	x	56.75 56.75	2.03	2.03	2.02	56.74	245.46	285.58	147.91	314.23	417.90	306.81	4151	4682	2970	4010	4293	4268
50	10	×	56.75 56.75	2.04	2.04	2.04	56.75	765.83	680.23	428.27	563.48	1128.88	847.33	16686	13179	5266	6304	9672	9794
100	9	4	77.61 77.61	29.38	29.38	6.93	7.78	625.21	392.02	168.70	187.98	204.20	698.42	49140	29850	10168	8666	14426	6520
100	×	4	48.76 48.76	8.72	8.72	6.04	26.82	371.98	836.81	356.90	782.17	568.03	340.19	25341	37881	18964	34894	22507	14522
100	10	4	43.51 43.51	4.32	4.32	4.32	43.31	148.09	44.02	8.64	17.50	39.84	68.94	10875	1288	307	348	576	1074
100	9	9	59.28 59.28	9.41	9.41	5.33	22.89	201.71	256.55	218.15	239.38	428.11	180.65	10180	10857	8823	9104	18007	6085
100	×	9	52.10 52.10	5.11	5.11	4.53	52.08	626.96	380.98	398.19	75.75	167.60	246.32	49338	28355	40180	1286	3042	10095
100	10	9	51.23 51.23	4.52	4.52	4.52	51.23	539.51	338.08	222.25	148.77	189.52	755.32	28173	22321	9924	2428	3587	25125
100	9	x	58.33 58.32	2.81	2.81	2.70	58.25	861.99	1562.33	$1284.50 \ 661.40$	661.40	506.51	447.86	30967	35979	24283	6785	4620	6645
100	8	×	57.53 57.53	2.29	2.29	2.27	57.53	(0.21)	(0.03)	2493.71	743.06	775.63	1250.77	80039	112763	56433	7183	7549	14744
100	10	×	57.31 57.31	2.15	2.15	2.15	57.31	(0.06)	(0.01)	(0.05)	1384.88	1384.88 1296.781069.77	069.77	70320	87082	101959	9137	9011	11935
150	6	4	77.61 77.61	29.38	29.38	6.93	7.78	1263.19 107.18	107.18	154.69	217.05	214.49	156.04	76293	6924	7789	11128	12527	6577
150	8	4	48.76 48.76	8.72	8.72	6.04	26.82	$1382.57\ 2057.22$	2057.22	869.85	508.54	795.61	407.60	86130	120951	42405	31613	32705	19499
150	10	4	43.51 43.51	4.32	4.32	4.32	43.31	147.35	32.47	22.35	11.43	18.68	78.77	13428	550	685	214	339	1622
150	9	9	61.61 61.61	10.30	10.30	6.71	24.69	544.47	132.41	117.53	120.22	167.07	94.94	19639	4502	3275	2975	4778	3757
150	×	9	56.82 56.82	6.78	6.78	6.50	56.80	(0.01)	125.11	1006.17	88.80	124.49	152.24	113245	901	53107	664	660	1605
150	10	9	55.87 55.87	6.15	6.15	6.15	55.87	111.98	(0.00)	167.07	138.64	53.78	137.25	2345	89894	3173	743	573	764
	Average		56.38 56.38	8.43	8.43	4.73	40.30	951.44	922.41	558.98	333.91	349.55	434.91	37161	32028	20681	8823	7943	9965
Avg.	Avg. Opt. Gap(%)	(%)						(0.01)	(0.00)	(0.00)	(0.00)	(0.00)	(0.00)						
# of St	# of Solved Ins.(/24)	(24)						21	21	23	24	24	24						
# of Bes	# of Best Solutions(/24)	s(/24)		x	x	24		1	1	6	9	2	ы	1		4	9	ъ	ъ
							-												

Table A.2: LP gap, CPU time/ optimality gap and number of nodes of ProfitVLP in **B** type instances

1.	E/IN.	DL	1	1.	11	4D		S	Or	' C		VII	U		111	U1	٧A		пĽ	is c		LO						0	0
	PM5	5389	195620	115305	66734	57322	67819	57322	21764	18843	5496	217651	116855	24158	85315	49519	22312	15121	17731	4747	189367	153399	17171	77732	67901	69608			1
so.	PM4	4582	113821	58345	25452	41496	22146	24301	14275	13802	3208	67202	42564	27477	41428	46347	18713	11332	9690	3816	118125	50298	32231	42435	53502	36941			11
Number of Nodes	PM3	16029	55561	64855	25754	65312	31578	17679	14515	11431	23443	72687	52502	28226	68349	26137	14123	11026	11658	106412	91799	82438	26376	44136	34224	41510			4
Jumber	PM2	25878	33642	46926	22019	25086	24680	18448	15233	12847	21072	183491	61780	32600	43094	25728	17985	13911	9930	24382	85248	52135	31197	52963	30143	37934			×
4	PM1	29775	210493	125472	81063	52149	55828	25123	21204	21012	52312	119696 182370 183491	153907	75878	73212	57383	23039	27750	18319	61934	245267 114423	149194 132028	67638	82554	58336	75133			
	PM0	21173	263317	153821	89914	33616	60059	29311	22195	21175	44662	119696	94767	111839	69973	87953	29552	23977	20528	17131	245267	149194	46143	80373	48787	78518			
	PM5	137.35	(0.39)	(1.16)	(0.35)	(0.68)	(0.58)	(0.68)	(0.55)	(1.18)	157.72	(0.39)	(1.37)	1773.18	(0.48)	(0.81)	1.97	(0.91)	(2.99)	126.14	(0.57)	(1.16)	1430.80	(1.14)	(1.49)	3001.11	(0.78)	ы	11
CPU Time (sec.)/Optimality Gap(%)	PM4	235.64	(1.39)	(1.38)	2466.03	(0.02)	(0.81)	(5.18)	(1.01)	(1.76)	227.35	(0.58)	(2.58)	2271.14	(0.52)	(0.78)	(2.55)	(1.58)	(1.17)	213.28	3170.46	(1.25)	(0.52)	(1.55)	(1.41)	3057.75	(1.09)	9	с
'Optimali	PM3	808.90	1823.53	(3.42)	(0.23)	(0.16)	(0.86)	(4.04)	(1.10)	(1.96)	1312.17	(0.75)	(2.41)	(0.41)	(0.06)	(0.76)	(1.49)	(0.81)	(2.36)	3397.84	3295.62	(2.19)	(0.39)	(0.99)	(1.77)	3293.33	(1.09)	ъ	3
ne (sec.)/	PM2	908.56	(1.46)	(2.19)	(1.82)	(1.15)	(0.71)	(1.30)	(1.19)	(1.74)	690.56	(0.67)	(2.07)	(0.06)	(0.55)	(0.96)	(0.64)	(2.43)	(1.82)	783.26	(0.95)	(2.20)	2271.70	(1.18)	(1.77)	3194.00	(1.49)	4	1
CPU Tin	PM1	545.82	(0.77)	(2.43)	(0.02)	(0.86)	(0.81)	(1.47)	(0.74)	(1.26)	1212.46	(0.81)	(2.10)	(0.02)	(0.47)	(0.59)	(1.32)	(0.30)	(1.31)	1091.24	(0.73)	(2.20)	(0.02)	(1.34)	(1.77)	3268.79	(0.89)	ŝ	2
Ũ	PM0	415.66	(0.20)	(1.31)	(0.06)	1029.34	(0.88)	(1.72)	(0.63)	(1.05)	901.64	3191.66	(3.44)	(0.58)	(0.74)	(0.66)	(1.68)	(0.53)	(2.09)	350.66	2749.68	(1.16)	1725.05	(1.34)	(1.86)	2982.99	(0.83)	4	ъ
	PM5	3.99	12.69	13.27	14.80	12.88	12.88	17.56	16.49	16.53	3.99	12.69	13.27	14.80	12.88	12.88	19.38	16.49	18.40	3.99	12.69	13.27	14.80	14.34	14.34	13.24			33
	PM4	3.99	11.27	11.80	14.10	9.04	9.04	10.90	9.96	10.01	3.99	11.27	11.80	14.10	8.95	8.95	12.61	9.95	10.00	3.99	11.27	11.80	14.10	10.18	10.18	10.14			24
LP Gap (%)	PM3	34.53	11.75	11.80	17.42	9.04	9.04	11.74	9.96	10.01	34.53	11.75	11.80	17.41	8.95	8.95	13.44	9.95	10.00	34.53	11.75	11.80	17.20	10.18	10.18	14.49			13
LP G	PM2	34.53	11.75	11.80	17.42	9.04	9.04	11.74	9.96	10.01	34.53	11.75	11.80	17.41	8.95	8.95	13.44	9.95	10.00	34.53	11.75	11.80	17.20	10.18	10.18	14.49			13
	PM1	36.40	13.23	13.27	21.78	12.88	12.88	18.37	16.49	16.53	36.40	13.23	13.27	21.78	12.88	12.88	20.07	16.49	16.53	36.40	13.23	13.27	21.69	14.34	14.34	18.28			
	PM0	36.40	13.23	13.27	21.78	12.88	12.88	18.37	16.49	16.53	36.40	13.23	13.27	21.78	12.88	12.88	20.07	16.49	16.53	36.40	13.23	13.27	21.78	14.34	14.34	18.28			
rs	d	4	4	4	9	9	9	×	×	x	4	4	4	9	9	9	×	8	8	4	4	4	9	9	9		p(%)	(/24)	ons(/24)
Parameters	k^{max}	9	×	10	9	×	10	9	×	10	9	×	10	9	×	10	9	x	10	9	x	10	9	x	10	Average	Avg. Opt. Gap(%)	# of Solved Ins.(/24)	of Best Solutions(/24)
Ц	ρ_{min}	50	50	50	50	50	50	50	50	50	100	100	100	100	100	100	100	100	100	150	150	150	150	150	150		Avg.	# of \$	# of Be

Table A.3: LP gap, CPU time/ optimality gap and number of nodes of *ProfitVLP* in C type instances

50

APPENDIX A. TABLES OF COMPUTATIONAL RESULTS

$\mathbf{P}_{\mathbf{f}}$	Parameters				LP G	LP Gap (%)			-	CPU Tin	ne (sec.)/	CPU Time (sec.)/Optimality Gap(%)	y Gap(%	0		Z	Jumber	Number of Nodes	ល	
ρ_{min}	k^{max}	d	PM0	PM1	PM2	PM3	PM4	PM5	PMO	PM1	PM2	PM3	PM4	PM5	PM0	PM1	PM2	PM3	PM4	PM5
50	9	4	36.72	36.72	34.79	34.79	4.31	4.77	561.12	488.34	633.79	1956.61	232.02	160.37	28765	25766	15534	34652	5139	7266
50	×	4	13.44	13.44	11.93	11.93	11.47	12.93	1164.72	455.10	(0.28)	(1.16)	(1.09)	2809.47	67315	28114	94733	100649	56289	170833
50	10	4	13.48	13.48	11.98	11.98	11.98	13.48	(3.12)	(2.15)	(2.67)	(2.30)	(1.64)	(2.26)	100368	110347	68070	28127	66041	111921
50	9	9	21.92	21.92	17.43	17.43	13.98	14.99	(0.01)	(0.01)	(0.60)	(0.70)	1757.17	2004.23	84878	98031	62948	22232	14977	26490
50	×	9	13.27	13.27	9.32	9.32	9.32	13.27	(1.58)	(0.74)	(0.73)	(0.54)	(0.71)	(0.09)	81713	56679	29972	30236	45316	72111
50	10	9	13.27	13.27	9.32	9.32	9.32	13.27	(1.04)	(0.75)	(0.86)	(0.79)	(0.62)	(0.82)	52052	47068	19260	18872	40327	57108
50	9	x	20.76	20.76	13.77	13.77	12.87	19.97	(3.12)	(2.14)	(2.17)	(2.63)	(4.98)	(2.56)	32632	29856	21022	16450	26431	29340
50	×	x	17.01	17.01	10.25	10.25	10.25	17.01	(1.10)	(06.0)	(1.36)	(1.71)	(1.25)	(1.53)	29339	18631	13130	15488	12540	22387
50	10	×	17.03	17.03	10.27	10.27	10.27	17.01	(1.33)	(1.62)	(1.69)	(1.61)	(2.39)	(3.12)	23767	20408	11139	11722	13368	20784
100	9	4	36.72	36.72	34.79	34.79	4.31	4.77	3386.70	507.64	1106.28	1203.65	698.44	164.79	121859	20229	30277	20402	13817	7294
100	×	4	13.44	13.44	11.93	11.93	11.47	12.93	1712.80	(1.62)	3393.36	(0.21)	3577.48	2669.71	143447	187751	115416	91689	133343	154873
100	10	4	13.48	13.48	11.98	11.98	11.98	13.48	(2.29)	(2.14)	(3.88)	(1.46)	(2.42)	(0.82)	150628	127016	61970	70603	47248	164907
100	9	9	21.92	21.92	17.42	17.42	13.98	14.99	(0.58)	(0.01)	(0.01)	(0.58)	1718.09	1618.76	90554	77487	56953	24518	14288	17998
100	×	9	13.27	13.27	9.21	9.21	9.21	13.27	(0.71)	(0.09)	(0.32)	3097.56	(0.91)	(0.64)	72710	67244	35361	40838	80211	71418
100	10	9	13.27	13.27	9.21	9.21	9.21	13.27	(0.93)	(1.19)	(0.81)	(0.73)	(0.81)	(0.73)	48044	44638	31362	31477	21707	52541
100	9	x	20.60	20.60	13.74	13.74	12.86	19.86	(1.25)	(0.47)	(0.04)	(2.09)	(2.89)	(1.35)	28266	29342	28226	15084	18162	19170
100	×	x	17.01	17.01	10.24	10.24	10.24	17.01	(0.60)	(0.78)	(0.76)	(2.54)	(1.35)	(1.71)	25717	19918	13032	10990	14204	20374
100	10	8	17.01	17.01	10.24	$10.24 \ 10.24$	10.24	17.01	(1.10)	(1.22)	(1.29)	(2.77)	(3.31)	(1.22)	22651	17197	11800	10205	11563	18160
150	9	4	36.72	36.72	34.79	34.79	4.31	4.77	419.46	290.98	801.11	1717.41	224.96	178.18	23992	14481	38333	27987	4510	7150
150	8	4	13.44	13.44	11.93	11.93	11.47	12.93	2384.95	(0.62)	(1.68)	932.03	(0.53)	1703.53	118142	116417	99826	32216	110576	113171
150	10	4	13.48	13.48	11.98	11.98	11.98	13.48	(2.10)	(2.74)	(2.99)	(1.81)	(2.42)	(2.40)	118407	118407 194520 49374	49374	75712	64753	86667
150	9	9	22.45	22.45	17.82	17.82	14.60	15.60	(0.72)	(0.01)	(0.00)	(2.17)	3056.64	1750.43	59335	83396	46790	19144	25628	22813
150	×	9	14.78	14.78	10.49	$10.49 \ 10.49$	10.49	14.78	(1.40)	(1.33)	(1.48)	(1.35)	(0.83)	(1.41)	80001	83067	53054	39108	43934	53446
150	10	6	14.78	14.78	10.49	10.49	10.49	14.78	(1.86)	(1.61)	(1.45)	(1.44)	(1.53)	(1.71)	48006	61615	24584	26854	36213	61914
	Average		18.72	18.72	14.81	14.81	10.44	13.73	3101.29	3072.64	3072.64 3247.35	3221.22	3019.44	2794.21	68858	65801	43007	33965	38358	57922
Avg.	Avg. Opt. Gap(%)	(%							(1.04)	(0.92)	(1.05)	(1.19)	(1.24)	(0.93)						
# of S	# of Solved Ins.(/24)	(24)							9	4	4	ъ	7	6						
# of Bes	of Best Solutions(/24)	i(/24)			13	13	24		4	33	1	IJ	4	x		1	S	10	7	1

Table A.4: LP gap, CPU time/ optimality gap and number of nodes of ProfitVLP in **D** type instances

51

APPENDIX A. TABLES OF COMPUTATIONAL RESULTS

	14 CM5	0 6198	17 8852	629	0 1710	0 752	0	5 3298	380	134	7 2866	6 49649	1141	8 1069	5 1163	0	2 35885) 14182	2267	4 5142	6 9365	1 800	0 1854	9 18144	l 4892	8 7099			6
des	3 CM4	7 8610	9 2597	715	7 1910	3 570	0	9 625	10	0	3 6647	4 6046	544) 2328	425	0	8 8222	800	30	8 6324	3 6276	611	5 2730	808	491	0 2388			10
of Not	2 CM3	2 11277	15729	654	2097	1333	0	2 31589	x	0	13453	3 35824	069	2710	4594	0	4 27678	557	103	9 8928	5 40893	576	1955	3 963	480	8420			ы
Number of Nodes	CM2	25542	71304	745	3692	685	0	40052	0	0	9254	66906	257	2647	830	0	30454	40	519	18429	11125	968	3592	18036	642	12738			9
Д	CM1	13054	53197	811	2807	843	20	32144	250	150	15631	29950	945	2951	2435	67	30739	1615	7030	15466	5313	1275	2363	78776	18242	13170			-
	CM0	19701	17862	863	4634	1907	211	233085	0	80	16737	32944	1326	1473	1426	381	29703	12777	1516	8900	44811	1085	21164	24278	3086	11248			-
()	CM5	113.41	203.96	8.96	53.68	42.57	0.61	148.13	33.74	3.02	88.21	888.37	16.25	52.00	50.73	1.28	3014.50	(0.33)	202.88	92.46	235.52	13.19	146.91	505.64	278.16	408.10	(0.01)	23	c
CPU Time (sec.)/Optimality Gap(%)	CM4	146.60	51.14	15.63	79.11	68.32	1.71	106.77	12.14	5.64	131.53	78.93	7.65	97.16	32.86	1.66	952.09	199.87	22.89	137.16	113.91	13.13	130.49	171.76	158.56	114.03	(0.00)	24	1
Optimali	CM3	246.76	260.04	24.50	88.92	99.65	2.69	(0.30)	13.34	6.94	339.86	543.48	15.94	112.94	214.85	3.38	(0.57)	142.29	20.53	242.02	1361.99	8.33	87.50	198.72	135.33	473.76	(0.04)	22	Ŧ
ne (sec.)/	CM2	374.14	801.58	14.79	89.38	39.93	1.74	(0.29)	4.00	5.78	183.54	1687.35	7.91	75.78	87.82	2.19	(0.57)	25.54	73.83	262.52	238.58	20.99	108.43	759.93	189.82	510.66	(0.04)	22	c
CPU Tin	CM1	175.16	811.10	10.26	61.67	49.29	3.54	1996.49	16.66	13.68	209.80	696.36	19.96	63.87	67.67	4.77	(0.63)	220.31	625.47	189.55	88.44	23.46	96.44	(0.34)	916.46	565.15	(0.04)	22	÷
	CM0	261.90	255.51	17.32	85.34	71.74	6.21	1329.72	3.79	5.16	219.06	571.61	22.05	44.16	58.18	8.88	3412.02	(0.88)	131.76	105.72	947.77	19.76	387.94	765.14	188.60	521.64	(0.04)	23	Ċ
	CM5	1.91	7.26	5.64	5.78	9.27	0.00	9.21	0.00	0.00	1.91	7.26	5.64	5.78	9.44	0.00	9.78	0.33	0.00	1.91	7.26	5.64	6.30	12.38	6.99	4.99			c
	CM4	1.91	1.58	0.62	1.31	1.15	0.00	0.44	0.00	0.00	1.91	1.58	0.62	1.31	1.32	0.00	0.96	0.00	0.00	1.91	1.58	0.62	1.78	3.69	5.08	1.22			č
p (%)	CM3	53.83	22.71	5.66	30.34	9.27	0.00	9.21	0.00	0.00	53.70	22.69	5.66	30.34	9.44	0.00	9.78	0.00	0.00	53.62	22.69	5.66	29.10	10.35	5.08	16.21			1
LP Gap (%)	CM2 CM3	53.83	22.71	5.66	30.34	9.27	0.00	9.21	0.00	0.00	53.70	22.69	5.66	30.34	9.44	0.00	9.78	0.00	0.00	53.62	22.69	5.66	29.10	10.35	5.08	16.21			1
	CM1	53.24	23.05	5.77	30.68	9.27	0.00	9.21	0.00	0.00	54.24	23.05	5.77	30.68	9.44	0.00	9.78	0.88	0.00	54.24	23.05	5.77	31.32	12.38	6.99	16.66			ŀ
	CM0	54.24	23.05	5.77	30.68	9.27	0.00	9.21	0.00	0.00	54.24	23.05	5.77	30.68	9.44	0.00	9.78	0.88	0.00	54.24	23.05	5.77	31.32	12.38	6.99	16.66			ł
	p	4	4	4	9	9	9	x	x	x	4	4	4	9	9	9	x	x	x	4	4	4	9	9	9		(%)	24)	
Parameters	k^{max}	9	×	10	9	×	10	9	×	10	9	×	10	9	×	10	9	×	10	9	×	10	9	×	10	Average	Avg. Opt. Gap(%)	# of Solved Ins.(/24)	
Pa	ρ_{min}	50	50	50	50	50	50	50	50	50	100	100	100	100	100	100	100	100	100	150	150	150	150	150	150		Avg.	# of Sc	:

Table A.5: LP gap, CPU time/ optimality gap and number of nodes of *Coverage VLP* in \mathbf{A} type instances

APPENDIX A. TABLES OF COMPUTATIONAL RESULTS

Ļ	Parameters			LP (LP Gap (%)			-	CPU Tim	CPU Time (sec.)/Optimality $Gap(\%)$	Optimalit	y Gap(%			Ń	umber o	Number of Nodes		
ρ_{min}	k^{max}	p	CM0 CM1	1 CM2	2 CM3	3 CM4	t CM5	CM0	CM1	CM2	CM3	CM4	CM5	CM0	CM1	CM2	CM3	CM4	CM5
50	9	4	54.24 54.24	1 53.75	5 53.75	1.91	1.91	193.65	249.32	443.58	229.15	182.90	93.13	16136	19605	26851	9866	5938	5315
50	8	4	23.05 23.05	5 22.69	9 22.69	1.58	7.26	217.40	250.88	1371.16	326.72	100.75	653.08	15880	24977	58418	19454	6358	28674
50	10	4	5.77 5.77	7 5.66	5.66	0.62	5.64	18.51	16.73	14.12	8.75	19.83	5.49	1125	898	658	622	968	498
50	9	9	30.68 30.68	8 30.34	4 30.34	1.31	5.78	85.60	70.00	108.38	91.01	85.15	92.55	5087	3068	4460	2661	2254	3648
50	8	9	9.27 9.27	7 9.27	9.27	1.15	9.27	46.20	58.52	70.34	126.16	35.54	43.66	1618	962	666	920	410	733
50	10	9	0.00 0.00	0 0.00	0.00	0.00	0.00	2.78	3.43	1.96	1.58	1.49	1.62	20	49	0	0	0	0
50	9	×	9.21 9.21	1 9.21	1 9.21	0.44	9.21	993.46	2832.36	(0.31)	997.20	106.86	85.75	13939	34035	38492	10581	974	874
50	8	×	0.00 0.00	0 0.00	0 0.00	0.00	0.00	71.84	73.22	9.42	26.15	17.15	23.76	845	786	20	50	10	400
50	10	×	0.00 0.00	0 0.00	0 0.00	0.00	0.00	10.22	6.66	4.26	5.42	5.18	6.82	220	59	0	0	0	190
100	9	4	54.24 54.24	4 53.65	5 53.65	1.91	1.91	193.65	351.52	270.66	303.63	138.82	58.47	16136	24076	15971	10857	7955	2824
100	×	4	23.05 23.05	5 22.69	9 22.69	1.58	7.26	217.40	2141.64	300.77	1272.10	77.90	446.48	15880	129486	23257	73610	5558	24236
100	10	4	5.77 5.77	7 5.66	5.66	0.62	5.64	17.30	22.74	11.46	20.61	15.67	11.45	978	1065	714	653	968	902
100	9	9	30.68 30.68	8 30.28	8 30.28	1.31	5.78	67.19	63.94	113.23	106.41	76.37	65.47	3114	2682	6621	2508	1761	2360
100	8	9	9.44 9.44	4 9.44	9.44	1.32	9.44	108.21	79.64	145.11	173.98	52.91	100.91	3842	2313	1113	1836	521	4664
100	10	9	0.00 0.00	0 0.00	0 0.00	0.00	0.00	11.27	14.70	2.25	2.51	1.48	5.31	418	492	0	0	0	89
100	9	×	9.78 9.78	8 9.78	3 9.78	0.96	9.78	(0.44)	(0.46)	(0.47)	(0.36)	2115.30	2009.85	29528	29173	31932	21391	15394	18291
100	8	×	0.88 0.00	0 0.00	0 0.00	0.00	0.00	(0.88)	1016.32	2016.47	686.79	481.46	1789.27	20365	11097	6476	1574	1477	10274
100	10	8	0.00 0.00	0 0.00	0.00	0.00	1.14	725.10	343.28	42.00	11.03	58.59	(1.14)	7686	3190	100	20	19	15575
150	9	4	54.24 54.24	453.62	2 53.62	2 1.91	1.91	113.95	233.72	227.44	259.32	95.73	73.11	7836	18333	12214	10286	3105	4149
150	œ	4	23.05 23.05	5 22.69	9 22.69	1.58	7.26	1028.98	598.60	160.18	232.00	71.69	18.17	68400	32616	8133	13838	4084	5525
150	10	4	5.77 5.77	7 5.66	3 5.66	0.62	5.64	23.13	23.08	9.60	10.04	8.53	18.17	1200	1301	491	466	645	776
150	9	9	31.32 31.32	2 28.23	3 28.23	1.76	6.30	100.34	52.67	162.01	62.76	64.42	96.12	2090	1542	7745	1524	1489	2055
150	8	9	13.14 13.14	4 10.29	9 10.29) 4.12	13.14	310.53	312.13	879.47	195.80	107.40	450.92	9465	3899	14650	903	457	4974
150	10	6	8.34 8.34	4 5.63	3 5.63	5.55	8.34	545.08	269.56	348.89	157.98	653.42	208.04	5125	2907	773	438	1353	2306
	Average		16.71 16.71	71 16.19	9 16.19	1.26	5.11	512.58	528.53	579.71	371.14	190.60	420.15	10497	14525	10823	7669	2571	5806
Avg.	Avg. Opt. Gap(%)	()						(0.06)	(0.02)	(0.03)	(0.02)	(0.00)	(0.05)						
# of S	# of Solved Ins.(/24)	24)						22	23	22	23	24	23						
# of Be	# of Best Solutions(/24)	/24)	5 6	9	9	24	×		ŝ	2	7	6	×			З	9	16	4

Table A.6: LP gap, CPU time/ optimality gap and number of nodes of *Coverage VLP* in **B** type instances

53

	r_{max}		UND		CANO	CIRO		JAN	UND	CAAT	CARD	CARL CARD CARD CARL	CAAL		CIND		CINO CINO	CIND		CIAR
ρ_{min}	<i>k</i>	d	CMU	CMI	CMZ	CM3	CM4	CMD	CMU	CMI	CMZ	CM3	CM4	CMD	CMU	CMI	CMZ	CM3	CM4	CMD
50	9	4	25.73	25.73	25.71	25.71	1.19	1.19	432.22	900.92	3165.87	1843.91	150.42	158.94	25535	48016	165456	43576	5481	7935
50	×	4	2.12	2.12	2.12	2.12	1.73	1.73	17.82	32.34	34.28	45.52	22.19	43.85	3541	8041	5304	5359	3325	7035
50	10	4	0.00	0.00	0.00	0.00	0.00	0.00	0.45	0.50	0.81	0.94	0.91	0.46	0	0	0	0	0	0
50	9	9	9.33	9.33	9.32	9.32	4.20	4.40	786.90	485.58	725.56	1299.77	533.40	261.94	43195	15868	14914	19261	5390	4445
50	×	9	0.00	0.00	0.00	0.00	0.00	0.00	0.48	0.56	0.93	0.88	0.96	0.46	0	0	0	0	0	0
50	10	9	0.00	0.00	0.00	0.00	0.00	0.00	0.53	0.67	06.0	0.96	0.73	0.67	0	0	0	0	0	0
50	9	x	3.07	3.07	3.01	3.01	1.34	2.54	56.66	62.70	96.86	144.78	82.68	105.36	3140	3299	2386	2468	1164	5045
50	×	×	0.04	0.04	0.02	0.02	0.02	0.04	2.06	1.45	0.64	0.79	0.82	1.38	163	40	0	0	0	20
50	10	×	0.04	0.04	0.02	0.02	0.02	0.04	5.09	4.43	0.78	1.02	1.00	6.75	456	418	0	0	0	486
100	9	4	25.73	25.73	25.71	25.71	1.19	1.19	342.98	379.13	477.49	1277.67	91.70	140.39	20271	19062	17330	30092	2723	7229
100	×	4	2.12	2.12	2.12	2.12	1.73	1.73	85.01	25.16	14.24	29.73	15.64	92.02	11960	3464	1240	4053	1927	27160
100	10	4	0.00	0.00	0.00	0.00	0.00	0.00	1.19	0.92	0.87	0.87	1.22	0.56	0	6	0	0	0	0
100	9	9	9.33	9.33	9.32	9.32	4.20	4.40	284.11	541.96	388.66	1703.63	475.63	237.37	10200	13656	10011	23266	4724	4902
100	×	9	0.00	0.00	0.00	0.00	0.00	0.00	0.42	1.56	1.02	1.02	0.81	0.53	0	57	0	0	0	0
100	10	9	0.00	0.00	0.00	0.00	0.00	0.00	4.08	0.60	1.26	1.08	1.21	2.44	330	0	0	0	0	39
100	9	8	3.56	3.56	3.13	3.13	1.76	3.09	196.36	273.46	191.69	180.66	192.90	170.01	8225	17602	4506	2313	1987	8702
100	×	8	0.88	0.88	0.40	0.40	0.38	0.88	11.23	11.54	10.08	6.99	1.41	12.65	482	581	43	28	0	474
100	10	8	0.88	0.88	0.40	0.40	0.40	0.88	13.58	18.82	25.41	17.09	4.97	14.22	533	209	415	170	12	525
150	9	4	25.73	25.73	25.71	25.71	1.19	1.19	367.43	383.30	1142.58	2294.78	172.68	91.51	17763	18110	61517	64122	5660	4664
150	×	4	2.12	2.12	2.12	2.12	1.73	1.73	73.07	38.82	12.76	61.09	79.50	11.40	6277	4756	1314	6003	9639	1095
150	10	4	0.06	0.06	0.06	0.06	0.06	0.06	1.48	5.31	3.39	4.54	2.66	7.63	528	667	972	558	230	1002
150	9	9	9.33	9.33	8.99	8.99	4.20	4.40	572.66	417.78	585.98	1927.39	473.40	267.09	15987	10033	10880	19465	4232	6283
150	×	9	0.13	0.13	0.06	0.06	0.06	0.13	4.86	2.34	3.61	1.16	1.06	8.42	283	64	20	0	0	474
150	10	9	0.13	0.13	0.06	0.06	0.06	0.13	5.03	6.50	1.32	1.36	1.56	5.78	457	402	0	0	0	332
4	Average		5.02	5.02	4.93	4.93	1.06	1.24	135.70	149.85	286.96	451.98	96.23	68.41	7118	6869	12346	9197	1937	3660
Avg. (Avg. Opt. Gap(%)	(%							(0.00)	(0.00)	(0.00)	(0.00)	(0.00)	(0.00)						
# of So	# of Solved Ins.(/24)	/24)							24	24	24	24	24	24						
# of Best	# of Best Solutions(/24)	3(/24)	7	2	12	12	24	13	S	Г	4		ÿ	x	л:	cr:	6	10	20	œ

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	CM5	4460	5086	0	8462	0	39	6319	342	400	81	6980	0	3494	474	61	18690	97678	118411	5010	8268	760	3302	240	0	12223			4
				0		J	က		ŝ	4(2 4881		-		4	9								2^{ζ}	•				
les	3 CM4	5 7610	1449	0) 5097	0	0	1366	0	0	7012	11227	0	1 5138	0	0	3219	952	1493	2 4178	4801	254	5708	0	0	2479			15
of Noc	CM3	20915	1497	0	36960	0	0	1808	0	0	47622	4738	0	26504	0	0	4794	515	1633	54512	1782	161	14116	0	0	9065			12
Number of Nodes	CM2	17870	4079	0	18273	0	0	3122	0	0	27070	1087	0	10579	0	474	8808	94567	60112	18728	6144	569	23610	20	0	12296			×
Z	CM1	34889	2734	0	10412	0	51	1902	270	255	23082	5577	0	14758	46	500	16979	69792	65763	17714	5394	559	8963	50	23	11655			33
	CM0	17552	7082	0	15258	70	69	3000	156	363	15638	6179	0	9873	365	486	35763	104629	117575	94078	1580	827	10803	141	0	18395			4
	CM5	92.84	47.08	0.52	669.14	1.30	1.25	119.09	3.69	5.31	110.99	45.60	0.54	186.58	2.98	2.94	395.33	(0.31)	(0.32)	105.06	70.16	6.35	187.72	7.82	0.81	385.98	(0.03)	22	ъ
$\operatorname{Gap}(\%)$	CM4	259.94	15.30	0.99	490.20	0.91	1.20	104.06	0.70	0.80	243.26 1	107.88	0.88	468.53 1	1.19	1.32	311.55 3	86.22	85.88	187.28 1	39.14	3.87	697.38 1	1.04	1.37	129.62	(00.0)	24	33
mality (<i>CM3</i> (758.12 2	11.86	0.92	2235.29 4	1.09	1.11	113.57 1	0.86	0.86 ($2111.85 \ 2_{\circ}$	38.84 10	0.86	1841.72 4	1.60	1.24	415.81 3	41.16 8	123.07 8	1900.28 1	13.44	2.53	1289.40 6	0.92	1.46	454.49 12)) (00.0)	24	9
CPU Time (sec.)/Optimality $\operatorname{Gap}(\%)$	<i>CM2</i> (598.64 75	35.59 1:	0.97 (510.66 22	0.90	0.98	113.23 11	1.06 0	0.86 (779.60 21	17.40 3	0.87 (633.62 18	1.17	5.35 1	206.31 41	(0.28) 4	(0.29) 12	447.40 19	40.80 1:	5.40 2	985.60 12	2.53 0	1.34 1	482.94 45	(0.02) (0	22	4
me (se																							-						
CPU Ti	CM1	609.85	19.55	0.42	349.39	0.51	1.88	36.32	2.92	3.19	430.85	36.73	0.48	637.17	1.58	5.59	321.45	(0.05)	(0.31)	345.84	60.46	6.56	363.12	1.72	1.60	434.89	(0.01)	22	4
)	CM0	353.54	47.49	0.41	565.19	1.16	2.04	48.02	2.39	4.06	334.94	22.64	0.56	269.34	3.58	5.05	420.18	(0.23)	(0.32)	1801.76	14.85	4.72	431.83	2.34	0.72	480.71	(0.02)	22	2
	CM5	1.19	1.73	0.00	4.40	0.00	0.00	2.67	0.04	0.04	1.19	1.73	0.00	4.40	0.00	0.00	1.82	0.68	1.21	1.19	1.73	0.06	4.40	0.13	0.13	1.20			14
	CM4	1.19	1.73	0.00	4.20	0.00	0.00	1.46	0.02	0.02	1.19	1.73	0.00	4.20	0.00	0.00	1.82	0.64	0.64	1.19	1.73	0.06	4.20	0.04	0.04	1.09			24
p (%)	CM3	25.71	2.12	0.00	9.32	0.00	0.00	3.12	0.02	0.02	25.71	2.12	0.00	9.32	0.00	0.00	2.99	0.64	0.64	25.71	2.12	0.06	8.98	0.04	0.04	4.94			13
LP Gap	CM2	25.71	2.12	0.00	9.32	0.00	0.00	3.12	0.02	0.02	25.71	2.12	0.00	9.32	0.00	0.00	2.99	0.64	0.64	25.71	2.12	0.06	8.98	0.04	0.04	4.94			13
	CM1	25.73	2.12	0.00	9.33	0.00	0.00	3.20	0.04	0.04	25.73	2.12	0.00	9.33	0.00	0.00	3.64	1.21	1.21	25.73	2.12	0.06	9.27	0.13	0.13	5.03			2
	CM0	25.73	2.12	0.00	9.33	0.00	10.91	3.20	0.04	0.04	25.73	2.12	0.00	9.33	0.00	0.00	3.68	1.21	1.21	25.73	2.12	0.06	9.33	0.13	0.13	5.49			9
	d	4	4	4	9	9	9	x	x	x	4	4	4	9	9	9	×	x	×	4	4	4	9	9	9		(%)	/24)	s(/24)
Parameters	k^{max}	9	×	10	9	8	10	9	8	10	9	×	10	9	×	10	9	8	10	9	x	10	9	8	10	Average	Avg. Opt. Gap(%)	# of Solved Ins.(/24)	of Best Solutions(/24)
Pa	$ ho_{min}$	50	50	50	50	50	50	50	50	50	100	100	100	100	100	100	100	100	100	150	150	150	150	150	150		Avg.	# of Sc	# of Bes