

**FLOW INITIATION
IN
SOFTWARE DEFINED NETWORKING**

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FLOW INITIATION IN SOFTWARE DEFINED NETWORKING

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ABSTRACT

FLOW INITIATION IN SOFTWARE DEFINED NETWORKING

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With today's technology requirements, computer networks and specifically the Internet is being expected to provide mobile, distributed and constantly changing services to its users. Forwarding middle boxes used in the industry nowadays are configured to have their low-level switching operations (e.g. packet handling), tightly coupled to their high-level control definitions and algorithms. This fact has contributed in slowing down the innovation in computer networks. Software Defined Networking has recently been introduced as an abstraction between those low-level and high-level functionalities by introducing a standard protocol to act as an interface, which divides control and data planes in middle-boxes. There are a number of challenges related to SDN most of which are still treated with conventional network or computer science techniques, however some

challenges unique to SDN paradigm such as flow initiation overhead and controller handling in networks also exist. The present study includes a comprehensive literature review of the current state-of-the-art techniques, which tackles these challenges and proposes a hybrid mechanism to address the flow initiation issue for minimizing the overhead and the delay. This proposal uses the unified network map available on controllers to form a-priori knowledge for switches for making better forwarding decisions during the flow initiation process.

KEYWORDS: Software Defined Networking, Service Centric Networking, Flow Initiation, Multiple Controller Handling

ÖZ

YAZILIM TANIMLI AĞLARDA AKIŞ BAŞLATMA

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Günümüz teknoloji gereksinimleri ile, bilgisayar ağlarının ve özellikle İnternetin kullanıcılarına, mobil, dağıtılmış ve sürekli değişen hizmetler sunabilmesi bekleniyor. Yönlendirme kutuları ve arayüzlerinde, düşük seviyeli işlemler yüksek-seviyeli kontrol işlemleri ile yüksek derecede tümleşik olarak tasarlanmıştır. Bu da bilgisayar ağları alanında yaşanan inovasyon hızını yavaşlatmıştır. Yazılım Tanimli Ağlar (YTA) yakın zamanda kontrol ve veri düzlemleri arasında bölünme sağlayan bir arayüz standardı olarak ve bu düşük düzeyli ve üst düzeyli işlevler arasında bir soyutlama katmanı olarak ortaya konmuştur. Çoğu YTA sorunları hala eski ağ veya bilgisayar bilimleri teknikleri ile çözülmektedir ancak akış başlatılması ve denetleyici yönetimi gibi SDN'e özgü başka sorunlar da vardır. Bu çalışma, bu zorlukları ele alan kapsamlı bir literatür taraması içerir ve akış başlatılması

sorununu gidermek için de hibrit bir mekanizma önerir. Bu öneri akışın başlatılması sürecinde anahtarlar için daha iyi yönlendirme kararları almayı sağlayan apriori bilgi oluşturmak için de denetleyicilerde bulunan birleşik ağ haritasını kullanır.

ANAHTAR KELİMELER: Yazılım Tanımlı Ağ, Hizmet Odaklı Ağ, Akış Başlatma, Çoklu Denetleyici Yönetimi

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... To My Professor

and Mentor

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LIST OF SYMBOLS AND/OR ABBREVIATIONS

Table 1: List of Abbreviations

Symbol Abbreviation	Description
CCN	Content Centric Network
CLI	Command Line Interface
DNS	Domain Name Server
GUI	Graphical User Interface
HYB	Hybrid Flow Initiation
ICN	Information Centric Network
IP	Internet Protocol
OFM	Original Flow Message
OVSF	Open Virtual Switch Kernel
PIM	Packet In Message
RCP	Routing Control Protocol
SCN	Service Centric Network
SDN	Software Defined Network
TCP	Transport Control Protocol
UDP	User Datagram Protocol
WAN	Wide Area Network

1 CHAPTER ONE

INTRODUCTION

1.1 Introduction to the problem

Computer networks, as a type of communication infrastructure, are one of the most important technical aspects of how we implement and use different types of computerized information systems and distributed computing along with many other technologies. In our survey conducted in order to find out fundamental requirements of contemporary technologies, it became evident that many technologies such as cloud computing, pervasive and embedded computing and mobile computing, etc. need a basis of collaborative, distributed and specialized processing of data. Meaning that the processing of data in order to provide information is required to be distributed to ensure reliability and accessibility, be in collaboration to provide context awareness and knowledge discovery, be specialized so that each individual acquiring and processing data can perform its optimal task instead of using a general purpose centralized computer. A combination of 'hardware and software technologies', 'algorithms', and 'frameworks and standards' all based on the above mentioned basis provide opportunities for secure, pervasive and powerful computation to address fundamental requirements of contemporary technologies.

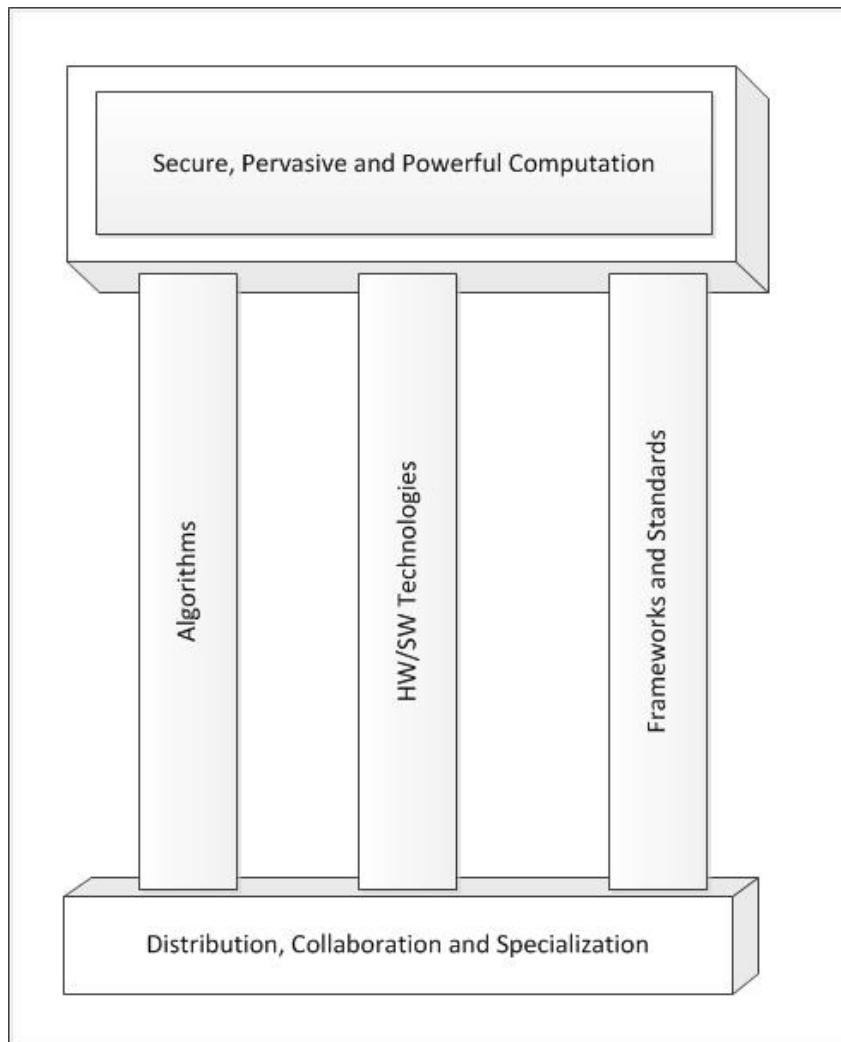


Figure 1: Requirements and basis for contemporary technologies

Computer networks were initially designed for serving fixed hosts with topology dependent addresses, which drastically differs from what they are used for nowadays (Nordstrom, Rexford, & Freedman, 2012). The internet as the largest network of networks is being used for accessing services that run anywhere from mobile phones and huge servers to a collection of dynamically changing heterogeneous and/or virtual machines. Demands of technologies such as cloud computing, mobile and embedded-distributed computing, etc. enforce a drastic change in computer networks as the main enabler of today's state-of-the-art

technologies. This is mainly the reason why many coping mechanisms such as load balancers, DNS servers, etc. are developed to bridge the gaps between the initial design of the computer networks and its contemporary use (Rexford, 2012).

On the other hand network middle boxes, which are responsible for main operations in networks, namely packet forwarding, are proprietary and closed sourced and the rate of innovation is almost completely dependent on the producer company thus new architectural changes take a lot of time to be materialized as fundamental solutions for networking challenges.

Contrary to computer software and operating systems, computer networking architecture and the underlying principles of how they operate did not experience a serious evolution during the last four decades. New paradigms have started to emerge in late 90's to cope with shifts in telecommunication network consumer and developer demands (McKinney, Montgomery, Ouibrahim, Sijben, & Stanaway, 1998) but computer networks in particular have started to play their part in this evolution in 2005 (Feamster, Balakrishnan, & Rexford, 2004). Principles of Software Defined Networking and new paradigms such as Service Centric Networking (SCN) are promising in tackling these issues.

Some of these new methods, such as Routing Control Protocol (RCP) and "Serval" project (Nordstrom, Rexford, & Freedman, 2012), have been proposed as new architectures and concepts, to tackle networking challenges. Some, such as SDN, have been proposed as standards and frameworks to enable such innovations and to provide pace and power to research in computer networks.

1.1.1 Software Defined Networking

One of the major bottlenecks in computer networks research is that the network programmers are bound with the capabilities that are provided by middle box

producers. Other than research and innovation blockage, computer network middle boxes control the data flow in network in a completely decentralized manner. This, along with pros, introduces some drawbacks for example creates a lot of maintenance issues for operators and service providers. Middle boxes are configured manually thus controlling the network becomes more error prone (Brandon, 2013). Operators and administrators try every method to keep their network integrated: via network manager applications, etc. (Kim & Feamster, 2013).

One reason why computer networks have not changed as much as other computer technologies in their principles and methods may be that switches are not as widely configured and administered by everyone as computers and software are. Switches are mainly customized and configured in larger networks by specialists and until a decade ago current network architecture and methods were sufficient for most of their operations. Thus demand has been weak to stir a revolution in the proprietary model of business in network solution companies. Providing a proprietary middle box with a Command Line Interface (CLI) or other types of GUI's as its operating systems interface (e.g. cisco ios) has made it quite hard for network policy makers and protocol designers to innovate.

Another reason is particularly due to lack of an abstraction between simple switch fabric operations (data plane) and high level functions (control plane) that operators employ to instruct routers to perform consistent to their policies. The absence of decoupled data and control planes makes it difficult to change or introduce new functionalities in switches without knowing and/or changing the underlying data flow mechanisms. Software Defined Networking (SDN) overcomes these limitations. Introducing a standard abstraction of low level switch fabric operations, it proposes that the control plane should be decoupled

from the switch to provide flexible and scalable manipulation of control plane without changing or even knowing the data flow mechanism of the switch fabric.

Emergence of “Software Defined Networking” as an evolution of concepts introduced in 2005 brought a serious opportunity of a practical and drastic change in computer networks for researchers, developers and even proprietary middlebox producers by separating the decision and policy making functionality of middleboxes from their packet forwarding features. For this it may be possible to drive an analogy with the emergence of computer operating system in 1950’s for UNIVAC and IBM. In computer systems CPU’s have low level functionalities such as adding, reading and writing of bit level data and with the introduction of operating systems an abstraction between these low level operations and high-level applications was introduced. Similarly routers and generally switch fabric of middleboxes have low-level operations of dropping, forwarding or de-multiplexing of incoming packets. SDN in a similar way has introduced a hardware abstraction of the system for computer networks.

Dependent control-data planes imply that they can hardly be developed independently and freely. Since data and control planes are tightly coupled a change in control-plane functionality implies a change in the forwarding mechanism. A local abstraction between data and control planes is hard to standardize due to different implementations by different vendors. There also is an innate market resistance by vendors due to marginal profits of proprietary operating systems from certificates and licenses as well as professional training programs, etc.

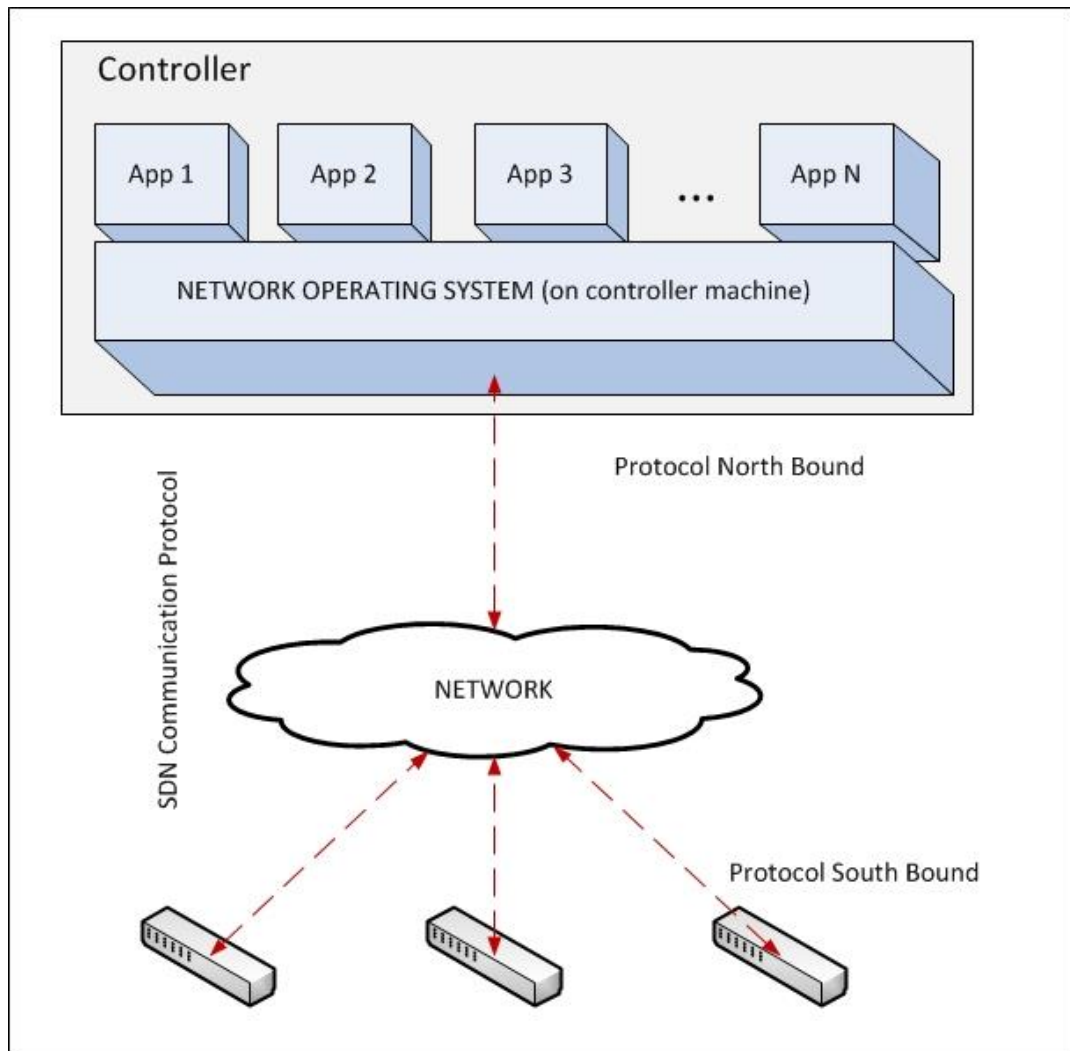


Figure 2: Software Defined Network Architecture schema. Communication between switches and the controller is maintained by a controller protocol and applications are developed upon network operating system. (image regenerated based on the present study, literature review and authors perception of SDN and its underlying components)

SDN principles imply that the control functionalities of several switches can be moved to a remote server, commonly known as the “controller server” and can be presented to the switch fabric by means of standardized protocols and virtualization technologies remotely. Software Defined Networking introduces several advantages such as fine-grained manipulation power over control functions of routers in a network, faster and cheaper processes in the design of

new architectures and protocols as well as in testing their implications. However these advantages also introduce new challenges.

These challenges broadly include providing a secure, reliable, accessible and dynamic framework in which switches can interact with remote control planes or namely “Controllers”. Specifically, challenges such as data flow initiation, scalability issues of large networks, controller discovery, switch-controller communication security, etc. are some existing challenges.

1.1.2 Service Centric Networking

One of the major changes came through rethinking the address scheme in networks. Today’s networks operate based on an address scheme (IP addresses), which is defined by the location of each node throughout the topology. This address is then used to identify interfaces and sockets as well as to de-multiplex packets (Nordstrom, Rexford, & Freedman, 2012). This scheme initially was thought out to provide nodes with a communication channel rather than services and contents. IP addresses, along with TCP/UDP port numbers and protocols form a five-tuple identifier, which identifies a connection or a flow of data between two nodes in today’s networks, which clearly makes the connection completely dependent on the location of the serving and receiving nodes and that is basically why it is hard to change the location of either end points (Rexford, 2012) and why it is hard to define more than one flow of data within a connection. This means when a server or client is dislocated or relocated, as in case of a virtual machine migration for instance, the whole connection has to start all over again. This fact creates a lot of inconveniences for needs of operators and users of networks nowadays. Many servers in data centers are being run on virtual machines and hosts on cloud, which change their location in network topology and also geographically. Many users use hand-held devices to

receive a particular service and constantly switch between devices to access different aspects of a service (e.g. accessing streaming media on mobile).

A lot of techniques were created to give the illusion of an integrated and constant connection in case of server relocation and failure and/or client on the move and clients agnostic to the location of computers providing the service they use cases. These techniques are most of the time unreliable and need a lot of hardware and management investment to function properly.

In a simple distributed or replicated service over the internet, as shown below, whenever an instance of a service fails or migrates and whenever another instance is sprung up, load balancer, wide area address resolution system and domain name service needs to be updated. This issue in turn produces management challenges as in most types of distributed systems.

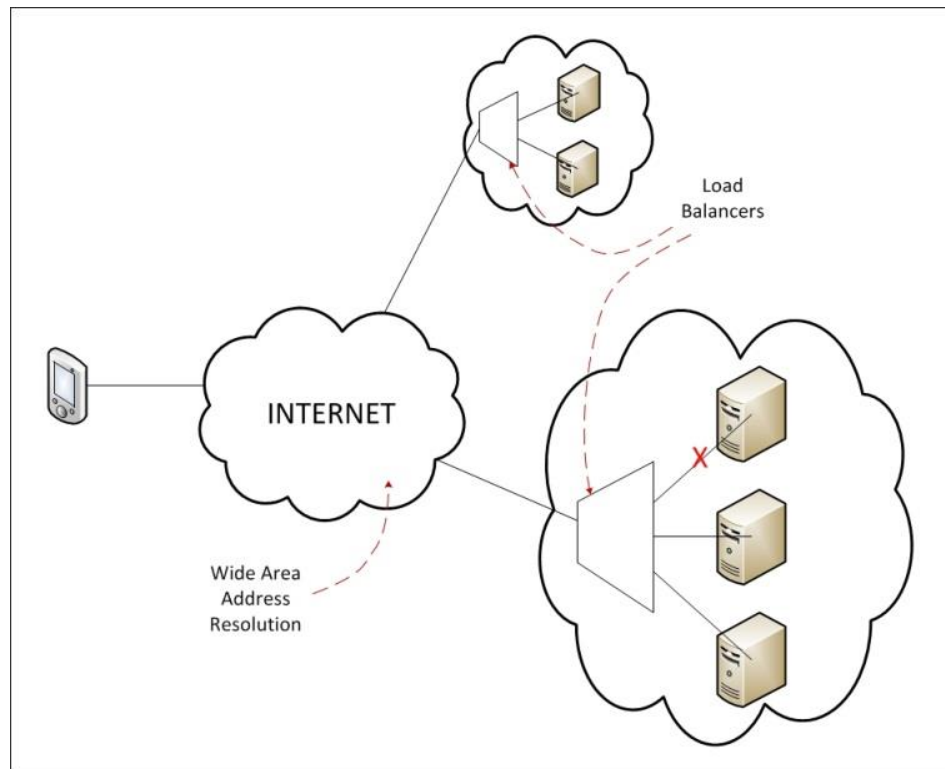


Figure 3: Load balancer management overhead. Upon failure of a distributed/replicated service instance, load balancer and WAN address resolution directories must be updated. (Image regenerated from source: Jen Rexford's speech on Software defined service-centric network (Rexford, 2012))

Likewise, in case of virtual machine migration since the serving machine needs to maintain its IP address, it is either restricted to operate in a single layer-two subnet, or to use triangular routing techniques to redirect packets to a service that has been relocated.

Many other examples of such scenarios conclude that when a server is dislocated, which is the case with many mobile and virtual machines in networks, the connections and subsequently services to users have to be re-established.

In order to better support dynamic services for mobile and multi-homed devices a better abstraction between service resolution policy and service resolution mechanism is needed alongside abstractions that will allow service name

definition to be independent of IP addresses and port number. These in turn allow a better separation of control and data planes in a very similar way to software defined networking.

Few recent attempts to change network addressing schemes have introduced information or context as the primary entity in networks instead of servers and clients involving in a connection. Researchers in this field focus on the content that is being exchanged rather than the parties exchanging it. Naming contents and building routing protocols based on them will provide a better solution for content replication, content movement and load balancing as well as location awareness. "Information Centric Networking" or simply ICN is a concept also known as Content Oriented Networking, which has sprung several projects around the world such as CBCB (Carzaniga, Wolf, & Rutherford, 2004), DONA (Koponen, Chawla, & Chun, 2007) and PERSUIT (Lagutin, Visala, & Tarkoma, 2010) and MDHT (D'Ambrosio & et., 2011). Roots of ICN or Content Oriented Networking lies in a study back in year 2000 when Cheriton introduced the concept of Name-based routing in a project called TRIAD (Cheriton & Gritter, 2000).

A conceptually close but more inclusive approach was Service Centric Networking (SCN), which first emerged in telecommunication networks in 1998, where different parties such as Brokers and Retailers of services were introduced to create an abstraction where access networks were no longer defining and providing the service but instead they provided only the connectivity to service providers. This framework was introduced by Bell Labs using an architecture called TINA (McKinney, Montgomery, Ouibrahim, Sijben, & Stanaway, 1998).

One reason why the author in this study has chosen service centric networking as a more inclusive approach to investigate is the convenience of conceiving all sorts of content and information dissemination as a type of service instead of treating

all types of service as a type of content. (e.g. from a high-level user point of view mere controlling of a remote surveillance camera might not explicitly convey an information or content exchange). On the other hand Content Centric Networking (CCN) studies like DONA and TRIAD do not tackle challenges such as end-host stacks, server migration and host network integration (Freedman, et al., 2010).

1.1.3 Serval

One of the most recent studies in the field of Service Centric Networking is a project called “Project Serval” investigated by Mike Freedman and Jen Rexford along with many other Ph.D. and Post-Doc contributors in the Princeton University. In a single framework Serval aims to provide an architecture in which services are identified by a service name and also flows that take those services on network are identified by different identifiers called “flow identifier”. These identifiers are completely independent of IP addresses, i.e., the service is free of the locations where end points are located. In serval, the authors are also defining a new layer in networking stack above the unchanged “Networking Layer” called Service Access Layer (SAL). Without this layer Serval’s attempt would be merely replacing IP with a new identifier which will not help with the vision of service centric networking. Here ‘*service*’ is a process or a group of processes offering the same functionality and a ‘*flow*’ is the traffic in the network carrying the service. A flow needs to be dynamic in order to change its parameters during a single service connection.

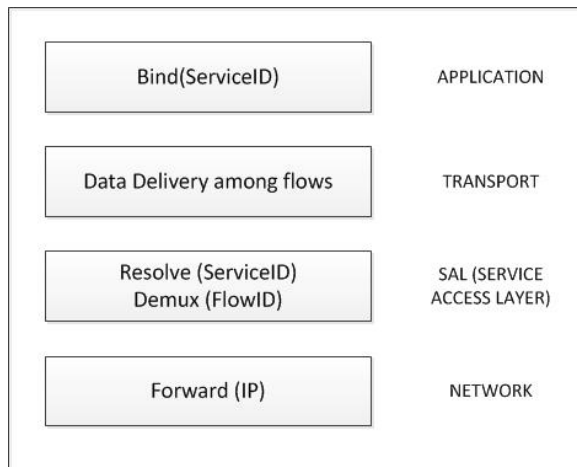


Figure 4: Serval architecture overview: regenerated from source: Serval (Nordstrom, Rexford, & Freedman, 2012)

In Serval, project investigators believe that the problem with the current networking architecture, which makes it hard to define more than one flow for a service and hard to recover a service instance failure, is not the IP addressing scheme. Instead they believe that the network stack has to be changed. Today all the identifiers in network, including the application and transport layers are IP bound meaning that they run by identifiers based on IP addresses and port numbers. By introducing SAL, which operates above an unmodified Network layer (based on IP), authors of Serval propose identifying services and flows based on their identifiers in SAL layer. As a result applications and processes can bind to servicelD's and flowID's using the notion of Active Sockets instead of binding to a five-tuple identifier of IP addresses and port numbers alongside protocols. A servicelD is unique and its is flexible in representing different granularities of service, i.e., it can correspond to a specific instance of a service or a group of processes and even a distributed system which provides the same service. This architecture enables late-binding as well as service level routing throughout the network, which in turn may enable load balancing between different instances of a service. It means that it is left to the underlying network stack to discover

services and to decide which instance of a service will respond to a request but not individual servers. This is mainly why this type of calling sockets is given the notion of active sockets because request packets trigger network wide events so that control applications can decide to respond based on request packets.

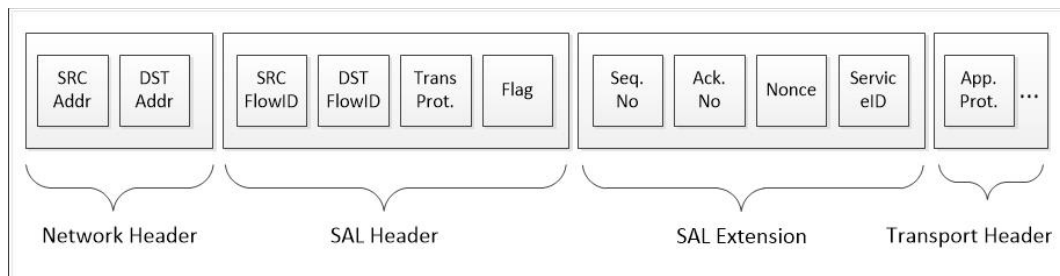


Figure 5: Serval packet headers. Image regenerated from source: Serval (Nordstrom, Rexford, & Freedman, 2012)

For instance when a process is sprung to bind to a service with the serviceID of “X” this will trigger the events that will register that service in the network stack, specifically in SAL. Subsequently this can trigger control applications, local or remote to the machine, to decide to perform load balancing or other actions. Thus with service layer enabled routers (service level routers in gateway routers or load balancers) the same network stack that runs on end hosts can run on routers to provide very large or wide area networks.

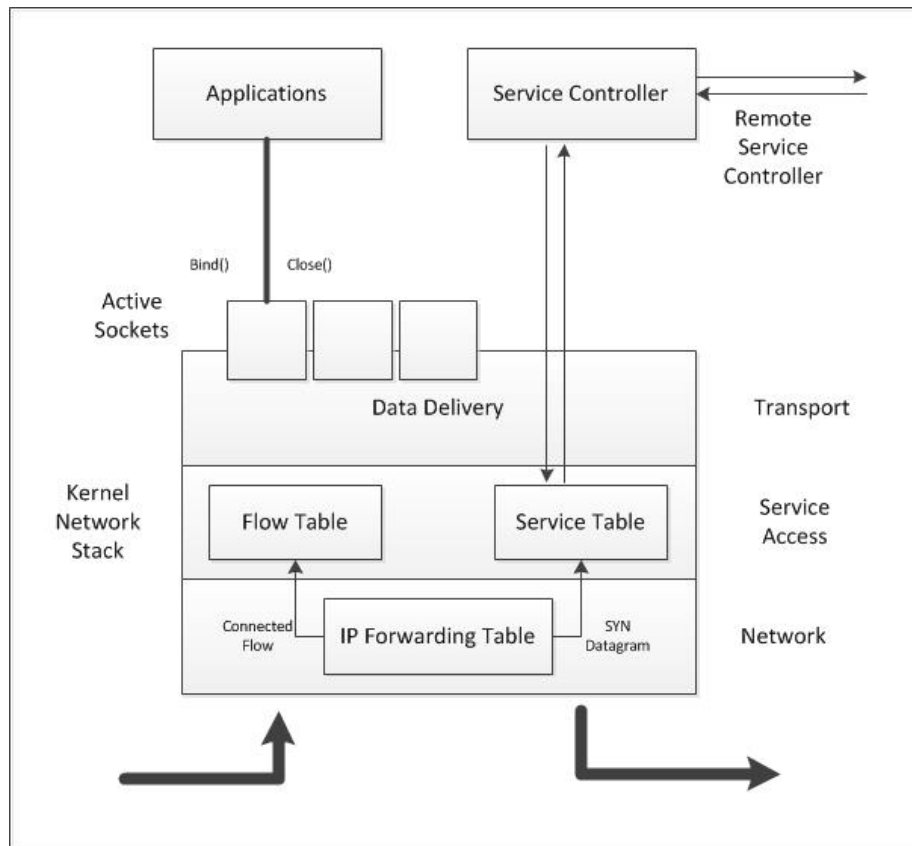


Figure 6: Detailed architecture of SAL. Image regenerated from source: Serval (Nordstrom, Rexford, & Freedman, 2012)

Using a controller API on an SDN based controller a variety of service discovery, failover and load balancing policies can be introduced to end hosts and middle-boxes. Thus the controller now can interact with not only end hosts running processes based on serviceIDs but also SDN enabled switches that perform service oriented forwarding in the network.

Some challenges that are being studied in Serval as an architecture based on SDN are joining the end-host and switch control functionalities, software defined service resolution and path selection, as well as general challenges such as communication security and policies to register serviceIDs and multiple dynamic service instance handling methods.

1.2 Purpose of the study

In Software Defined Networking the time it takes and the process necessary for a switch to obtain forwarding rules for new packet types is called “flow initiation overhead”. This overhead increases the time needed for the first packet of a flow to reach its destination.

This study enhances current solutions related to flow initiation in Software Defined Networking by proposing a hybrid algorithm, which uses currently available technology and methods to optimize the time needed for flow initiation.

As an innate consequence, a tradeoff in the form of extra traffic is introduced by the proposed algorithm. However, a thorough literature review suggests that Service Centric Networking bears fundamental solutions to minimize the risks of this tradeoff.

This study proposes the utilization of Service Centric methods and Serval project in particular to deal with the tradeoffs resulting from the proposed flow initiation algorithm.

1.3 Significance of the Study

Although the flow initiation overhead, as a scalability challenge, does not pose a threat in near future, thanks to high capacity of controllers to handle thousands of requests with low latency (Yeganeh, Tootoonchian, & Ganjali, 2013), it is worth mentioning that computer networks and internet grow continuously and new paradigms emerge that utilize the network in a more intensive manner. Considering high traffic networks with wide topologies (e.g. operators and datacenters), scalability of Software Defined Networking is introduced as one of the most important challenges of its architecture. Enhancing flow initiation time leverages scalability of Software Defined Networks while optimizing resource usage in SDNs.

In order to tackle bottleneck issues of SDN, which is common in centralized controller systems, a variety of solutions have been proposed (ONF O. , 2011). As a result of our literature review we have concluded that alternatively the Service Centric Networking mechanisms introduced in Serval Project can also resolve these and related issues.

Service Centric approaches have already been employed and tested for different services such as HTTP and FTP however the present study argues that implementation of controller service using SCN principles with Serval architecture is an alternative solution for handling multiple controllers in SDNs.

2 CHAPTER TWO

THEORY

2.1 Introduction

Among all the challenges there yet to be tackled, the present study takes SDN flow initiation challenge in hand and provides solutions to this problem. The author will conduct a series of implementations and tests to demonstrate how SCN resolves implementation obstacles and challenges for SDN and vice versa.

SCN needs an implementation platform in which a new addressing scheme can be defined and processed so the traffic can be forwarded based on serviceIDs as well as introducing new layers into the network stack. SDN is a promising architecture, which can house these types of innovations. Otherwise current technology only allows enhancements over the conventional addressing scheme.

On the other hand SDN has some innate challenges such as scalability and controller handling, and SCN is a very promising architecture to provide better scalability, load balancing and service discovery opportunities without the need for error prone third party patches to the server-client structure.

This co-existence and co-operation plays an important role in facilitating the solution for number of challenges for both sides as well as providing a platform on which many requirements of contemporary networking are met. In the literature review process of the present study, it became evident that a service centric and software defined networking platform will provide a lot of

fundamental solution opportunities for future networks such as cloud computing and the need for distributed and collaborative computing. Without an abstraction between service policy making and service forwarding functionalities it is hard to imagine fast innovations in new methods to provide technological requirements of contemporary computing needs. In turn, without a separation between data and control planes of switches, a radical change in network architecture to house new methods seems hard to maintain.

One of the most successful implementations of SDN is the OpenFlow standard protocol, which allows experimental studies to be tested and implemented on networks as well. An OpenFlow compliant switch or router still includes low level fast packet forwarding capabilities and tables locally, but high-level routing protocols are applied on the switch using a remote server on the network. Unlike earlier attempts to realize data and control plane separation, such as Ethane (Nick McKeown, 2007), Open flow does not require customization of hardware (switches that support Ethane protocol). Furthermore, earlier implementations such as RCP (Feamster, Balakrishnan, & Rexford, 2004) although made deployment easier, were limited to what hijacked protocols (BGP, RIP, etc) could support and could not have further innovation or introduction of new protocols, and FORCES (Yang & Anderson, 2004) required standardization, adoption and deployment of new hardware. OpenFlow uses a secure protocol to allow high level control functions to interact with switches via installing rules into tables in switches; these tables are named flow tables. When a switch receives a packet, it compares it with the available rules and applies the set of mandated actions accordingly (e.g. forwards the packet to a port, or drops it or delays it). In case there are no rules associated with the corresponding pattern, the switch queues the packet in its memory and asks the controller for a set of actions for the new packet. Controller, on the other hand, which is listening (as default on port 6633) receives the packet and de-multiplexes it to the upper stacks locally, where it is

received by the listening instance of a controller application, which is also referred to as Network Operating System.

There are quite a variety of network operating systems available in different programming languages such as the following:

- NOX: A C++/Python controller built and open sourced by Nicira Networks (Nicira).
- POX: A Python based controller application, which is mainly suggested for research purposes (Nicira).
- Beacon: A Java controller built by David Erickson at Stanford (Beacon).
- Maestro: A Java controller built by Zheng Cai at Rice university (Maestro).

Each controller application has its own development team, which provides similar features but have their own unique libraries too. Beacon controller developers claim that it is stable and has had no down-time since it has started to control a network of 100 virtual and 20 physical switches for months. It is cross-platform, open-source, fast and dynamic. Beacon is written and based on Java programming language (Beacon).

NOX is the original OpenFlow controller which is based on C++ and provides ease of development on Linux.

POX is NOX's younger sibling which is purely based on Python programming language and is suitable for research and fast deployment projects.

Maestro is funded by NSF and is being developed in Rice University.

Following is a benchmark of different OpenFlow controllers (network operating systems). Although this figure is only provided for historical purposes, it clearly demonstrates the number of flows per second handled by different controllers running on a number of CPU threads.

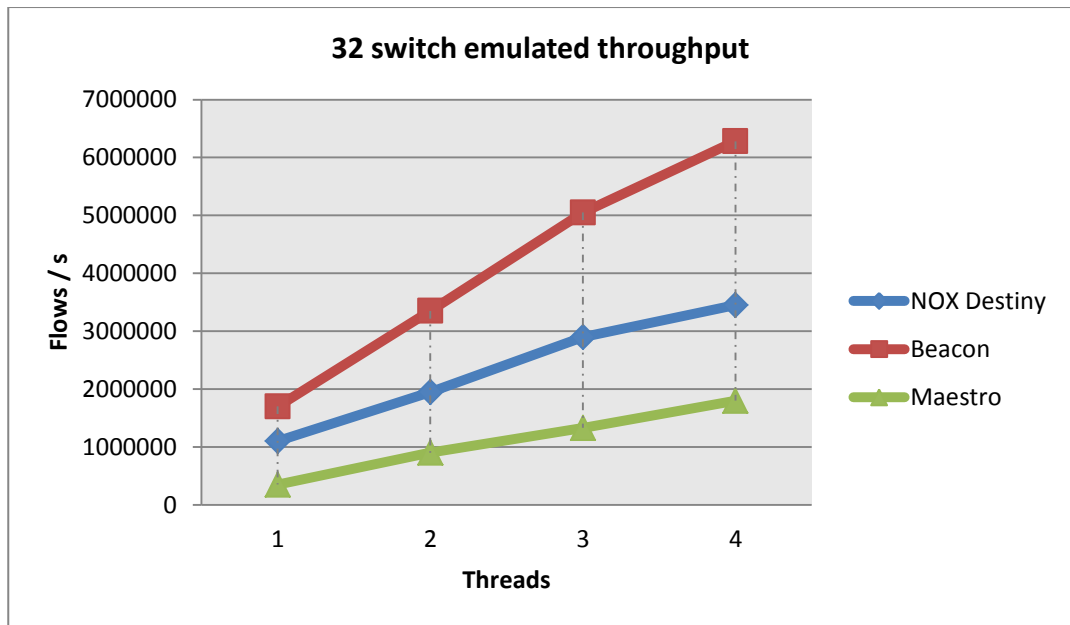


Figure 7: OpenFlow controller benchmarks. Image regenerated from source: NoxRepo (OpenFlow, 2013)

For this study, POX controller has been selected for the following reasons:

- POX is based on Python, which is a run-time programming language without the need for a compiler. This facilitates the process of development of ideas better and eases the path from design to implementation.
- POX unlike NOX is a multithread processor friendly controller. NOX only operates with one CPU.
- POX is actively being developed and its development mailing lists are more active.

2.2 Flow initiation in OpenFlow

OpenFlow as a control-switch communication protocol provides three types of messages transmitted between switches and the controller. The author will not discuss all message types here since this exceeds the boundaries of this research. A specific message however, namely “Packet_in”, will be discussed which is signaled when switch forwards a part or whole bits of a packet to controller for routing decisions to be made accordingly. Packet_in message is a type of asynchronous message. Asynchronous messages are sent by switches mainly to report a state, error or arrival of a new type of packet.

When a switch receives a packet, which does not have a rule or set of actions associated with it in its forwarding table, and the switch has enough buffer memory, Packet_in event contains only some fraction of the original packet header and a bufferID to be used by the controller when setting the forwarding rule for the corresponding new packet (ONF O. N., OpenFlow Switch Specification, Version 1.0 (Wire Protocol 0x04), 2011). Consequently when the controller decides what to apply on the newly arriving packets, using OpenFlow standard with TLS (Transport Layer Security) or TCP communication protocol, inserts a rule in the forwarding table of the corresponding switch. Afterwards switch acts on the buffered packet(s) based on this new rule.

In case a switch does not support packet buffering or has run out of buffer memory, it forwards the whole packet instead and will act based on the new rule once it is dictated by the controller. Meanwhile other packets that arrive in the same flow are either automatically dropped or are treated based on an existing forwarding until a new rule is provided or are forwarded as whole packets to the controller without buffering them. If buffering is employed as the default algorithm, this will pose the following risks and challenges:

- Initial flow of packets must wait in the buffer until:

1. Packet_in message containing part of the first packet's header is composed.
 2. The composed packet_in message reaches to the controller.
 3. Controller processes the message and decides on the forwarding rule(s).
 4. Forwarding rule(s) is/are dictated to the switch as a flow table row.
- In case the switch lacks a buffer or its buffer is full, all of the packets of the unknown flow will either be sent to the controller as a whole (not just the header of the first packet but all bits of all of packets) and usually are expired or dropped until the corresponding rule are dictated by the controller. In this case, there is a possibility of unnecessary bandwidth usage in terms switch buffer space as well as retransmissions.
 - Late Packet_in: There is a possibility that the controller message is delayed or dropped for intermediate switches on a path (from packet source to packet destination). As an instance, if next hop (switch) in the path is far from the controller compared to the initial switch, the following rare but possible scenario may occur:
 1. Initial switch receives the forwarding rule before the second hop (switch) in the path does.
 2. Initial switch forwards the packet to the second switch on the path.
 3. Second switch has not yet received the forwarding rule for the subject message, either because the controller chose a longer path for load balancing reasons, or the rule was delayed or dropped due to buffer overflow. Thus the second switch treats the new packet as it should and sends the packet_in request to the controller
 4. Controller recalculates the rules for the subject message while the switch is keeping it in its buffer.

- This iteration repeats itself whenever the next switch in the path is far from the controller compared to the switch sending the packet_in message.

The “Late Packet_in” case is depicted in Figure 8.

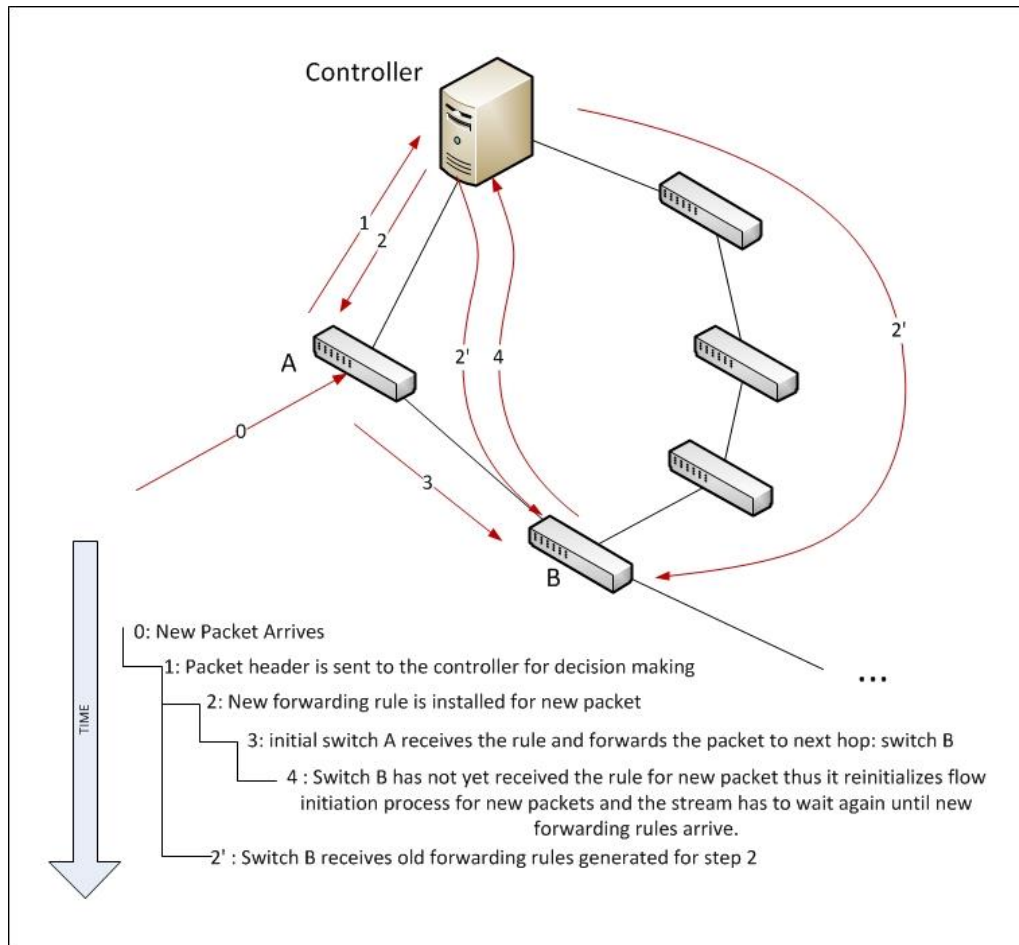


Figure 8: Late Packet_in : Flow initiation

When huge networks of operators and access networks are considered these risks grow proportionally. Thus it is regarded as a scalability challenge.

There have been a number of studies conducted to reduce or optimize flow initiation process. Tootoonchian et al. (Tootoonchian, Gorbunov, & Ganjali, 2012)

demonstrated that this challenge can be tackled by modifying NOX controller and introduced NOX-MT which focused on NOX controller performance and multithreading capabilities using known techniques such as I/O Batching, etc. Results of the mentioned study brought a magnitude of progress in controller performance. DevoFlow (Curtis, 2011) on the other hand has proposed to handle short-life flows by data-plane where only persistent flows are defined by controllers. This method, supported by ASICs, forwards fewer requests to controller alleviating flow initiation concerns. In 2010, a study on flow-based networking, namely DIFANE is introduced, which addressed the concern with centralized controller architectures. Yu proposed that by proactively installing all possible rules and data-paths, partitioning these rules among switches and then forwarding new packets to the switches containing related rules, will dramatically lessen the switch-controller requests.

As another solution, at first glance, simply eliminating the buffering step and sending whole new packets to the controller and forwarding those initial packets right from the controller point until the optimal path is installed on the source switch, might seem as an alternative solution (see Figure 11: Algorithm 2, case 1: optimal in section 3.2.2). Advantages of this method are:

- Reduction of switch buffer expenses.
- The possibility to program the controller to immediately forward initial packets it receives while flow initiation process takes place, thus eliminating the waste of time in flow initiation and reducing the time needed for first packets to arrive to the destination.
- Reduction of the risk of Packet_in Echo scenario by reducing the risk of buffer overflow or loss of initial packets.

The author will demonstrate that eliminating the buffering step from the default solution for flow initiation will not provide a better solution to the above

mentioned risks either. Details of cases and scenarios will be presented in section 3.2 where the default algorithm fails to address flow initiation challenges in either way: either buffering packets and sending packet header to the controller (which will be referred to as “buffer-flow solution” in this study) or sending whole packets to the controllers for decision making (which will be referred to as “forward-flow solution” in this study). Afterwards another approach as a fitter solution to the issue will be described which in essence is formed around installing apriori information regarding the network topology on switches to facilitate a more intelligent decision between a buffer-flow or forward-flow solution when an unfamiliar stream of packets arrive to a switch.

The theory provided in this study as a solution will in turn face a bottleneck issue at controller point. Although initial benchmarks of single OpenFlow controller has demonstrated that 30000 switch requests can be handled (Tavakkoli, 2009), replicating the controller instances eliminates this bottleneck. It is worth mentioning that as a result of replicating controller service instances, handling multiple controllers (service discovery, load balancing, failover, etc.) will sprung up as a new challenge.

In case controller service is considered no different than any other service type, SCNs or particularly Serval claim a fundamental progress in addressing the issues related to multiple and dynamic service instances such as service discovery, load balancing and failover scenarios. This is basically the reason why author has decided to study controller handling in SCN also.

2.3 Controller Handling

In OpenFlow switch specification document version 1.2 mechanisms to utilize multiple controllers were introduced. These mechanisms, which continued through the last version of OpenFlow switch specification document version

1.3.2, only support controller failover and load balancing (ONF O. , 2011) (ONF O. N., OpenFlow Switch Specification Version 1.3.2 (Wire Protocol 0x04), 2013). Based on the latest version of the above mentioned document, a switch may connect to several controllers. In cases of controller failure or overloading, switch connects to alternative controllers based on installed rules. The rules involving the multiple control handling are entirely orchestrated by controllers. Multiple controllers connected to a switch choose a role based on the policy made by controllers themselves. Controller roles are as follows:

- Equal: This is the default role of a controller when connected to a switch. Sending the OFPCR_ROLE_EQUAL request, the controller is given the “Equal” role and is equal to all other controllers in the same role and has full access and rights to the connected switch.
- Master: This role is similar to the “Equal” role, except that a switch can only have one “Master” role controller. When a controller claims this role by sending the OFPCR_ROLE_MASTER request message, the switch changes the role of all other Master controllers to “Slave” without informing them.
- Slave: in this role the controller has read-only access to the switch and will not be able to alter the state of the switch. The switch on the other hand does not send any asynchronous message to the controller in this role except the port status message.

A switch might have multiple Equal and Slave role controllers and at most only one Master controller.

For a switch to connect to the controller the following steps take place:

1. When the switch activates an interface or is turned on, it propagates a “link up” message.

2. Controller initiates the connection to the switch by sending and receiving hello packets and exchanging OpenFlow versions supported.
3. Switch informs the controller about its functions and status.
4. Connection establishes between controller and the switch for further OpenFlow protocol transmissions.

This method can alternatively be performed in the service layer instead. This not only creates a firm basis for further features of multiple controller handling such as virtualization and dynamically distributed and specialized controller service, but also provides a distributed service resolution mechanism that is controlled centrally in a controller server, which is similar to the mechanism that is currently used for out of service level routing and policy making methods.

3 CHAPTER THREE

THE PROPOSED TECHNIQUES

3.1 Introduction

Since OpenFlow is one of the most successful SDN implementations and undoubtedly the most famous platform to realize SDN architecture, the author will proceed to run simulations and implementations based on OpenFlow framework. “Mininet” network emulator, as one of the most frequently used emulators available, that supports OpenFlow controllers and switch instances, is initially tested in order to check its utility in simulating virtual networks on a single Linux based PC that can serve for the purposes of the present study.

Simulation on such a platform ensures the possibility of implementing the outcome of the study on physical/real machines since mininet uses real Linux kernels for hosts and real switch image: Open Virtual Switch Kernel (OVSK), for its switches, which is built into all new Linux kernels.

3.2 Flow initiation

As stated in section 2.2 of chapter 2, flow initiation causes a considerable delay in communication over OpenFlow based SDN model. To resolve this issue, the author suggests the following theory:

Proactive flow installation by controller based on a function, which decides if destinations of all possible paths are best accessed (less distant

and less delayed in packet transmission) by controller or the source of the flow. This study suggests a mechanism, which involves a switch, either local on controller machine or connected via dedicated and highly reliable and fast link and a mechanism that uses the available network map as a-priori knowledge in order to pre-configure switches.

In this context when destination switch is said to be “optimally accessible” by a node it means that the communication with the destination from that node in network takes less time. This criteria can be manipulated, however the concept is that if a node has the most desirable path to a switch when compared to a controller, the switch is optimally accessible by the node, and vice versa, if a controller has the most desirable path to a switch when compared to another node, the switch is optimally accessible by the controller.

3.2.1 Current flow initiation algorithm (Algorithm 1)

As default, OpenFlow switch description document suggests a Packet_in message that includes a part of the header of the new packet to be sent to the controller for decision making while packets of the new flow wait in switch buffer, until the new forwarding rule arrives from the controller. For purpose of convenience this algorithm will be referred to as “PIM”: Packet_In Method.

Case 1 (optimal): Desirable case for “packet_in transmission” method. In this case since the destination access is faster from the source switch, transmission of only the header of the packets is preferable, since packets waiting in buffer will arrive to the destination faster and unnecessary traffic is not created from controller to the destination switch.

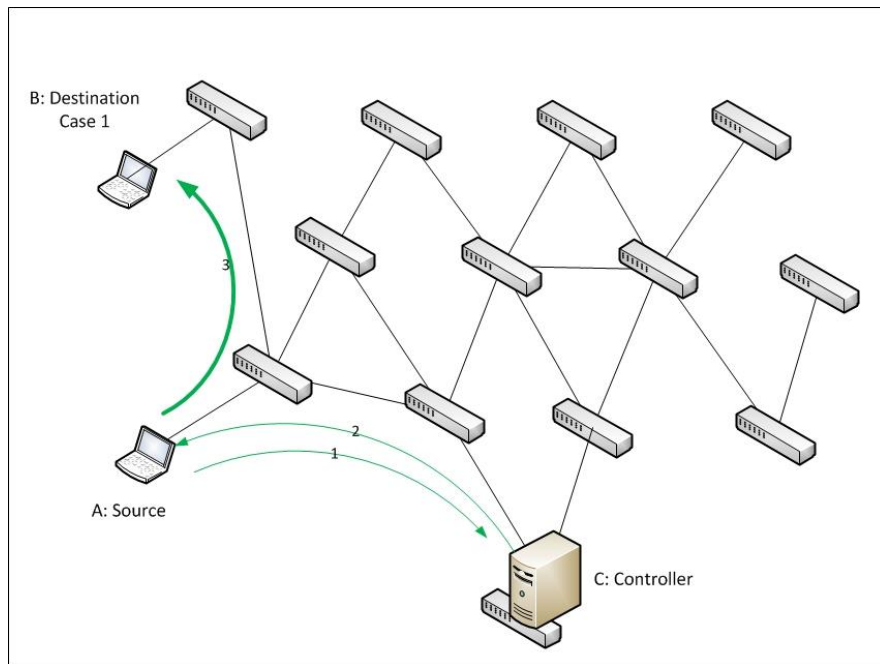


Figure 9: Algorithm 1, Case 1: Optimal

Case 2 (non-optimal): Destination switch is accessible by the controller in less time.

In this case since the destination is more easily accessible by the controller, forwarding the whole packets instead of only the header is more desired. Buffered packets will eventually have to follow a path that is easily accessible by the controller, thus if the controller receives the whole packets it may forward them from the controller point and may save the time it takes for the initial switch to forward buffered packets only after receiving the forwarding rules. Sending only the header will delay the arrival of packets to the destination.

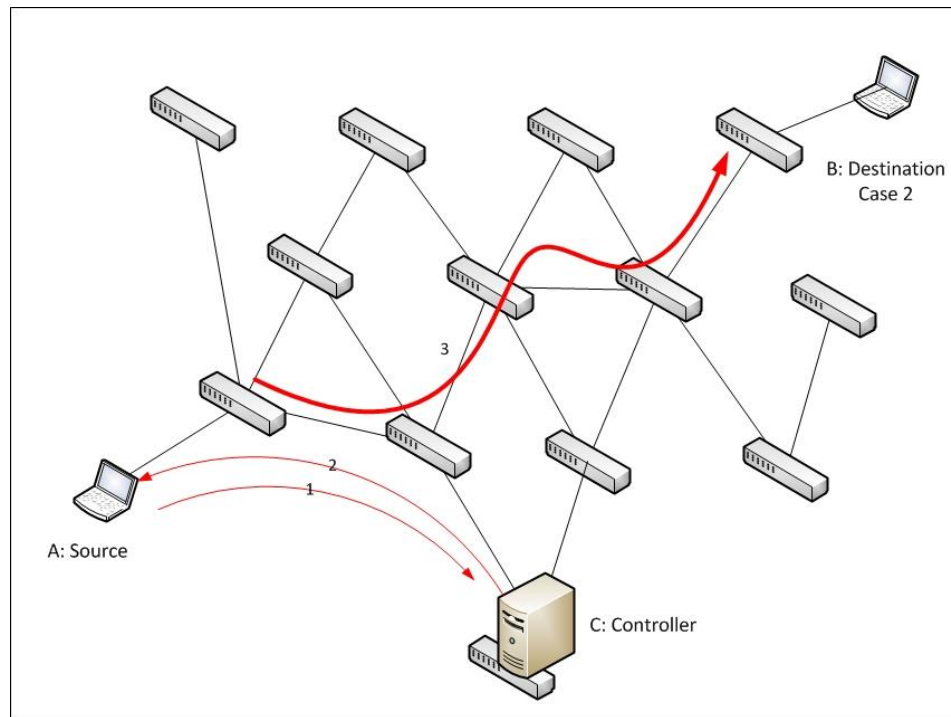


Figure 10: Algorithm 1, case 2 : non-optimal

3.2.2 Sending whole packet (Algorithm 2)

An OpenFlow switch sends the whole packet to the controller for decision making only if its buffer is missing or it is full or it is configured to do so. If this method is not bound to the above mentioned limitations, whole packets can be sent to the controller regardless of the buffer status. Upon receiving a new packet from a switch, the controller not only installs new forwarding rule on switches on the path but also forwards the packets it received during the flow initiation process. For purpose of convenience, this algorithm can be referred to as “OFM” standing for “original flow method”, in which packets are not buffered, instead are sent to the controller.

Case 1 (optimal): Destination switch is accessible by the controller in less time.

In this case since the destination is more easily accessible by the controller, forwarding the whole packets instead of only the header is optimal. Since buffered packets will eventually follow a path that is easily accessible by the controller, if the controller could have received the whole packet it could forward them from controller point and save the time it takes for the source switch to forward the buffered packets (after receiving forwarding rules).

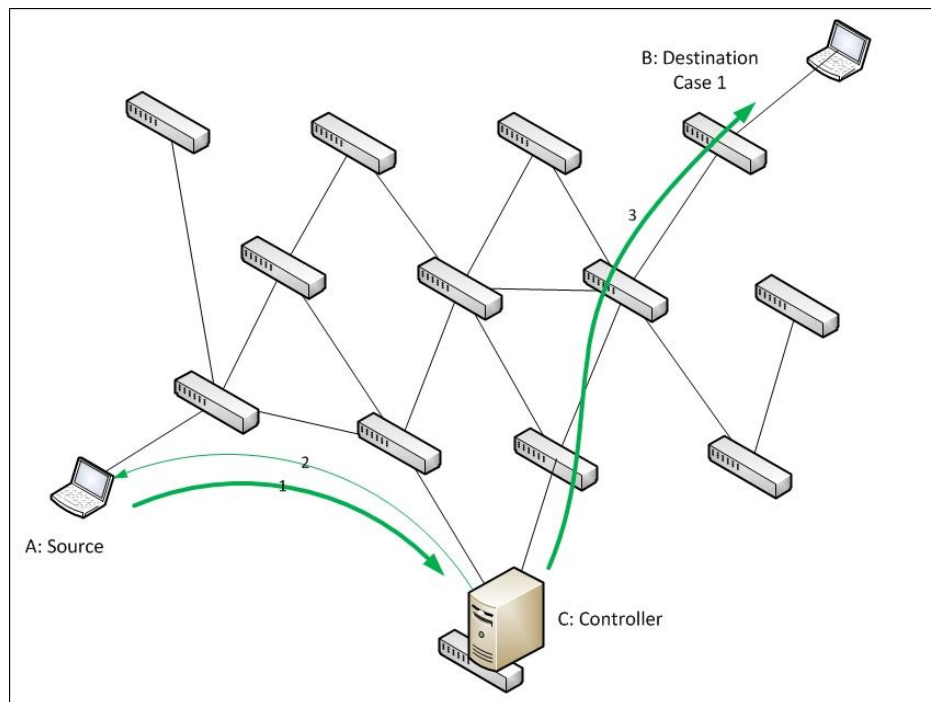


Figure 11: Algorithm 2, case 1: optimal

Case 2 (non-optimal): Destination switch is accessible by the source of the flow in less time.

In this case sending the whole packet is not desired, since the source switch has a better condition for forwarding initial packets to destination and the path from controller to destination is less optimized. Besides sending the header is faster and consumes less bandwidth.

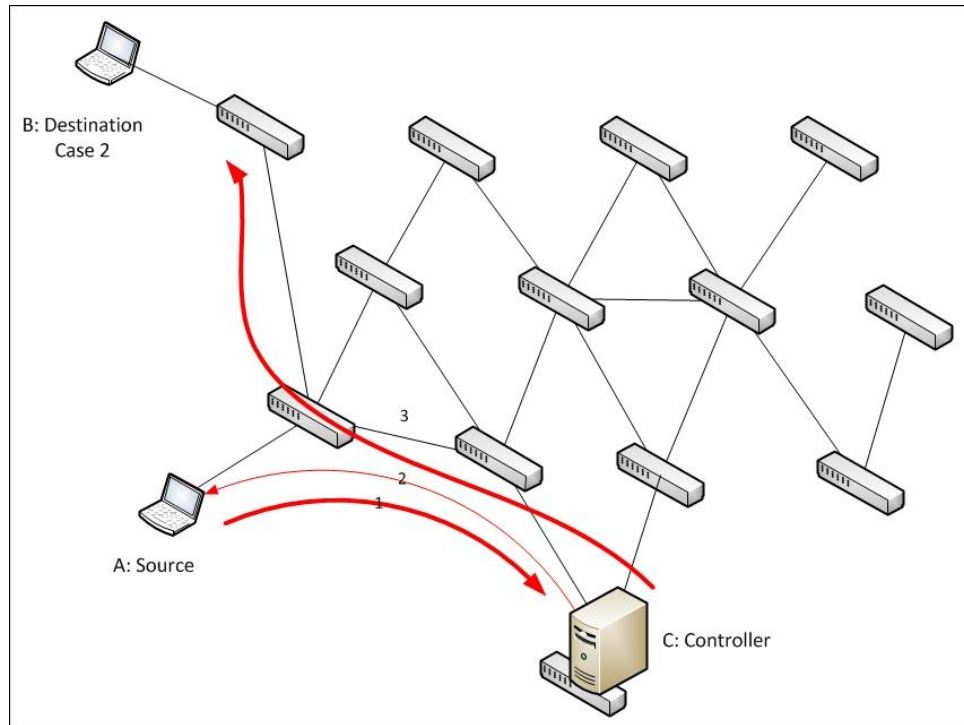


Figure 12: Algorithm 2, case 2: non-optimal

3.2.3 Hybrid Algorithm (Algorithm 3):

Referred to as “HYB” method for convenience, this method utilizes the cases where previous algorithms were advantageous. As seen in previous sub-sections, both approaches have advantages and disadvantages in certain cases. However if switches could have an information, which is based on the topology, they can be dictated when to use each flow initiation method. This study contributes by suggesting that using the network map composed by statistics acquired from switches in an SDN, controllers can install rules to determine whether a switch should utilize PIM method (buffer the original packets) or OFM method (do not buffer packets) when new flows arrive towards specific destinations. This operation can be performed when controller is sprung up as follows:

1. Controller puts a table together composed of all possible subnet routes for all the switches (based on their location in network).

2. Controller decides which destinations are optimally accessible by the controller from all sources.
3. Controller installs a rule on switches dictating whole package dissemination (Algorithm 2) in the above mentioned cases.
4. The rest of the routes are regarded by default as optimal cases and are ordered to apply Algorithm 1.
5. These initiation rules are placed on the bottom of the flow table to allow new rules and regulations to be placed on the top in future, preventing their execution once new policies take effect upon actual packet arrivals.

Case 1 (optimal): Destination switch is optimally accessible to the controller.

Case 2 (optimal): Destination switch is optimally accessible to the source of the flow.

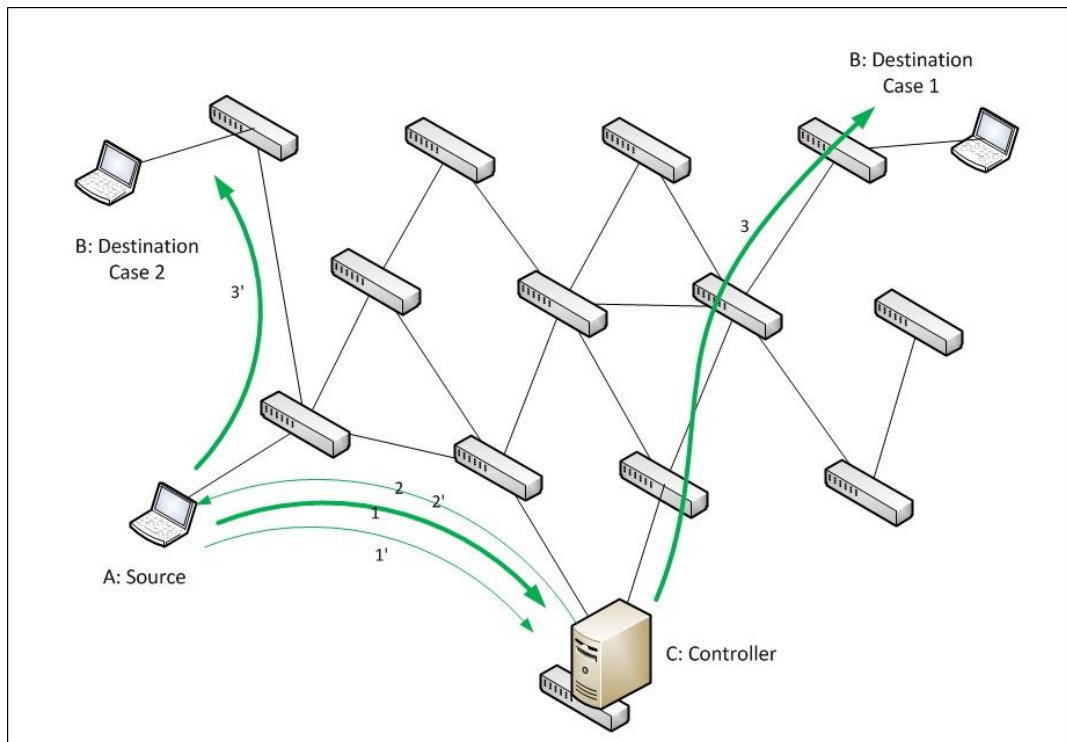


Figure 13: Hybrid Algorithm 3 (the main contribution) Both cases : optimal

In this algorithm regardless of the possible cases, since the best of Algorithm 1 and 2 are chosen intelligently, all cases are optimized.

This hybrid algorithm, which is suggested in the present study, is testable using mathematical models. However as a result of accepting the whole packets in some cases and taking on the role of forwarding initial packets yields a forwarding role and traffic on the controller. To resolve these issues this study suggests that high speed packet switching functionality to be integrated on the controller machines locally. The resulting platform will act analogous to brain in living organisms, which not only perform decision making but also play role in neural pulse transmission in living neural systems. As for extra traffic burden on controller machine, this study has also conducted a literature survey to find best practices in service handling challenges. This is basically the reason why “Multiple Controller Handling” is being addressed by the author.

To test the above mentioned, simulation in a high-traffic large network will demonstrate enhancement in flow initiation time compared to Algorithm 1 and Algorithm 2.

3.2.4 Multiple Controller Handling

Since OpenFlow and any other SDN implementation for that matter implies control functionality to be dictated by a controller to the switch fabric, it is safe to assume control traffic as a type of service. It is necessary to keep in mind that in order for switches and controllers to communicate on service level, both need to have an understanding of service centric addressing scheme, namely serviceID's and FlowID's as well as the network stack which processes packets containing the above mentioned encapsulations.

Considering controller traffic as a type of service will allow inter-controller load balancing and failover recovery mechanisms to be implemented inherently more robust and secure.

The present study will not analyze the implications of implementing serval architecture on current OpenFlow based POX controllers and effects of various failover scenarios since the scope of the work in hand does not include how service centric perspective introduces a redemption from techniques that are being used for load balancing and recovery operations. This solution for bottlenecks in controller point is solely suggested by the author based on information derived through the literature review conducted for the main purpose of the study. As future work however this suggestion may be applied to demonstrate an automated and fundamentally robust process in which switches query control planes for packet forwarding instructions. The author does not expect a better performance in terms of controller discovery time or rate; rather expect to end up with similar results with an IP based topology on a service centric approach. The contribution here is to demonstrate that service centric approach is implementable and feasible and is a fundamental solution to the challenge.

For this method the author argues that controller handling is feasibly implementable by the serval network stack on both controller and switches. Controller will run POX as its network operating system and will communicate with the switch based on serviceIDs and FlowIDs instead of IP, port and protocol tuples.

In controller service discovery, switch receives a packet, which has no corresponding entry to match in its flow table, encapsulates it with a service level header and forwards it to either a service level broadcast address or its known controller instance. Then the controller receives the enquiry and decides to de-

multiplex it or forward it to another controller machine based on its service policies. Afterwards the control traffic is established accordingly.

In case of a controller failover or overload scenario, service level policies will handle the incidence in a much similar manner when any other service type fails or needs load balancing automatically.

Both cases above shall demonstrate Serval's ability to handle incidents of initial discovery and failover mechanisms of SDN based networks.

In Serval project, the authors demonstrate that service centric network and Serval architecture function adequately and smoothly on a number of protocols by implementing a prototype containing almost 28000 lines of code. This prototype has demonstrated that applications like Firefox, TFTP, Iperf, Mongoose, Apache bench, etc. are easily portable to service level operation only by changing few lines of codes. In these prototype tests, authors have concluded with similar results as conventional methods in protocols such as HTTP, FTP, etc. as expected (Nordstrom, Rexford, & Freedman, 2012).

Controller service which is transmitted over OpenFlow protocol is essentially no different than HTTP or any other protocol for that matter. Since controller service is being introduced recently and applications using OpenFlow protocols are numbered, it is easier to apply a service centric approach to available applications and new features to be introduced to SDN architecture.

This will also pave the path for all other network traffics to be able to migrate to service centric architecture since switches understand SCN addressing and network stack schemes.

4 CHAPTER FOUR

SIMULATION BASED ASSESSMENT OF PROPOSED TECHNIQUES

4.1 Algorithm expression

For any arbitrary topology, the Hybrid Algorithm will find the best method of flow initiation regardless of the location of the controller, source and destination hosts. This hybrid algorithm, being intuitively evident, can also be explained as follows:

As discussed in section 3.2 we can conclude that the time required for initial packets of new and unknown flows to reach their destination in Algorithm 1 Case 1 and Algorithm 2 Case 1 are smaller than Case 2 respectively.

For convenience the following reference table is constructed:

Table 2: Scenario specific flow initiation time reference

Scenario	Time needed for initial packets of unknown flows to reach destination.
Algorithm 1 Case 1	σ
Algorithm 1 Case 2	τ
Algorithm 2 Case 1	σ'
Algorithm 2 Case 2	τ'

If the following assumption is made for both algorithms:

In a single topology:

If the probability of Case 1 incident equals p , then the probability of Case 2 incidents are equal to $(1 - p)$ in each algorithm.

Then we can conclude that the expected values of initial packet latency (average time needed for initial packets to arrive destination) during flow initiation for all three algorithms are as following:

$$E_t\{Algorithm1\} = p(\sigma) + (1 - p)(\tau)$$

$$E_t\{Algorithm2\} = p(\sigma') + (1 - p)(\tau')$$

$$E_t\{Algorithm3\} = p(\sigma) + (1 - p)(\sigma')$$

Thus we can conclude that:

Since $p(\sigma') < (1 - p)(\tau)$ and at the same time $p(\sigma) < (1 - p)(\tau')$

Then:

$$E_t\{Algorithm3\} \leq E_t\{Algorithm1\}$$

$$E_t\{Algorithm3\} \leq E_t\{Algorithm2\}$$

The present study also provides simulation results for all the above mentioned cases and concludes that Hybrid algorithm provides enhancements over both Algorithms 1 and 2.

Literature survey also supports the suggested method to resolve controller congestion issue by resorting to multiple controllers and handling them by service centric architecture and mechanisms.

4.2 Simulation

In order to simulate OpenFlow and SDN concepts there are in total three simulators available, namely EstiNet, MiniNet and NS3. Before reviewing each simulator it is important to stress the basic and fundamental necessity of the present study in order to demonstrate merits of HYB method. First and foremost, the controller in the setup of the network for this study will need to operate in an “in-band” mode. In-band control in this context means that the controller will use the same medium-channel for control traffic and data traffic. (data and control traffic are transmitted on the same network.)

4.2.1 *EstiNet*

EstiNet is a simulator/emulator which allows its users to use both of its capabilities. However, it is a proprietary and it is indeed an expensive simulator/emulator for the purposes of the present study, and hence is not used here. In addition, Esti-Net is not set up to utilize in-band controller mechanisms out of the box and modifications in source code are necessary (information based on the email reply from the developer team of EstiNet).

4.2.2 *Mininet*

Mininet is a considerably fast to deploy emulator and it is easy to test openflow setups in mininet. The author has started the present study utilizing mininet for experimental purposes. However, since its documentation in general and its functionality assessment in particular are very limited, it was not obvious in the short term that mininet will not serve for the purpose of the present study. The reasons why we did not use mininet in the present study are as follows:

- Mininet has few components to support in-band controllers, which is necessary for this study. There is no method to define and use a controller, which is also used for data transmission. Provided controller

classes and switches all utilize out-band control mechanisms, which means all switches and controllers are connected to each other on a network separate from the actual data network.

- We changed the component codes in mininet so that it will provide in-band control mechanisms, however since mininet controller and switches are not created for hybrid-networks (networks which control and data signals are on the same sets of connections and network), mininet emulator demonstrated unexpected results and performance. Technically speaking, the code for mininet generated unnecessary recursive outputs. The controller, as a result of being not programmed to handle in-band controlling mechanisms repeatedly logged following messages:

```
o |99097|poll_loop|DBG|[POLLIN] on fd 7:
o |99098|poll_loop|DBG|[POLLIN] on fd 8:
o |99106|vconn|DBG|Dropped 9272 messages in last 1
  seconds due to excessive rate
```

It indicated great amount of packet loss due to the recursion taking place in the controller. In short the fact that the controller and switches in mininet are not optimized for in-band traffic created this excessive traffic.

- In mininet all switches and controllers are in the same namespace sharing same processes as the host computer. Only user space switches are compatible with separate namespace capability which cannot be used for remotely controlled in-band controllers.

4.2.3 NS3

NS3 provides modules for OpenFlow and SDN networks, however thanks to its comprehensive and solid documentation, in process of testing, it became quickly evident that NS3 does not support in-band controlling mechanisms for switches and remote controllers (ns3). Each switch in NS3 has its own class of controller, which is connected via a loopback interface on the same switch, therefore remote connection and link failure scenarios cannot be implemented.

Initially it seems as the best solution to modify codes of switches and controllers in NS3 to accommodate the purposes of the present study, however due to the complex nature of written codes for switches and controllers in NS3 it is necessary to have adequate knowledge on all aspects and classes in components of NS3 to change a behavior in a module. Since most of the capabilities of modules in NS3 are not necessary for this study and are out of the scope of the present work, this solution was discarded. However it is also indicated in the development documentation that remote controllers can be an option for future development projects and are welcomed by the developer team of NS3.

4.2.4 Simulation Tools

Since available simulation/emulation tools could not be used for the purpose of this study, the authors have developed a new simulator, which would serve for the purpose of the present work.

In order to provide compatibility and ease of porting to NS3, initially C++ was chosen as the language of programming. A program consisting of over 2900 lines of C++ code is written to simulate a network with SDN capabilities. However since the garbage collection is not handled automatically in C++, especially when raw pointers are used, the program demonstrated unexpected crashes and memory leaks during the experiments.

In order to demonstrate effects of the hybrid flow initiation mechanism, the authors re-wrote the whole simulator program from scratch in Python language, which provides automatic and efficient garbage collection mechanisms and has a less steep curve of programming and exception handling processes. This removes the risk of constant crashes during experiments and provides adequate performance metrics to test different scenarios.

The Python code for this simulation consisting of over 1500 lines of code using Python 2.7 codes is used to carry out experiments to evaluate our proposal in this study.

As a platform on which the code will run, authors have chosen GNU/Linux Debian on a dual-core 2.6 Gigahertz CPU computer which uses 4 Gigabytes of RAM. Linux distribution is selected since it provides full utilization of multi-threading and concurrency and is easier to setup compared to UNIX and UNIX based operating systems.

In Figure 14 the preliminary class diagram for the simulator indicates that the simulator is designed only to serve for the purposes of this study, however other types of uses can be derived based on its capabilities.

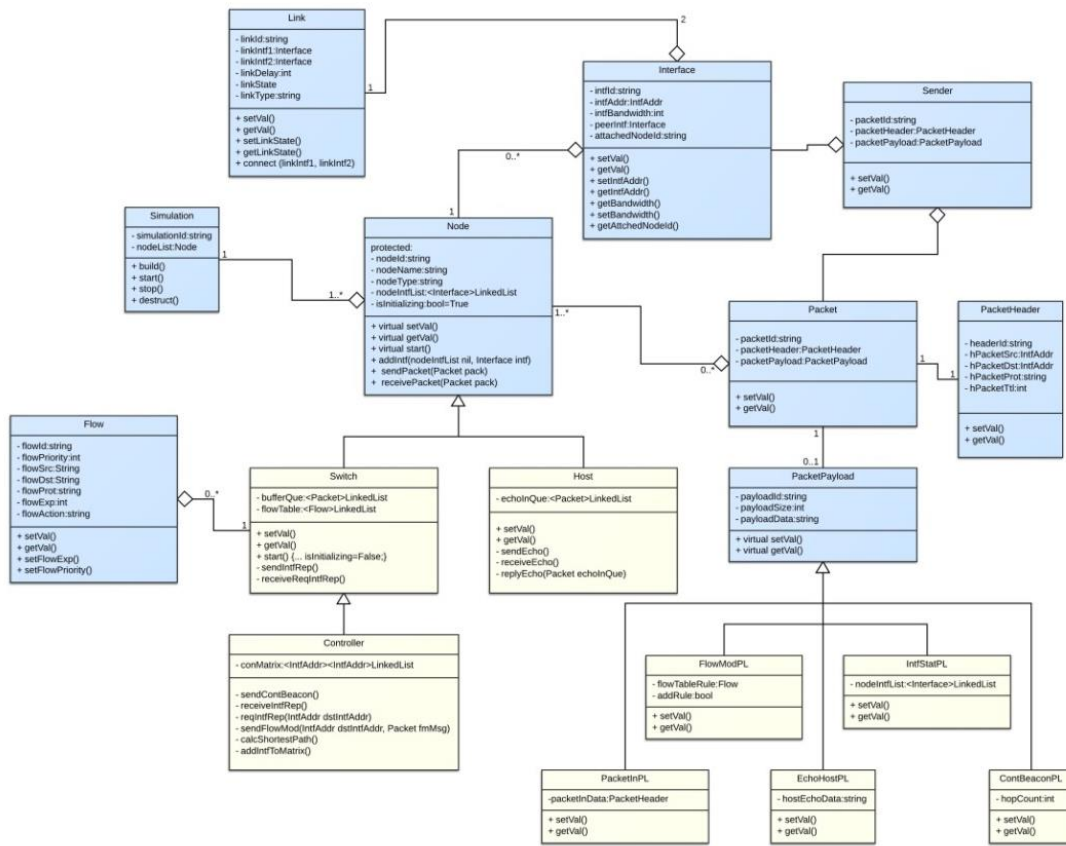


Figure 14: Simulator Class Diagram

Simulation experiments aim to demonstrate following points:

Using suggested hybrid mechanism in the present study for flow initiation,

- Reduces the number of packets buffered in switches for flow initiation purpose,
- Reduces the number of switches that buffer initial packets for flow initiation,
- Reduces the average time for initial packets of unknown flows to reach their destination.

During simulation following mechanisms are used:

- Overall architecture: Authors have put effort to model the characteristics and features of the simulator as close to real networks as it is useful for the purposes of the present study. Overall architecture of the simulator is as follows:
 - Node Types:
 - Hosts: nodes with one interface (NIC), one forwarding table (network route to and from the default gateway), sending and receiving echo applications and replying to ingress echo messages.
 - Switches: nodes with multiple interfaces, multiple flow tables, echo sending/receiving applications and controller communication applications.
 - Controllers: nodes that are inherently capable of switching, plus routing, flow modification, receiving interface statistics from switches, applications for sending and receiving echo messages and communicating on control features with switches.
 - Interfaces: each node on network can install one or more network interface card in order to connect to network Links. Each interface has bandwidth parameter that can be set individually.
 - Interface Address: each interface can have two types of address:
 - Hardware address: can be assumed and be utilized as MAC address.
 - Software address: can be assumed and be utilized as IP address, IPv4, IPv6 or any arbitrary address type.
 - Network Links: each network link, similar to network cable, connects two Network Interface Cards to each other and has a random and configurable link delay capability.

- Packets: consist of:
 - Packet Header: contains customizable header space to indicate packet sender/receiver MAC and IP addresses, protocol type, etc.
 - Packet Payload: for different types of packet headers different types of payloads can be assigned. The type of payload in a packet is determined by the protocol property of the header of packet. Using packet header protocol type, receiving party can demultiplex and read packet contents (payload)
- Simulator: creates topologies, starts/stops the simulation and determines the time of simulation.
- Applications: each host, controller or switch have different applications for reading and/or sending different types of packets.
- Flow Tables: Each switch has one or more flow tables which store rules as tuples on which the forwarding mechanism is based on. Each flow table has list of Flows (rules).
- Interface Statistics Packet: sent by each switch to the controller (described below), contains the list of interfaces present on a node and all of their properties such as the bandwidth and the peered interface on the other end of the link.
- Controller Discovery Mechanism: Currently OpenFlow switches broadcast “connection-up” messages indicating their states as “Up” and wait until a controller receives, responds and binds with them (ONF O. N., OpenFlow Switch Specification Version 1.3.2 (Wire Protocol 0x04), 2013). This handshake, while being quite useful when the controller is present in the network, can generate unnecessary broadcast flood inside network and on the other hand the controller will need to discover shortest path and

statistics to each switch separately. Since the suggested flow initiation mechanism in the present study is agnostic to the underlying topology and controller discovery mechanisms, authors are suggesting a different controller mechanism in order to create an autonomous controller discovery method, authors have implemented following algorithm:

- Upon initialization, switches stay in listening mode.
- Upon initialization, controller broadcasts a packet containing the address of the controller and hops (intermediary nodes) to reach the controller (initiated by the controller as being zero). For convenience this packet is called the “controller beacon” in the present study.
- Each switch, upon receiving the controller beacon checks to see if it has already received a controller beacon from another source.
- If the switch has already received a beacon, checks if its “hops_to_controller” parameter is less than the newly received beacon’s “hops_to_controller” parameter.
 - If newly received beacon is from a closer source to the controller, the switch re-sets its controller access address and “hops_to_controller” parameters based on the new beacon, creates a new beacon with augmented “hops_to_controller” property and broadcasts the beacon packet from all of its interfaces except the ingress port.
 - Otherwise, the switch discards the new beacon packet.
- Network Discovery: Each switch, upon setting up its controller access parameters based on received beacons, sends an “interface_statistics” message out of its controller access interface (which was set as the ingress interface of the beacon packet). Since the other switch sitting on the other end of the line also knows which interface finally leads to the

controller, the “interface_statistics” packet finds its way to the controller. This way the controller also acquires knowledge of the whole network without the need for all switches to broadcast their status. Since all control access interfaces on all switches are best interface to access controller (determined by the controller discovery method described above), “interface_statistics” packets are directed to the controller via the shortest path without the need for any calculation.

With the above features, authors have aimed to provide a solid and minimal way for the simulator to provide an experiment environment for purposes of the present study.

4.2.5 Experiments

The present part of our study aims to demonstrate the differences in three algorithms analyzed in the previous sections. In each experiment, the numbers provided are average of three iterations of execution.

Experiment 1: Linear topology with 2 switches

To begin with, a topology consisting of 2 switches and 2 hosts is considered as depicted in Figure 15. In experiments 1, two hosts in this topology send echo packets to one another. In each experiment, h_1 attempts to send an echo packet. After the corresponding flow initiation mechanism takes place, the actual transmission begins. When h_2 receives the echo packet, it immediately composes an echo reply packet and attempts transmitting it to the IP address, which sent the original echo packet. This transmission of echo reply packet will in turn be preceded with a flow initiation process for its own flow type, source and destination co-ordinates. Latency, which is the time difference between the transmission of echo packet and the reception of the echo reply packet by h_1 , is

taken as the primary parameter to be considered for our experimental evaluation. Only 100 Mbps connections are used in this experiment

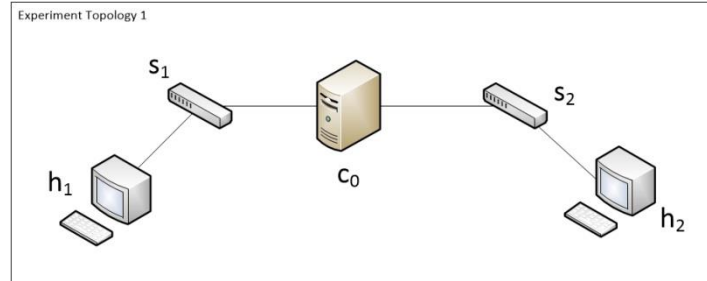
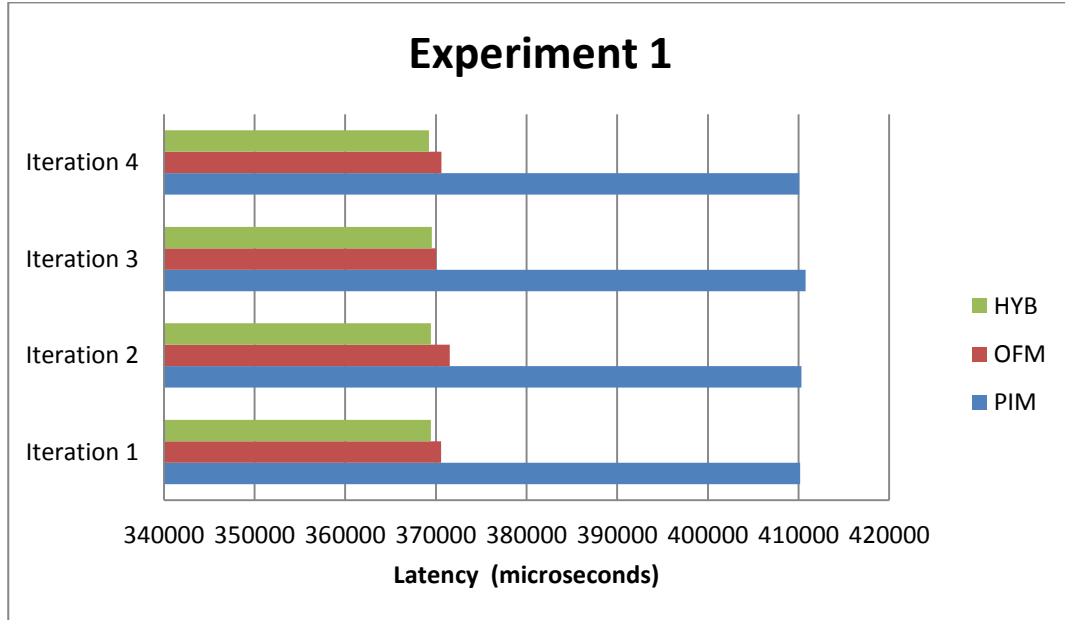


Figure 15: Experiment 1



The purpose of this experiment is to demonstrate that HYB and OFM are approximately equal in terms of latency in this topology. However, the PIM method (buffering initial packets in source switch) performs poorly when compared to other two methods of flow initiation.

The clear reason for this result to appear is that the destination is more quickly accessed by the controller, thus sending the Original Flow to the controller eliminates the time needed for waiting for flow initiation and retransmitting the echo packet once rules are installed by the controller.

Experiment 2: Linear topology with 4 switches

The purpose of this experiment is to demonstrate that by growing the network in size for linear topologies, the effect of HYB method magnifies and still the difference between the evaluation result for OFM and HYB methods stays close with a clear advantage on HYB method. The reason for this advantage will be discussed in section 14.2.6. Only 100 Mbps connections are used in this experiment.

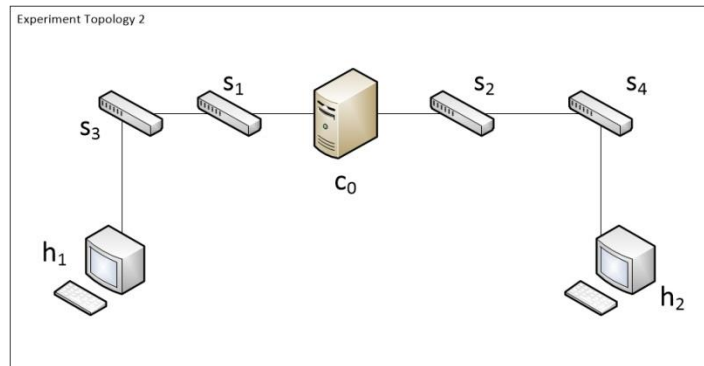
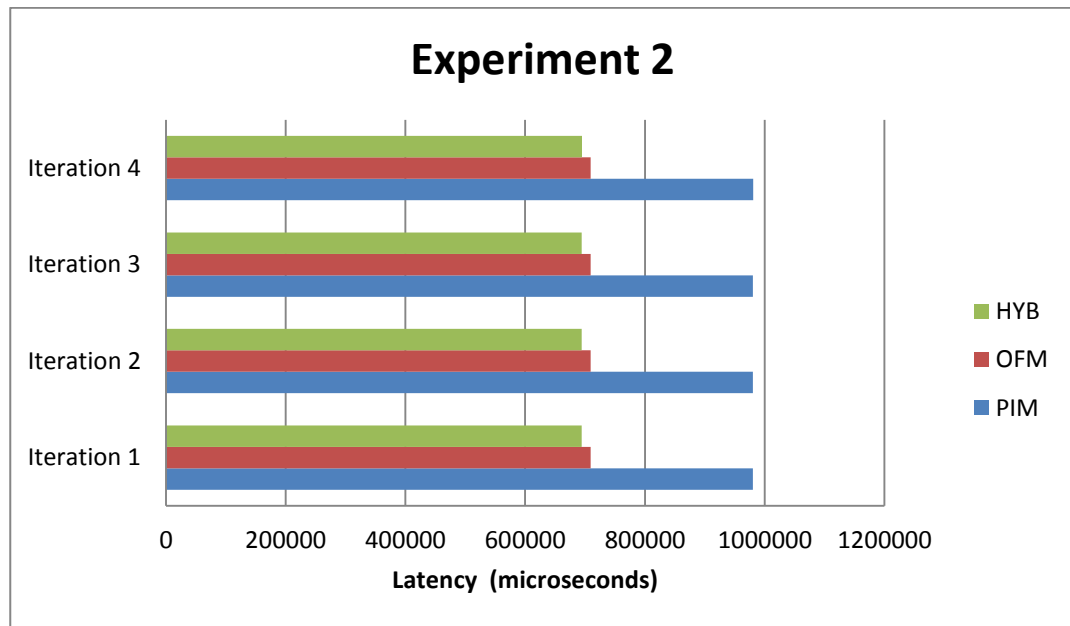


Figure 16: Experiment 2



As seen above while HYB and OFM methods outperform the PIM method, the difference between their performances has grown, which is expectable due to more distant sender and receivers of echo packet.

Experiment 3: Linear topology with 8 switches

The purpose of this experiment is to demonstrate the continuity in the advantage of utilizing OFM and HYB methods and to demonstrate the effect of growth in network size on this advantage. Only 100 Mbps connections are used in this experiment.

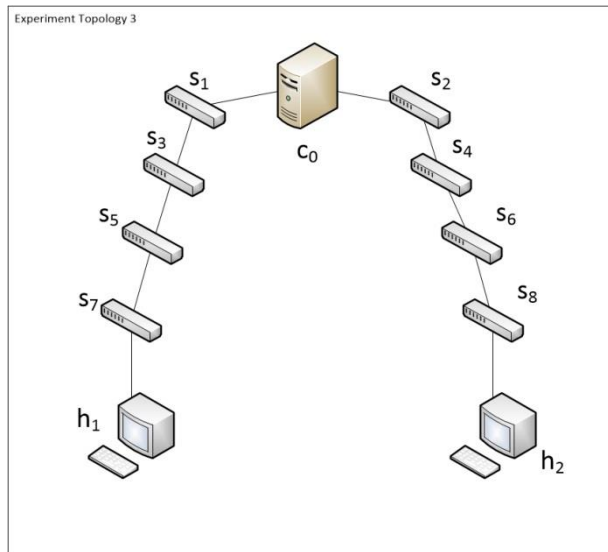
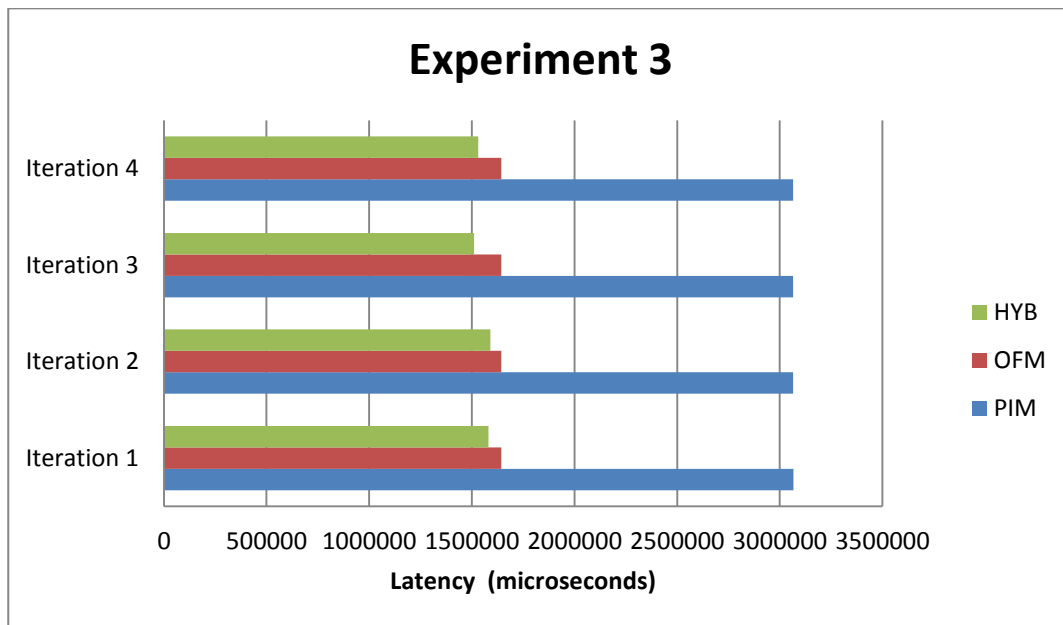


Figure 17: Experiment 3



This experiment will also act as a base for further experiments where PIM presents more advantageous results when compared to OFM but still falls short when compared to HYB method.

As clearly seen above, the time difference between sending echo and receiving echo packets using HYB and OFM is almost half the value for PIM method. This growth expressively indicates that with growing number of nodes in a linear topology with a controller in middle, HYB and OFM methods yield a considerable gain with regards to the time needed for initial packets of unknown flows to reach their destinations.

Experiment 4: Non-linear topology with multiple loops

When single or multiple loops are introduced in the network, the effect of HYB method becomes bolder as it outperforms both OFM and PIM.

Experiment Topology 4

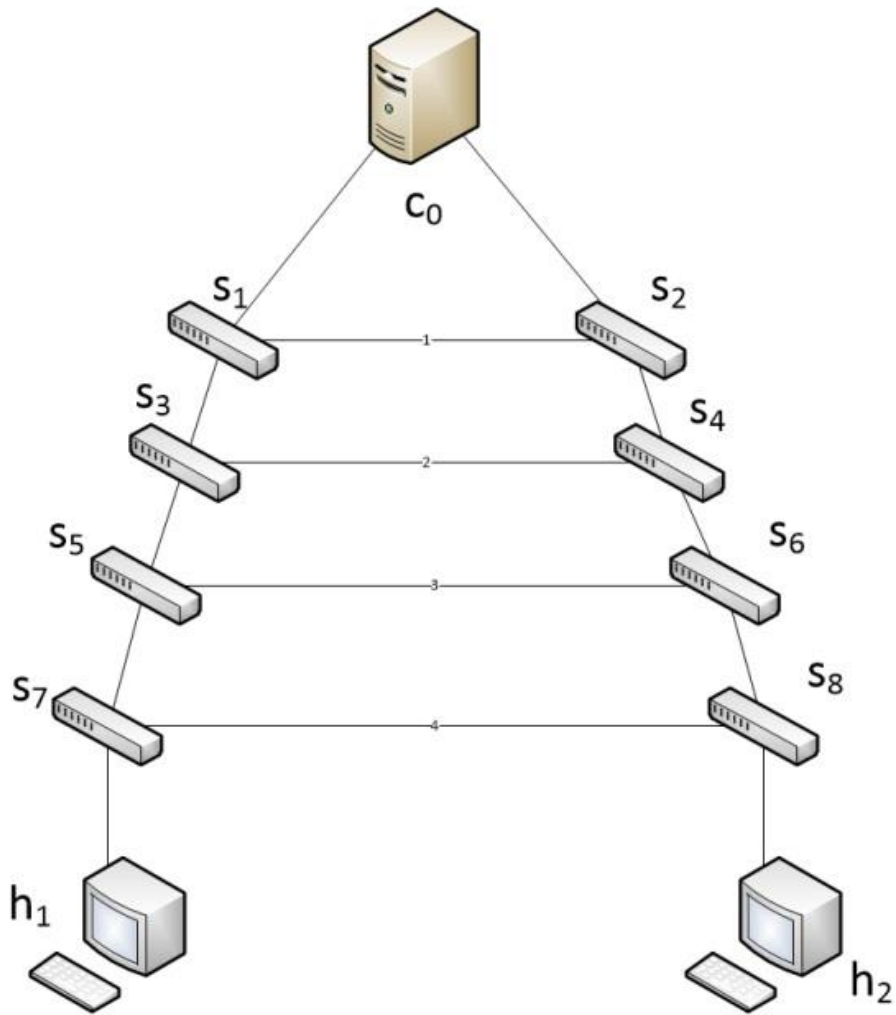
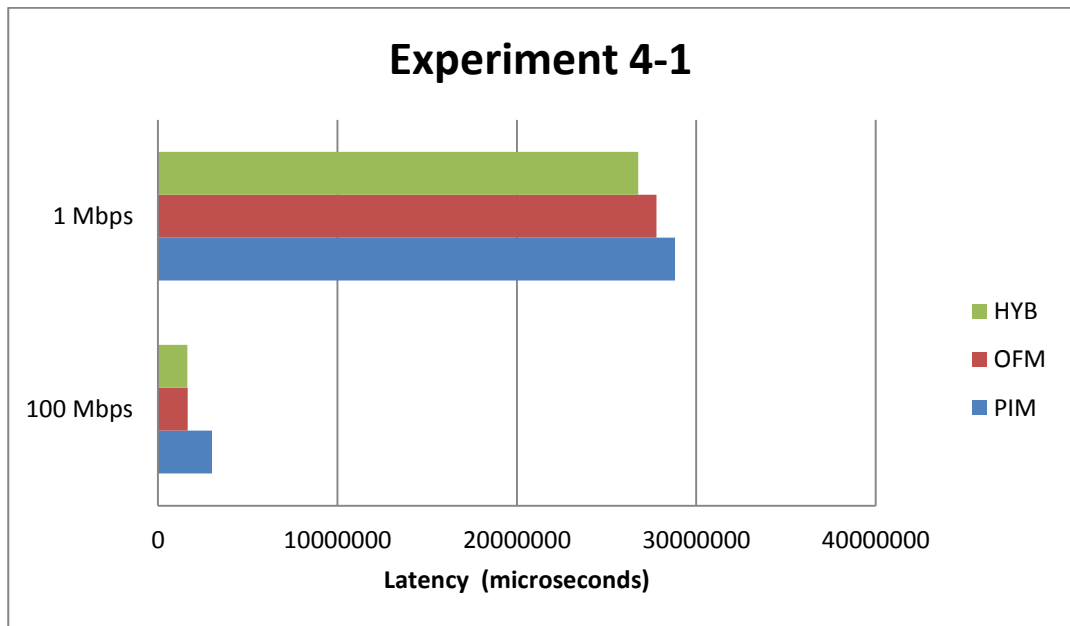


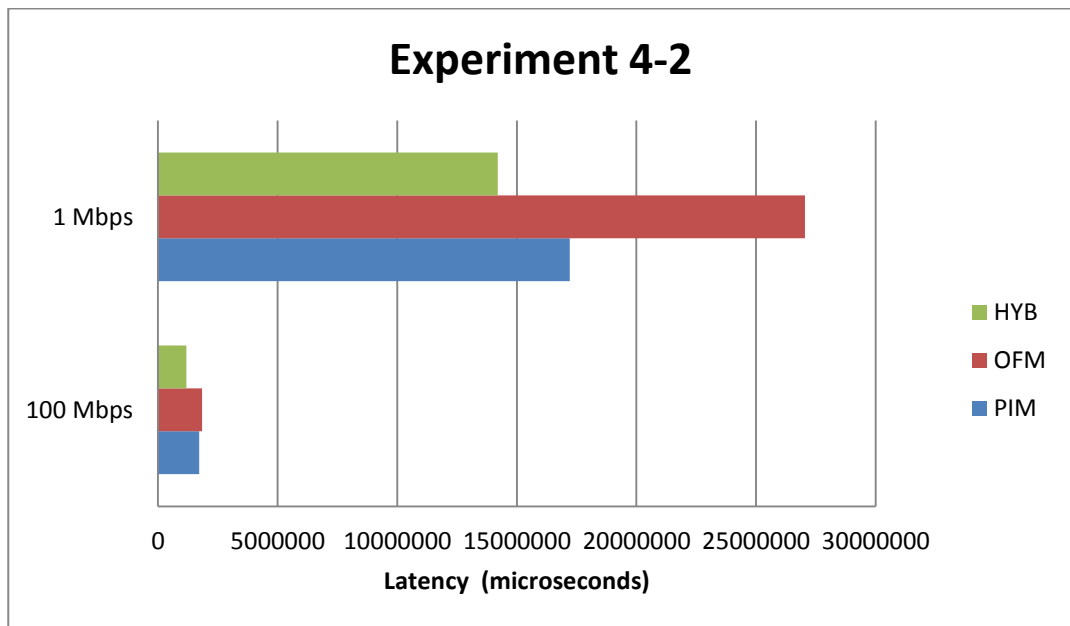
Figure 18: Experiment 4

For this experiment additional links between pairs of switches are created to demonstrate the effect of HYB method incrementally. For this experiment both 1 Mbps and 100 Mbps links are tested.

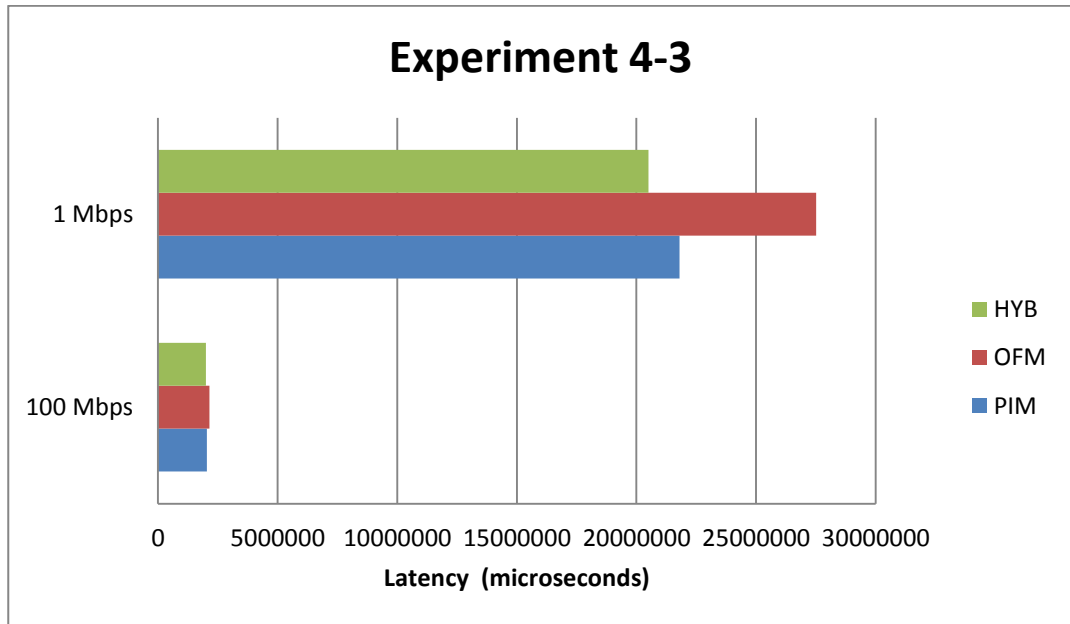
Experiment 4-1: Only Link 1 active



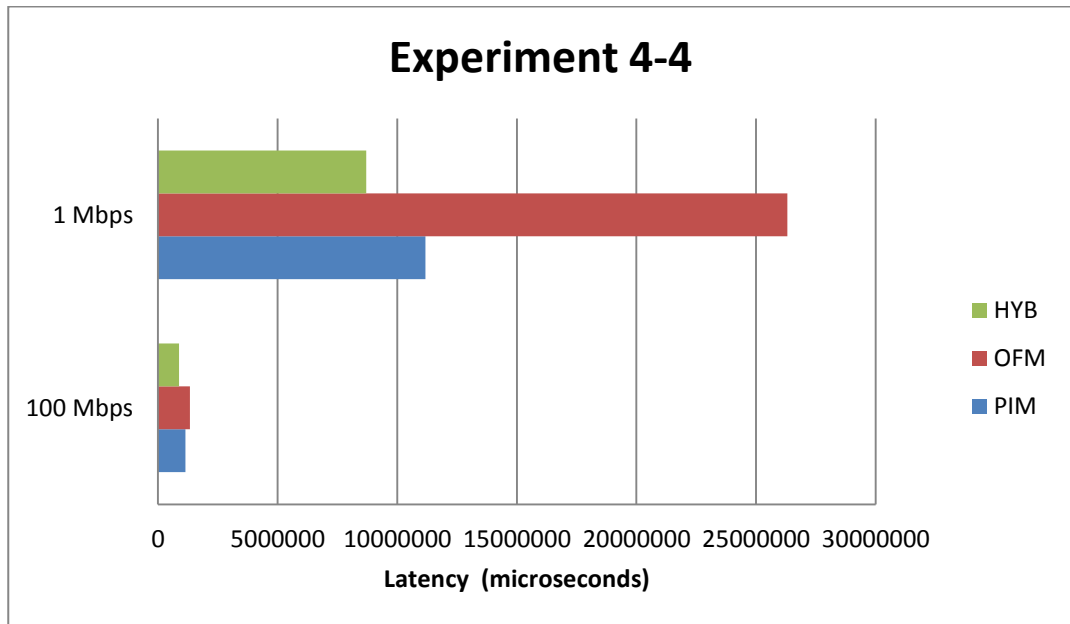
Experiment 4-2: Link 1 and link 2 active



Experiment 4-3: Link 1, 2 and link 3 active



Experiment 4-4: all 4 links active



As a clear indication, all four experiments demonstrate that the HYB method is at least as fast as other two methods.

By activating intermediary links one by one, the topology changes. As a result, in each step, the sender and receiver of the echo packet get closer to each other and the controller falls far to the destination compared to the source in the last experiment (4-4). The expected result is that in first experiment PIM method to fall short and OFM and HYB to perform better, and in last experiment to observe that the PIM and HYB methods to outperform the OFM method, which is exactly what results yield in terms of the time needed for initial echo packets to reach destination. This gradual change in the topology is a direct lead to demonstrate to consistent efficiency of the HYB method.

Experiment 5: Arbitrary topology with multiple loops

In order to demonstrate the utilization comparison among flow initiation methods, this experiments takes an arbitrary network topology and performs various echo experiments between pairs of hosts.

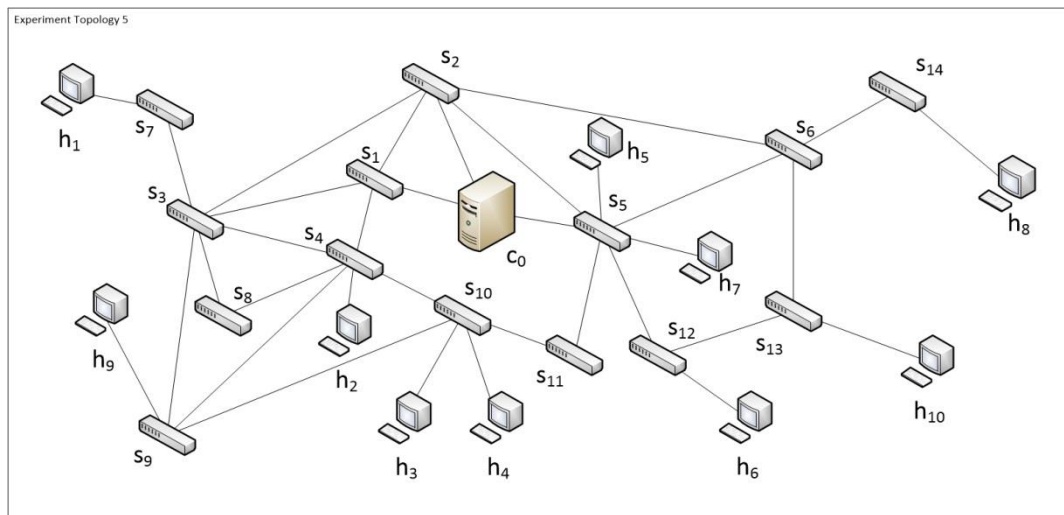


Figure 19: Experiment 5

For purpose of demonstrating the buffer usage of the switches in topology in each flow initiation method, the topology in Figure 19 is created on the simulator. The exact interface connection of the topology above is demonstrated in Figure

20. Here the closely bound nodes represent interfaces of the same device, edges between them demonstrate internal routes and edges out of them demonstrate outer links to other switches.

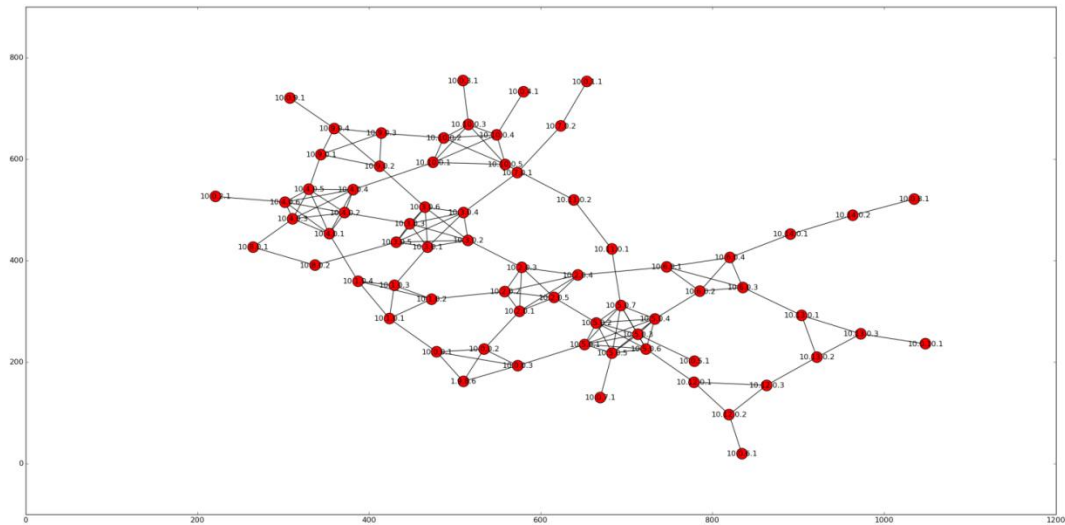


Figure 20: Experiment 5 , interface connections

Here, the following experiment is performed:

From all hosts in the network, random other IP's are send an echo message. The choice and the time between echo messages are completely random to provide an arbitrary case for the experiment.

Here is the buffer size plot for PIM method:

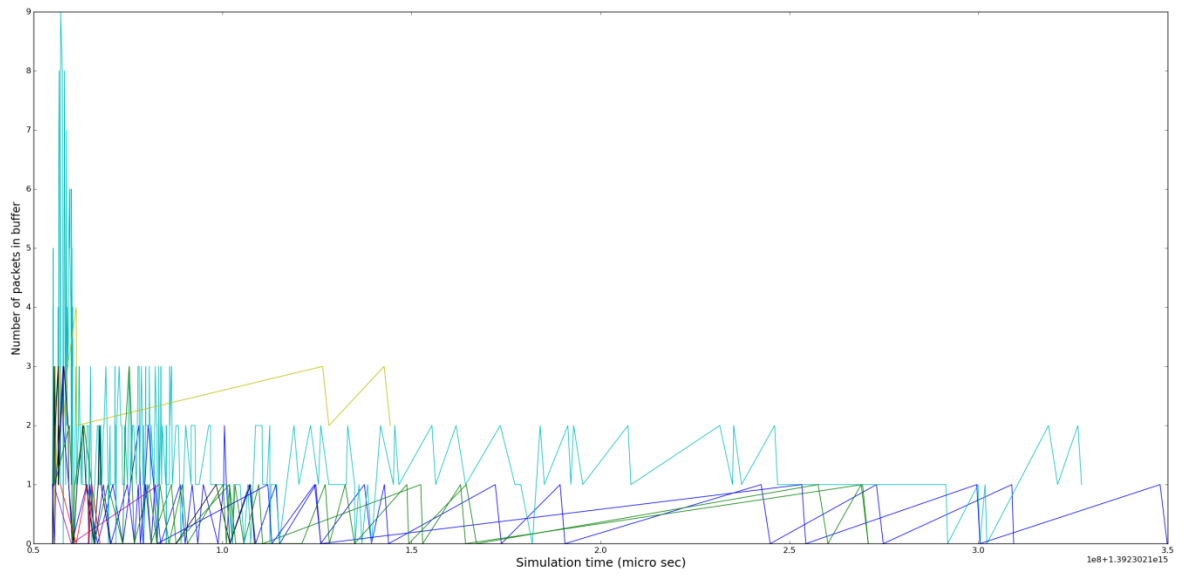


Figure 21: Buffer Size plot for all switches in network when PIM method is used

Here is the buffer size plot for PIM method:

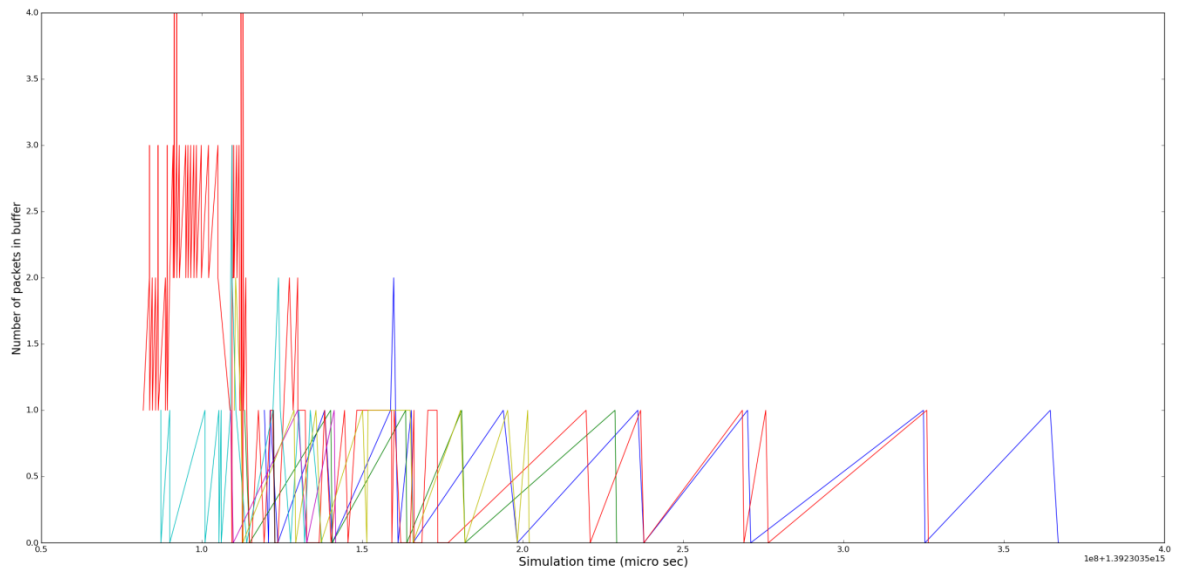


Figure 22: Buffer Size plot for all switches in network when Hybrid method is used

As can be derived from the comparison between Figure 21 and Figure 22 , where each color of line indicate a switch in topology, in a 5 minute run, where hosts constantly echo random destinations:

- In HYB method less number of switches are needed to buffer packets.
- The maximum number of buffered packets reach 9 packets in PIM where HYB method tops only 4 packets.
- In HYB method only few switches intensively use buffer, and much frequently empty their buffers leaving more space and less requirement for buffer space and less possibility of buffer overflow.

Needless to say, OFM method does not allow switches to buffer packets, thus is not plotted.

Following experiments are applied to demonstrate the efficiency of HYB method once again in initial packet delivery time, however this time in an arbitrary network.

The average of number of events regarding sending (**Blue** color) and receiving (**Green** color) echo packets is plotted below:

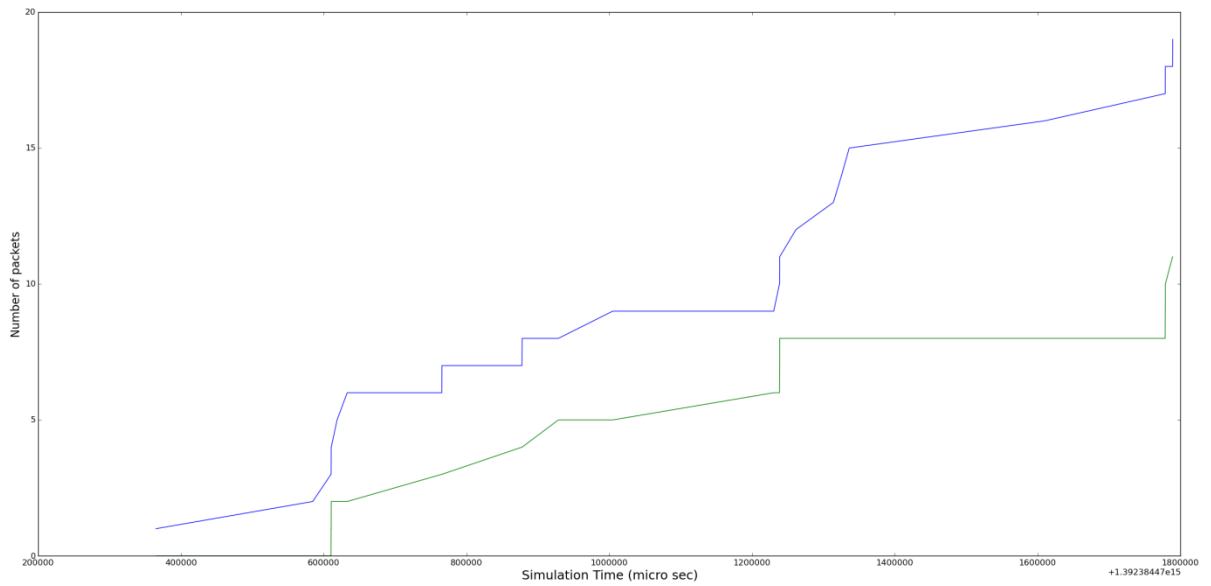


Figure 23: Echo packet send/receive events in HYB method (1: cutoff 20 packets)

Here is another experiment with a longer duration:

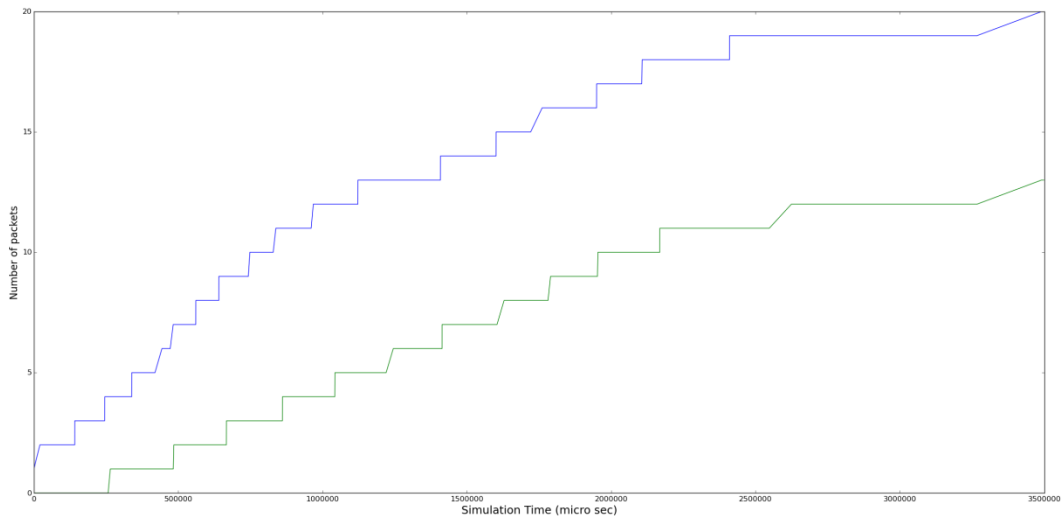


Figure 24: Echo packet send/receive events in HYB method (average of 10 repetitions)

Observing how closely the number of send-receive events follow each other in HYB method we can compare it to other flow initiation methods below:

Here is the same experiment for OFM method.

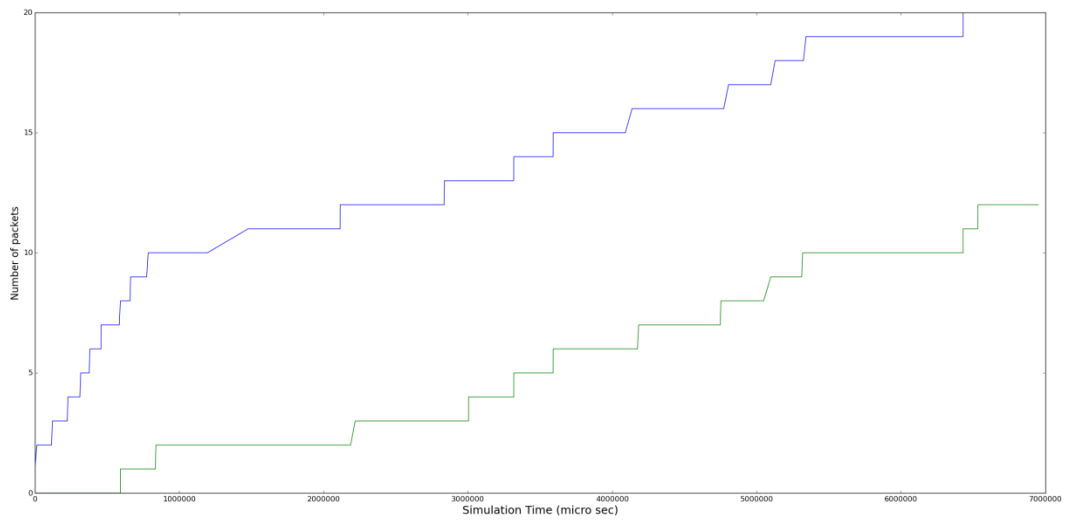


Figure 25: Echo packet send/receive events in OFM method (10 repetitions)

Here is the same experiment for PIM method:

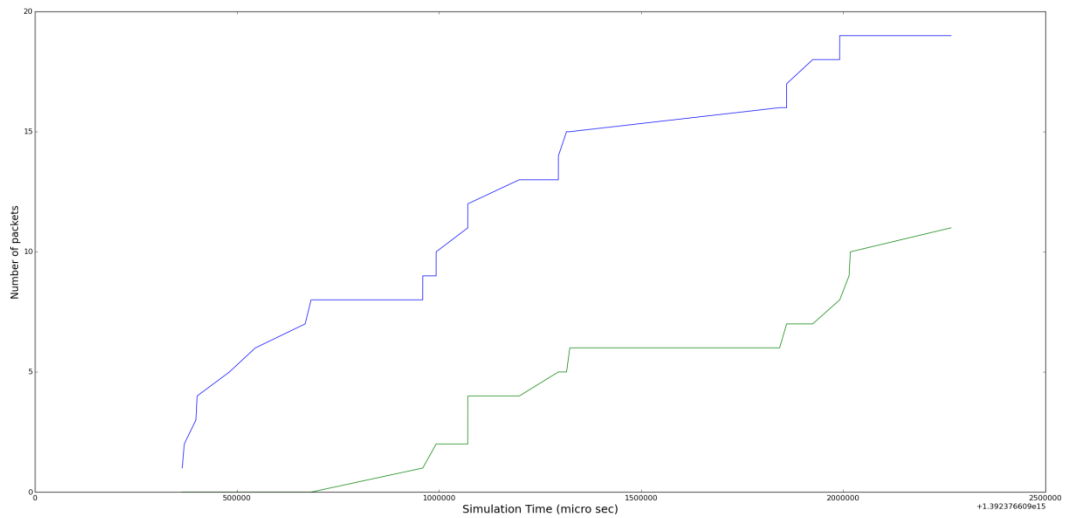


Figure 26: Echo packet send/receive events in PIM method (1 repetition)

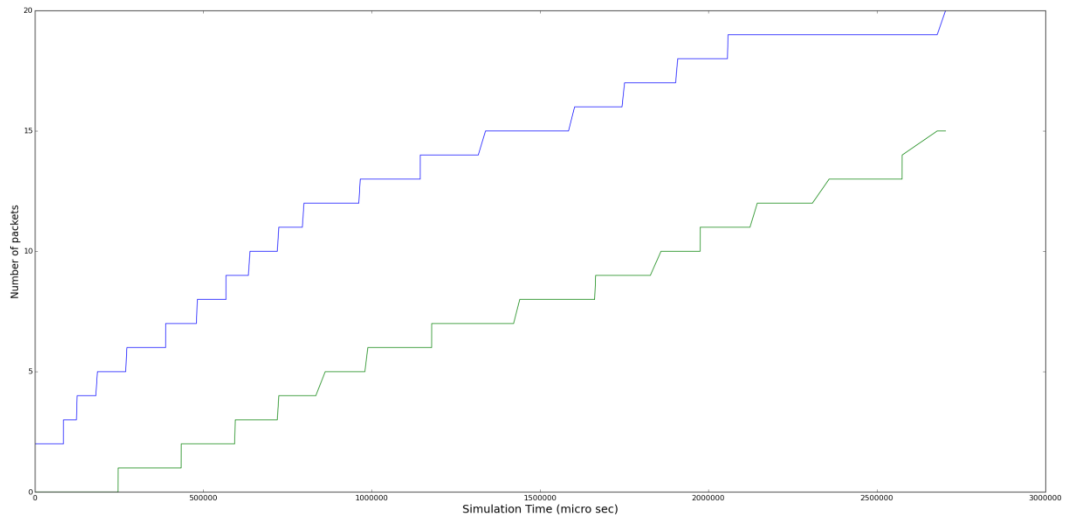


Figure 27: Echo packet send/receive events in PIM method (10 repetitions)

As can be derived from the above comparison, HYB method has a closer number of sent and received packets in each time instance and the time delay between the moments when the number of sent packets and receive packs are equal (all packets have arrived to the destination) is considerably less than OFM method and PIM methods.

4.2.6 Findings

From experiment 1 to 4 it can be clearly derived that hybrid flow initiation method in all cases has less or equal latency when compared to other two methods.

A comment that is worth mentioning is that in experiment 4 as more links are added that shortens the path between hosts, PIM and HYB methods' performance gets closer and when less number of such links are activated meaning that hosts are further apart from each other OFM performance is almost the same as the other two. This is expected because when hosts are close to each other OFM is not a desirable flow initiation method.

During experiment 5 authors concluded that the HYB method yields a considerable enhancement over buffer size and buffer usage in networks when compared to the PIM method. It is also evident from the comparisons between the echo send-receive time analysis of all three methods, HYB method of flow initiation on average provides means that enable initial packets of unknown flows to reach their destination quicker.

4.3 DISCUSSION

4.3.1 Economic influences

The present study does not aim to analyze monetary and economic implications of suggested methods. Production or configuration of switch-capable controller machines, bandwidth expenses and buffer expenses will all have influence on the selection of the optimal choice.

4.3.2 Implications of controller platforms with switch capabilities

As was discussed briefly in section 3.2.3 a platform with high speed switching capabilities and controller functionalities might at first seem like taking a step backwards to conventional networks. However, this study does not suggest coupling control and data planes in a single device again. Instead, two distinct

planes of the suggested platform will continue negotiating still based on SDN principles. The co-existence of those two functionalities on a single device, however will provide a communication speed that is incomparable to remote controller and switches over the network.

5 CHAPTER FIVE

5.1 CONCLUSION

Software Defined Networking as a considerably new principle has evolved the way networks operate and has brought unprecedented innovation pace into the field of computer networks. However similar to almost any new concept, it has its own challenges.

One of the challenges unique to Software Defined Network architecture is to reduce the time needed for flow initiation for new arrival packets. For this challenge, the present study proposes a hybrid solution which takes advantages of previously implemented algorithms and uses the internal network topology knowledge of controllers to decide when to utilize the advantageous one to achieve an optimal flow initiation time.

This study has also argued that using service centric approach to resolve multiple controller challenges is as applicable as any other distributed service over the network.

Although proposed concepts are intuitively logical, simulations are conducted to support findings and arguments of this study in practice.

The simulation experiments solidly conclude a sustaining and consisting advantage when the suggested Hybrid flow initiation method is utilized. Hybrid method provided less need for buffer and also quicker packet arrival time during flow initiation in an SDN.

When Hybrid method is used, the controller provided rules to switches prior to their request to ask for one of these flow initiation methods:

- For farther destinations, don't buffer packet, send the original flow to the controller unless told otherwise later.
- For closer destinations, buffer the packet, wait for flow initiation to conclude.

This way switches could save time during flow initiation and used less buffer size to hold initial packets.

The implications of this suggested method is:

- Less buffer expenses and resources needed in switches.
- Quicker results on flow initiation process.
- Less buffer overflow possibilities and thus less packet transmission failures.

5.2 FUTURE WORKS

NetBrain: The author will enhance the study over the possibility and implications of prototyping a platform on which controller functions communicate with a high speed switch local to the device. This platform for its analogy to function as the brain in neural systems can be seen as the Network Brain.

Technological requirements, Hardware and Software design aside, involve utilization of new methods and algorithms as well as mechanisms currently used in computer science, to enhance the overall reliability and performance of software defined networks.

The code for the simulation will be optimized for further use, and will be put online as an open source project to serve for other researches in SDN area.

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TEZİN ADI (İngilizce) : FLOW INITIATION IN SOFTWARE DEFINED NETWORKING

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